

1 Introduction

This lecture deals with stochastic processes known as Markov chains in continuous time. These processes will in the next lecture describe the substitution process on a sequence position. The lecture corresponds to sections 4.1, 10.7, and 13.3.1 in Ewens and Grant.

2 Definition and some first properties

Let $X = \{X(t) \mid t \geq 0\}$ be a family of random variables taking values in a discrete, countable, alphabet or state space \mathcal{X} . The variable t is called time. We denote the generic elements of \mathcal{X} by j, i, \dots . The special case we have in mind is the finite state space $\mathcal{X} = \{A, T, C, G\}$.

2.1 The Markov property

The process $X = \{X(t) \mid t \geq 0\}$ is called a continuous-time Markov chain if it satisfies the following definition.

Definition 2.1 $X = \{X(t) \mid t \geq 0\}$ satisfies the **Markov property**, if

$$P(X(t_n) = j \mid X(t_1), X(t_2), \dots, X(t_{n-1})) = P(X(t_n) = j \mid X(t_{n-1})) \quad (2.1)$$

for $j \in \mathcal{X}$, $i \in \mathcal{X}$, and any sequence $t_1 < t_2 < \dots < t_{n-1} < t_n$ of times.

■

The evolution of continuous-time Markov chains can be described in very much the same terms as those used for Markov Chains.

The general situation is as follows. For Markov Chains we wrote the n -step transition probabilities in matrix form and expressed them in terms of the one-step matrix \mathbf{P} . In continuous time there is no analogue for \mathbf{P} , since there is no implicit unit length of time. Some differential calculus enables us to see that there is a matrix \mathbf{Q} , called the **generator** of the continuous-time chain, which takes over the role of \mathbf{P} .

2.2 The transition probability

Definition 2.2 *The time-homogeneous transition probability is denoted by $P_{ij}(t)$ and is defined as*

$$P_{ij}(t) = P(X(t) = j | X(0) = i) \quad (2.2)$$

or

$$P_{ij}(t - s) = P(X(t) = j | X(s) = i) \quad (2.3)$$

for $j \in \mathcal{X}$.

This is most readily presented in a matrix form. ■

$$\mathbf{P}(t) = \{P_{ij}(t)\}_{i \in \mathcal{X}, j \in \mathcal{X}}.$$

2.3 Chapman - Kolmogorov equations

Proposition 2.1 *The family $\{\mathbf{P}(t) | t \geq 0\}$ satisfies*

- (a) $\mathbf{P}(0) = \mathbf{I}$ (= the identity matrix).
- (b) $\mathbf{P}(t)$ is a stochastic matrix.
- (c) the Chapman - Kolmogorov equations

$$\mathbf{P}(t + s) = \mathbf{P}(t)\mathbf{P}(s). \quad (2.4)$$

Proof: ■

- (a) This is obvious by the definitions.
- (b) Clearly

$$P_{ij}(t) \geq 0. \quad (2.5)$$

Also, since the events $\{X(t) = j\}$ are disjoint,

$$\sum_{j \in \mathcal{X}} P_{ij}(t) = P(\cup_{j \in \mathcal{X}} \{X(t) = j\} | X(0) = i) = 1 \quad (2.6)$$

Hence $\mathbf{P}(t)$ is a stochastic matrix.

(c)

$$\begin{aligned} P_{ik}(t+s) &= P(X(t+s) = j | X(0) = i) = \\ &= \sum_{k \in \mathcal{X}} P(X(t+s) = j | X(s) = k) P(X(s) = k | X(0) = i) \\ &= \sum_{k \in \mathcal{X}} P_{ik}(t) P_{kj}(s), \end{aligned} \tag{2.7}$$

where we used the Markov property (2.1). The equality is in matrix form written as

$$\mathbf{P}(t+s) = \mathbf{P}(t)\mathbf{P}(s). \tag{2.8}$$

By this the proof is completed. ■

Most questions about $X = \{X(t) \mid t \geq 0\}$ can be answered in terms of the matrices $\mathbf{P}(t)$.

Assumption 2.1 *We shall now assume that the transition probabilities $P_{ij}(t)$ are continuous functions of t . We shall also assume that*

$$\mathbf{P}(t) \rightarrow \mathbf{I}, \quad \text{as } t \downarrow 0. \tag{2.9}$$

This is to say that ■

$$P_{ij}(t) \rightarrow 0, i \neq j, \quad P_{ii}(t) \rightarrow 1, i = j, \quad \text{as } t \downarrow 0.$$

3 The generator

We make another assumption.

Assumption 3.1 *We assume that*

$$P_{ij}(h) = q_{ij}h + o(h), \quad i \neq j, \tag{3.1}$$

and

$$P_{ii}(h) = 1 + q_{ii}h + o(h), \tag{3.2}$$

where $o(h)$ ('small ordo') is a function such that $o(h)/h \rightarrow 0$, as $h \rightarrow 0$.

The numbers q_{ij} are known as the *instantaneous transition rates* or *intensities* of the continuous-time Markov chain. We are here assuming that the probability of two or more transitions in an interval $t, t + h$ is small. This can in fact be proved in a more rigorous treatment. Note that we are also implicitly thinking that the transition rates are not infinite. ■

From (3.1) and (3.2) we get

$$1 = \sum_{j \in \mathcal{X}} P_{ij}(h) = h \sum_{j \in \mathcal{X}, j \neq i} q_{ij} + 1 + q_{ii}h + o(h), \quad (3.3)$$

and this implies

$$h \sum_{j \in \mathcal{X}, j \neq i} q_{ij} = -q_{ii}h + o(h)$$

or, by dividing by h and letting h go to zero,

$$\sum_{j \in \mathcal{X}, j \neq i} q_{ij} = -q_{ii} \quad (3.4)$$

or

$$\sum_{j \in \mathcal{X}} q_{ij} = 0 \quad (3.5)$$

We introduce the symbol q_i by

$$q_i \stackrel{\text{def}}{=} \sum_{j \in \mathcal{X}, j \neq i} q_{ij}. \quad (3.6)$$

The assumption (3.2) gives thus

$$\lim_{h \downarrow 0} \frac{P_{ii}(h) - 1}{h} = q_{ii} = -q_i, \quad (3.7)$$

and the assumption (3.2)

$$\lim_{h \downarrow 0} \frac{P_{ij}(h)}{h} = q_{ij}, \quad i \neq j. \quad (3.8)$$

We introduce the square matrix

$$\mathbf{Q} = (q_{ij})_{i,j \in \mathcal{X}}. \quad (3.9)$$

In matrix form (3.7) and (3.8) are

$$\lim_{h \downarrow 0} \frac{\mathbf{P}(h) - \mathbf{I}}{h} = \mathbf{Q}. \quad (3.10)$$

The matrix \mathbf{Q} is called the *generator*.

The generator for a Markov chain on a state space with four elements is in general

$$\mathbf{Q} = \begin{pmatrix} -q_1 & q_{12} & q_{13} & q_{14} \\ q_{21} & -q_2 & q_{23} & q_{24} \\ q_{31} & q_{32} & -q_3 & q_{34} \\ q_{41} & q_{42} & q_{43} & -q_4 \end{pmatrix}.$$

3.1 An Example: the Poisson process

Let $X = \{X(t) \mid t \geq 0\}$ be a process that has the set of non-negative integers as the state space. One way of defining X as a Poisson process is to assume the following ((1)–(3)).

(1) The increments of the process are independent or

$$P(X(t) - X(s), X(u) - X(v)) = P(X(t) - X(s)) \cdot P(X(u) - X(v))$$

for $v < u \leq s < t$.

(2) $X(0) = 0$.

(3) $X(t) - X(s) \in \text{Po}(\lambda(t - s))$.

By these assumptions X is a continuous-time Markov chain. This is found by

$$\begin{aligned} & P(X(t_n) = j_n \mid X(t_1) = j_1, X(t_2) = j_2, \dots, X(t_{n-1}) = j_{n-1}) = \\ & = P(X(t_n) - X(t_{n-1}) = j_n - j_{n-1} \mid X(t_1) = j_1, X(t_2) = j_2, \dots, X(t_{n-1}) = j_{n-1}) \\ & = P(X(t_n) - X(t_{n-1}) = j_n - j_{n-1}) \end{aligned}$$

by assumptions (1) and (2), and this equals

$$\begin{aligned} & = P(X(t_n) - X(t_{n-1}) = j_n - j_{n-1} \mid X(t_{n-1}) - X(0) = j_{n-1}) \\ & = P(X(t_n) = j_n \mid X(t_{n-1}) = j_{n-1}), \end{aligned}$$

again by assumption (1). By assumption (3)

$$\begin{aligned} P_{ij}(t) &= P(X(t+s) = j | X(s) = i) = P(X(t+s) - X(s) = j - i) \\ &= e^{-\lambda t} \frac{(\lambda t)^{j-i}}{(j-i)!}. \end{aligned}$$

Then from (3.7) we get

$$\lim_{h \downarrow 0} \frac{P_{ii}(h) - 1}{h} = \lim_{h \downarrow 0} \frac{e^{-\lambda h} - 1}{h} = -\lambda,$$

and from (3.8)

$$\begin{aligned} \lim_{h \downarrow 0} \frac{P_{ij}(h)}{h} &= \lim_{h \downarrow 0} \frac{e^{-\lambda h} \frac{(\lambda h)^{j-i}}{(j-i)!}}{h} \\ &= \begin{cases} \lambda, & j = i + 1 \\ 0 & \text{otherwise.} \end{cases} \end{aligned}$$

We have the generator

$$\mathbf{Q} = \begin{pmatrix} -\lambda & \lambda & 0 & 0 & \dots \\ 0 & -\lambda & \lambda & 0 & \dots \\ 0 & 0 & -\lambda & \lambda & \ddots \\ \vdots & \vdots & \vdots & \ddots & \ddots \end{pmatrix}.$$

A Poisson proces is thus a continuous time Markov chain with $q_i = \lambda$, so that from (3.6) and (3.4) we have

$$P_{ii}(h) = 1 - \lambda h + o(h),$$

or

$$1 - P_{ii}(h) = \lambda h + o(h),$$

so that the total intensity of leaving i is λ . But, by (3), λ is the intensity of one jump upwards for the proces X .

3.2 An Example: The random telegraph

Let $Y \in \text{Be}(1/2)$ and $N = \{N(t) | t \geq 0\}$ be a Poisson process like in the previous example, and let Y be independent of N . Set

$$X(t) = (-1)^{Y+N(t)}.$$

Then $X = \{X(t) | t \geq 0\}$ is a continuous-time Markov chain, as essentially follows by the same argument as used in the preceding example. The transition matrix is

$$\mathbf{P}(t) = \begin{pmatrix} \frac{1}{2} \left(1 + e^{-2\lambda t} \right) & \frac{1}{2} \left(1 - e^{-2\lambda t} \right) \\ \frac{1}{2} \left(1 - e^{-2\lambda t} \right) & \frac{1}{2} \left(1 + e^{-2\lambda t} \right) \end{pmatrix}.$$

The sample paths of X , the random telegraph, are sequences of -1 and 1 , each digit prevailing a random (exponentially distributed time).

4 Forward and backward equations

The meaning of the notion of a generator can be explained as follows. Suppose that $X(0) = i$, and by conditioning $X(t+h)$ on $X(t)$ we get by the Chapman-Kolmogorov equations

$$\begin{aligned} P_{ij}(t+h) &= P(X(t+h) = j | X(0) = i) = \\ &= \sum_{k \in \mathcal{X}} P_{ik}(t) P_{kj}(h) \\ &= P_{ij}(t) (1 + q_{jj}h + o(h)) + \sum_{k \in \mathcal{X}, k \neq j} P_{ik}(t) (q_{kj}h + o(h)) \end{aligned}$$

from (3.1) and (3.2). Then we get

$$= P_{ij}(t) + h \sum_{k \in \mathcal{X}} P_{ik}(t) q_{kj} + o(h).$$

Thus we get that

$$\frac{P_{ij}(t+h) - P_{ij}(t)}{h} = \sum_{k \in \mathcal{X}} P_{ik}(t) q_{kj} + o(h)/h.$$

Hence we have, letting $h \rightarrow 0$, and letting $P'_{ij}(t)$ denote the first derivative with respect to t ,

$$P'_{ij}(t) = \sum_{k \in \mathcal{X}} P_{ik}(t)q_{kj} = (\mathbf{P}(t)\mathbf{Q})_{ij}.$$

Thus we have derived the following proposition.

Proposition 4.1

$$P'_{ij}(t) = \sum_{k \in \mathcal{X}} P_{ik}(t)q_{kj}, \quad (4.1)$$

or the matrix **forward equation**

$$\mathbf{P}'(t) = \mathbf{P}(t)\mathbf{Q}. \quad (4.2)$$

■

By a similar way, we can prove

Proposition 4.2

$$P'_{ij}(t) = \sum_{k \in \mathcal{X}} q_{ik}P_{kj}(t), \quad (4.3)$$

or the matrix **backward equation**

$$\mathbf{P}'(t) = \mathbf{Q}\mathbf{P}(t). \quad (4.4)$$

■

Thus we have the system of differential equations

$$\mathbf{P}'(t) = \mathbf{P}(t)\mathbf{Q}$$

with the initial conditions

$$P(0) = \mathbf{I}.$$

In courses on differential equations the solution is often written using the exponential of a matrix

$$\mathbf{P}(t) = e^{\mathbf{Q}t} = \sum_{l=0}^{\infty} \frac{t^l}{l!} \mathbf{Q}^l. \quad (4.5)$$

Hence we see that we can generate $\mathbf{P}(t)$ from knowledge of \mathbf{Q} . The representation (4.5) is the unique solution to the forward and backward equations, if the state space is finite.

In many cases the series expansion $e^{\mathbf{Q}t} = \sum_{l=0}^{\infty} \frac{t^l}{l!} \mathbf{Q}^l$ is useless for practical computations, since arbitrary high powers of \mathbf{Q} are needed, see also (Moler and Van Loan 1978). There is, however, a special case of interest in computational evolutionary biology, where the sum can be explicitly evaluated, a fact that leads to important results. We shall develop this in section 7 below.

5 Absolute probabilities

Definition 5.1 Let $X = \{X(t) \mid t \geq 0\}$ be continuous-time Markov chain. The probability

$$p_i(t) = P(X(t) = i)$$

is called the absolute probability for the chain to be in state $i \in \mathcal{X}$ at time t . The vector $\mathbf{p}(t)$ is a row vector whose components are $p_i(t)$. In particular $\mathbf{p}(0)$ is called the initial vector or the initial distribution. ■

The law of total probability gives

$$\begin{aligned} p_i(t) &= P(X(t) = i) = \sum_{k \in \mathcal{X}} P(X(t) = i \mid X(0) = k) P(X(0) = k) = \\ &= \sum_{k \in \mathcal{X}} P_{ki}(t) p_k(0), \end{aligned}$$

which we write in matrix form as

$$\mathbf{p}(t) = \mathbf{p}(0)\mathbf{P}(t). \tag{5.1}$$

This gives $\mathbf{p}'(t) = \mathbf{p}(0)\mathbf{P}'(t)$. If we multiply the forward equation (4.2) by $\mathbf{p}(0)$ from the left, we get

$$\mathbf{p}'(t) = \mathbf{p}(0)\mathbf{P}'(t) = \mathbf{p}(0)\mathbf{P}(t)\mathbf{Q} = \mathbf{p}(t)\mathbf{Q}. \tag{5.2}$$

If the state space is finite, this is a correct computation, in the case of countable state spaces there are things to be checked. When the equation (5.2) is expressed elementwise, we get

$$p_j'(t) = \sum_{i \in \mathcal{X}} p_i(t) q_{ij} = p_j(t) q_{jj} + \sum_{i \in \mathcal{X}, i \neq j} p_i(t) q_{ij}$$

$$= -q_j p_j(t) + \sum_{i \in \mathcal{X}, i \neq j} p_i(t) q_{ij}.$$

This can be seen as a flow of probabilities. The probability $p_j(t)$ gets an increment that corresponds to the probability that the process is in state i at time t , which is $p_i(t)$ multiplied by the instantaneous transition rate from i to j , q_{ij} . This is summed over all states $i \neq j$. On the other hand $p_j(t)$ is depleted with the probability that the chain is already in the state j multiplied by the instantaneous transition rate to leave the state, i.e., q_j . Inflow minus outflow equals the rate of change $p_j'(t)$.

6 Stationary distribution

6.1 Definition & the global balance equations

Definition 6.1 *The vector $\pi = (\pi_i)_{i \in \mathcal{X}}$ is a stationary distribution of the chain if*

$$\pi = \pi \mathbf{P}(t) \quad \text{for all } t \geq 0$$

and $\sum_{i \in \mathcal{X}} \pi_i = 1$ and $\pi_i \geq 0$.

■

Thus, (5.1) yields that if $\mathbf{p}(0) = \pi$, then the absolute probabilities are

$$\mathbf{p}(t) = \pi$$

for all $t \geq 0$.

Proposition 6.1

$$\pi = \pi \mathbf{P}(t) \Leftrightarrow \pi \mathbf{Q} = \mathbf{0}. \tag{6.1}$$

Here $\mathbf{0}$ is matrix of zeros.

Proof:

$$\begin{aligned} \pi \mathbf{Q} &= \mathbf{0} \\ &\Leftrightarrow \\ \pi \mathbf{Q}^n &= \mathbf{0} \quad \text{for all } n \geq 1 \\ &\Leftrightarrow \\ \sum_{n=1}^{\infty} \frac{t^n}{n!} \pi \mathbf{Q}^n &= \mathbf{0} \quad \text{for all } t \geq 0 \end{aligned}$$

$$\begin{aligned}
& \Leftrightarrow \\
& \pi \sum_{n=0}^{\infty} \frac{t^n}{n!} \mathbf{Q}^n = \pi \quad \text{for all } t \geq 0 \\
& \Leftrightarrow \\
& \pi \mathbf{P}(t) = \pi \quad \text{for all } t \geq 0,
\end{aligned}$$

as was claimed. ■

If we write $\pi \mathbf{Q} = \mathbf{0}$ elementwise we get

$$\sum_{i \in \mathcal{X}} \pi_i q_{ij} = 0, \quad \text{for every } j,$$

and this we write as

$$\sum_{i \in \mathcal{X}, i \neq j} \pi_i q_{ij} = -\pi_j q_{jj} = \pi_j q_j. \quad (6.2)$$

The left hand side is interpreted as the flow into the state j , since q_{ij} is the instantaneous transition rate from i to j and this is weighted by π_i , which is the probability that the chain is in the state i . These are summed over all states $i \neq j$. In the same way the right hand side is flow out from the state j , since $q_j = \sum_{k \neq j} q_{jk}$ is the total instantaneous transition rate out from that state. A stationary state is reasonably described by inflow being equal to outflow. The system of equations $\pi \mathbf{Q} = \mathbf{0}$ is called the *global balance equations*. The global balance equations or (6.2) will be used in several evolutionary biological contexts in the next lecture.

6.2 Rate of Change

Let the *rate of change*, R , be defined as

$$R \stackrel{\text{def}}{=} \lim_{h \downarrow 0} \frac{P(X(t+h) \neq X(t))}{h}. \quad (6.3)$$

We get

$$\begin{aligned}
P(X(t+h) \neq X(t)) &= \sum_{i \in \mathcal{X}} P(X(t+h) \neq i \mid X(t) = i) P(X(t) = i) = \\
&= \sum_{i \in \mathcal{X}} \sum_{j \in \mathcal{X}, j \neq i} P(X(t+h) = j \mid X(t) = i) P(X(t) = i).
\end{aligned}$$

Then, assuming that the state space is finite,

$$R = \sum_{i \in \mathcal{X}} \sum_{j \in \mathcal{X}, j \neq i} \lim_{h \downarrow 0} \frac{P(X(t+h) = j \mid X(t) = i)}{h} P(X(t) = i),$$

where from (3.8) we get

$$\lim_{h \downarrow 0} \frac{P(X(t+h) = j \mid X(t) = i)}{h} = q_{ij}.$$

Thus

$$\begin{aligned} R &= \sum_{i \in \mathcal{X}} \sum_{j \in \mathcal{X}, j \neq i} q_{ij} P(X(t) = i) \\ &= - \sum_{i \in \mathcal{X}} q_{ii} P(X(t) = i), \end{aligned}$$

where we have used (3.4). Assuming stationary state we get the final result.

$$R = - \sum_{i \in \mathcal{X}} q_{ii} \pi_i. \quad (6.4)$$

7 A special generator

We shall next compute the solution to $\pi \mathbf{Q} = \mathbf{0}$ and the rate of change R in (6.4) and $e^{\mathbf{Q}t}$, when the generator is of the form

$$\mathbf{Q} = \begin{pmatrix} -(u - u_1) & u_2 & u_3 & u_4 \\ u_1 & -(u - u_2) & u_3 & u_4 \\ u_1 & u_2 & -(u - u_3) & u_4 \\ u_1 & u_2 & u_3 & -(u - u_4) \end{pmatrix}, \quad (7.1)$$

where

$$u = u_1 + u_2 + u_3 + u_4. \quad (7.2)$$

7.1 Rate of change

Proposition 7.1 *If X is a continuous time Markov chain with the generator \mathbf{Q} in (7.1), then*

$$\pi \mathbf{Q} = \mathbf{0}$$

has the solution

$$\pi = \left(\frac{u_1}{u}, \frac{u_2}{u}, \frac{u_3}{u}, \frac{u_4}{u} \right) \quad (7.3)$$

The proof is left to the reader. ■

Proposition 7.2 *If X is a continuous time Markov chain with the generator \mathbf{Q} in (7.1), then the rate of change is*

$$R = \lim_{h \downarrow 0} \frac{P(X(t+h) \neq X(t))}{h} = u \left(1 - \sum_{i \in \mathcal{X}} \pi_i^2 \right). \quad (7.4)$$

where u is given in (7.2).

Proof: We have shown in (6.4) that

$$R = - \sum_{i \in \mathcal{X}} q_{ii} \pi_i.$$

If we insert from (7.1) and (7.3) we get

$$\begin{aligned} - \sum_{i \in \mathcal{X}} q_{ii} \pi_i &= \sum_{i \in \mathcal{X}} (u - u_i) \frac{u_i}{u} = u \sum_{i \in \mathcal{X}} \left(1 - \frac{u_i}{u} \right) \frac{u_i}{u} \\ &= u \sum_{i \in \mathcal{X}} (1 - \pi_i) \pi_i = u \left(\sum_{i \in \mathcal{X}} \pi_i - \sum_{i \in \mathcal{X}} \pi_i^2 \right) = u \left(1 - \sum_{i \in \mathcal{X}} \pi_i^2 \right). \end{aligned}$$

■

7.2 The exponential of a generator

Now we find

$$\mathbf{P}(t) = e^{\mathbf{Q}t},$$

when the generator is given in (7.1). For this a couple of smart observations are needed. We introduce the matrix

$$\mathbf{A} = \begin{pmatrix} \pi_1 & \pi_2 & \pi_3 & \pi_4 \\ \pi_1 & \pi_2 & \pi_3 & \pi_4 \\ \pi_1 & \pi_2 & \pi_3 & \pi_4 \\ \pi_1 & \pi_2 & \pi_3 & \pi_4 \end{pmatrix}.$$

One notes that

$$\mathbf{Q} = -u(\mathbf{I} - \mathbf{A}). \quad (7.5)$$

The interesting thing about \mathbf{A} is, that it is idempotent, i.e.,

$$\mathbf{A}^n = \mathbf{A}, \quad \text{for } n \geq 1.$$

This is easily verified by a computation

$$\begin{aligned} \mathbf{A}^2 &= \begin{pmatrix} \pi_1(\pi_1 + \pi_2 + \pi_3 + \pi_4) & \dots & \pi_4(\pi_1 + \pi_2 + \pi_3 + \pi_4) \\ \pi_1(\pi_1 + \pi_2 + \pi_3 + \pi_4) & \dots & \pi_4(\pi_1 + \pi_2 + \pi_3 + \pi_4) \\ \pi_1(\pi_1 + \pi_2 + \pi_3 + \pi_4) & \dots & \pi_4(\pi_1 + \pi_2 + \pi_3 + \pi_4) \\ \pi_1(\pi_1 + \pi_2 + \pi_3 + \pi_4) & \dots & \pi_4(\pi_1 + \pi_2 + \pi_3 + \pi_4) \end{pmatrix} \\ &= \mathbf{A}. \end{aligned}$$

Thus $\mathbf{A}^n = \mathbf{A}$ for all $n \geq 1$.

Next we recall that

$$e^{-ut\mathbf{I}} = \sum_{l=0}^{\infty} \frac{(-ut)^l}{l!} \mathbf{I}^l = \mathbf{I} \sum_{l=0}^{\infty} \frac{(-ut)^l}{l!} = e^{-ut} \mathbf{I}.$$

Then we have

$$\begin{aligned} e^{\mathbf{Q}t} &= e^{-ut(\mathbf{I}-\mathbf{A})} = e^{-ut} \mathbf{I} e^{ut\mathbf{A}} \\ &= e^{-ut} \mathbf{I} \sum_{l=0}^{\infty} \frac{(ut)^l}{l!} \mathbf{A}^l = e^{-ut} \mathbf{I} \left[\mathbf{I} + \sum_{l=1}^{\infty} \frac{(ut)^l}{l!} \mathbf{A}^l \right] \\ &= e^{-ut} \mathbf{I} \left[\mathbf{I} + \mathbf{A} \sum_{l=1}^{\infty} \frac{(ut)^l}{l!} \right] = e^{-ut} \mathbf{I} \left[\mathbf{I} + \mathbf{A}(e^{-ut} - 1) \right] \\ &= e^{-ut} \mathbf{I} + \mathbf{A} (1 - e^{-ut}). \end{aligned}$$

To summarize

$$\mathbf{P}(t) = e^{\mathbf{Q}t} = e^{-ut} \mathbf{I} + \mathbf{A} (1 - e^{-ut}), \quad \text{for } \mathbf{Q} \text{ in (7.1)}. \quad (7.6)$$

If we write this elementwise, we get

$$P_{ij}(t) = e^{-ut} \delta_{i,j} + (1 - e^{-ut}) \pi_j, \quad (7.7)$$

where $\delta_{i,j}$ is the Kronecker delta defined by

$$\delta_{i,j} = \begin{cases} 1 & i = j \\ 0 & i \neq j. \end{cases} \quad (7.8)$$

7.3 Separation of Species

We are still assuming \mathbf{Q} in (7.1), and make the additional assumption of *reversibility*. We assume namely first that

$$\pi_i P_{ij}(t) = \pi_j P_{ji}(t) \quad \text{for all } t, i, j \in \mathcal{X}. \quad (7.9)$$

This implies by (3.8) even that

$$\pi_i q_{ij} = \pi_j q_{ji}.$$

We see immediately that this is satisfied for \mathbf{Q} in (7.1).

Let us now suppose that we have two continuous-time Markov chains X and Y , with the same generator \mathbf{Q} in (7.1), assuming reversibility, and such that

$$X(0) = Y(0).$$

Then we have

Proposition 7.3 *Assume two continuous-time Markov chains X and Y , with the same generator \mathbf{Q} in (7.1), assuming reversibility, and such that*

$$X(0) = Y(0) \in \pi,$$

but evolving independently thereafter. Then

$$\begin{aligned} P(X(t) = i, Y(t) = j) &= \pi_i P_{ij}(2t) = \\ &= \begin{cases} \pi_i (1 - e^{-2ut}) \pi_j & i \neq j, \\ \pi_i e^{-2ut} + \pi_i (1 - e^{-2ut}) \pi_j & i = j. \end{cases} \end{aligned} \quad (7.10)$$

Proof:

$$\begin{aligned} P(X(t) = i, Y(t) = j) &= \sum_{k \in \mathcal{X}} P(X(t) = i, Y(t) = j \mid X(0) = Y(0) = k) P(X(0) = Y(0) = k) \\ &= \sum_{k \in \mathcal{X}} P(X(t) = i, Y(t) = j \mid X(0) = Y(0) = k) \pi_k \\ &= \sum_{k \in \mathcal{X}} P(X(t) = i \mid X(0) = k) P(Y(t) = j \mid Y(0) = k) \pi_k \\ &= \sum_{k \in \mathcal{X}} P_{ki}(t) P_{kj}(t) \pi_k = \end{aligned}$$

$$= \pi_i \sum_{k \in \mathcal{X}} P_{ik}(t) P_{kj}(t)$$

where we used reversibility (7.9), and the right hand side is

$$= \pi_i P_{ij}(2t),$$

where we invoked the Chapman-Kolmogorov equations (2.7). Then we insert from (7.7) to obtain the rightmost expression in (7.10). ■

7.4 Fraction of divergence

Next we compute

$$P(X(t) \neq Y(t)).$$

From the preceding proposition we get

$$\begin{aligned} P(X(t) \neq Y(t)) &= \sum_{i \neq j} P(X(t) = i, Y(t) = j) \\ &= \sum_{i \neq j} \pi_i P_{ij}(2t) = \sum_{i \neq j} \pi_i (1 - e^{-2ut}) \pi_j, \end{aligned}$$

in view of (7.10). The right hand side equals

$$= (1 - e^{-2ut}) \sum_{i \neq j} \pi_i \pi_j.$$

Here the sum $\sum_{i \neq j} \pi_i \pi_j$ is actually a double sum

$$\begin{aligned} \sum_{i \neq j} \pi_i \pi_j &= \sum_{i \in \mathcal{X}} \pi_i \sum_{j \in \mathcal{X}, j \neq i} \pi_j = \\ &= \sum_{i \in \mathcal{X}} \pi_i (\pi_1 + \pi_2 + \dots + \pi_{i-1} + \pi_{i+1} + \dots) = \\ &= \sum_{i \in \mathcal{X}} \pi_i (1 - \pi_i) = \sum_{i \in \mathcal{X}} \pi_i - \sum_{i \in \mathcal{X}} \pi_i^2 = 1 - \sum_{i \in \mathcal{X}} \pi_i^2. \end{aligned}$$

Now we recall the rate of change from (7.4), and get

$$P(X(t) \neq Y(t)) = \frac{R}{u} (1 - e^{-2ut}).$$

This will lead to a famous formula of evolutionary biology, *Jukes-Cantor formula*, later on.

8 Exponential holding times

Assume that $X(t) = i$. Let

$$T = \inf\{s \geq 0 | X(t + s) \neq i\}.$$

Then T is the further time the continuous time chain remains in the state i . The time T is called the *holding time*.

Proposition 8.1 $T | X(t) = i \in \text{Exp}(q_j)$.

Proof: We start by

$$P(T \geq t + h) = P(T \geq t) P(T \geq t + h | T \geq t).$$

The continuous-time Markov chain lacks memory and is time-homogeneous. Hence we get that

$$P(T \geq t + h) = P(T \geq t) P(T \geq h).$$

But the probability $P(T \geq h)$ is the probability that the continuous-time Markov chain has not moved from i before the time h . From the assumption (3.2) we obtain

$$P(T \geq h) = P_{ii}(h) = 1 + q_{ii}h + o(h) = 1 - q_i h + o(h).$$

Hence

$$P(T \geq t + h) = P(T \geq t) (1 - q_i h) + o(h).$$

This is rearranged as

$$\frac{P(T \geq t + h) - P(T \geq t)}{h} = -q_i P(T \geq t) + \frac{o(h)}{h}.$$

Letting $h \rightarrow 0$ this yields

$$\frac{d}{dt} P(T \geq t) = -q_i P(T \geq t).$$

This differential equation has the general solution

$$P(T \geq t) = C e^{-q_i t},$$

for some constant C . For $t = 0$ we get $C = 1$. Thus

$$P(T \geq t) = e^{-q_i t},$$

or

$$P(T \leq t) = 1 - e^{-q_i t},$$

which ‘verifies’ the claim as asserted. ■

The mean time spent at i is thus $\frac{1}{q_i}$. Assume that $X(0) = i$. Let

$$T_1 = \inf\{s \geq 0 | X(s) \neq i\}.$$

Proposition 8.2

$$P(X(T_1) = j | X(0) = i) = \frac{q_{ij}}{q_i}, \quad j \neq i.$$

Sketch of Proof: Let us define for $i \neq j$,

$$r_{ij}(h) = P(X(h) = j | X(0) = i, X(h) \neq i),$$

Next, if $0 \leq T_1 \leq h$,

$$\begin{aligned} P(X(T_1) = j | X(0) = i) &= P(X \text{ jumps to } j \mid X \text{ jumps only once in } [0, h]) \\ &\approx r_{ij}(h) \end{aligned}$$

for small h . But

$$\begin{aligned} r_{ij}(h) &= P(X(h) = j | X(0) = i, X(h) \neq i) = \frac{P(X(h) = j, X(0) = i, X(h) \neq i)}{P(X(0) = i, X(h) \neq i)} \\ &= \frac{P(X(h) = j, X(0) = i)}{P(X(0) = i, X(h) \neq i)} \\ &= \frac{P(X(h) = j | X(0) = i)}{P(X(h) \neq i | X(0) = i)} \\ &= \frac{P_{ij}(h)}{1 - P_{ii}(h)} = \frac{P_{ij}(h)/h}{(1 - P_{ii}(h))/h}. \end{aligned}$$

For small h

$$\frac{P_{ij}(h)/h}{(1 - P_{ii}(h))/h} \approx \frac{q_{ij}}{-q_{ii}} = \frac{q_{ij}}{q_i},$$

as was claimed. ■

9 The imbedded Markov chain

From the preceding, if $X(t) = i$, it remains there for an exponentially distributed time T and jumps then to another state with the probability $\frac{q_{ij}}{q_i}$. Let us set

$$\tilde{X}_0 = X(0), T_0 = 0.$$

Take $n \geq 1$. Suppose that \tilde{X}_{n-1} has been defined. Let $U_n \in \text{Exp}(q_i)$. Let

$$T_n = T_{n-1} + U_n$$

and

$$\tilde{X}_n = X(T_n).$$

By lack of memory and time homogeneity $\{\tilde{X}_n\}_{n=0}^\infty$ is a Markov chain that jumps from i to j with probability $\frac{q_{ij}}{q_i}$, if $i \neq j$ and jumps from i to i with probability 0. This is called the *imbedded Markov chain*.

10 References

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