

1.

$$\tilde{f}(x) = \pi/4 + \sum_{n=1}^{\infty} \left(\frac{1 - (-1)^n}{n^2 \pi} \cos(nx) + \frac{1}{n} \sin(nx) \right)$$

$$\tilde{f}(0) = \pi/2 \quad (\text{compare chapter 11.2, p. 429,})$$

2.

$$u(x,y) = A_0 x + \sum_{n=1}^{\infty} A_n \sinh\left(\frac{n\pi}{b} x\right) \cos\left(\frac{n\pi}{b} y\right)$$

$$A_0 = \frac{1}{ab} \int_0^b g(y) dy, \quad A_n = \frac{2}{b \sinh \frac{n\pi}{b} a} \int_0^b g(y) \cos\left(\frac{n\pi}{b} y\right) dy$$

3. (compare chapter 12^o, p. 475)

$$\begin{vmatrix} 3-\lambda & 1 \\ 1 & 3-\lambda \end{vmatrix} = 8 + \lambda^2 - 6\lambda = (\lambda-2)(\lambda-4)$$

$$\begin{pmatrix} -1 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}, \quad \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ -1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\Rightarrow \vec{X}_H(t) = C_+ e^{4t} \begin{pmatrix} 1 \\ 1 \end{pmatrix} + C_- e^{2t} \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

$$\vec{X}_P = \begin{pmatrix} u \\ v \end{pmatrix} \text{ (Ansatz) = constant (vector)}$$

$$\Rightarrow \vec{X}_P = - \begin{pmatrix} 3 & 1 \\ 1 & 3 \end{pmatrix}^{-1} \begin{pmatrix} 2 \\ 4 \end{pmatrix} = -\frac{1}{8} \begin{pmatrix} 3 & -1 \\ -1 & 3 \end{pmatrix} \begin{pmatrix} 2 \\ 4 \end{pmatrix} = -\frac{1}{4} \begin{pmatrix} 1 \\ 5 \end{pmatrix}$$

$$\vec{X}(t) = \vec{X}_H(t) + \vec{X}_P(t)$$