# Symmetries for the Euclidean Non-Linear Schrödinger Equation and Related Free Equations 

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February 2004


#### Abstract

We compare certain infinite dimensional Lie algebras of conserved quantities for the free Newton equation $\ddot{q}=0$, the free heat system and the euclidean non-linear Schrödinger equation. There is a natural differential operator defined for all polynomials of the conservation laws $I_{0}, I_{1}, \ldots$ in the NLS hierarchy. We discuss the invariant polynomials and point out a connection to the free classical equation. The basic ingredient is the presence of an extra 'Heisenberg' element in addition to $I_{0}, I_{1}, \ldots$.


0. Introduction. This work is related to the studies of invariance properties of Schrödinger (Bernstein) and related diffusion processes in [1]-[4], [8], [10], [14] and [15], in particular, the case of Gaussian processes [1]-[2].

Going back to a paper [11] by Sophus Lie from 1881, we know that the Lie algebra for the free heat equation in $1+1$ dimensions is, except for a 'trivial' infinite dimensional part stemming from linearity, of dimension six. It is a general fact, see [3], that this Lie algebra has a classical counterpart of constants of motion. In fact, in a certain sense they differ at most by one element which needs a "quantum correction". In particular, they have the same dimension. It is shown in the papers referred to above, how to obtain martingales, or stochastic constants of motion, from the heat Lie algebra.

The classical counterpart to the free heat equation is the free Newton equation $\ddot{q}=0$, which has a six dimensional Poisson-Noether Lie algebra generated by the functions $1, p, p t-q, p^{2}, p(p t-q)$ and $(p t-q)^{2}$, where $p:=\dot{q}$. It may also be described as all constants of motion in the variables $t, q$ and $p$ which are of order at most two w.r.t. $p$. With $I_{n}=p^{n}$ we get an infinite sequence of constants of motion in involution w.r.t. the usual Poisson bracket in two dimensions.

In the case of the free heat Lie algebra, it is clear that partial derivation w.r.t. the space variable $q$ preserves the heat equation: $\partial_{q}$ is a recursion operator [6],
[12]. We can express this in a more symmetric way by looking at the free heat system $\dot{u}+\frac{1}{2} u^{\prime \prime}=0,-\dot{v}+\frac{1}{2} v^{\prime \prime}=0$. (Here and below $\dot{u}=u_{t}$ and $u^{\prime}=u_{q}$.) Then all the functionals $I_{n}:=\frac{1}{2}\left(u^{(n)} v+(-1)^{n} u v^{(n)}\right)$, for $n=0,1, \ldots$ are conservation laws in involution w.r.t. a (well known) natural Lie bracket defined below. It is an elementary but deep fact that

$$
\begin{equation*}
v \frac{\delta I_{n}}{\delta v}-u \frac{\delta I_{n}}{\delta u}=u^{(n)} v-(-1)^{n} u v^{(n)}=\frac{\partial}{\partial q}\left(u^{(n-1)} v-u^{(n-2)} v^{\prime}+\ldots .\right) \tag{1}
\end{equation*}
$$

and that the expression $u^{(n-1)} v-u^{(n-2)} v^{\prime}+\ldots$. between the parentheses on the right is equivalent to $n I_{n-1}=\mathrm{D} I_{n}$, in the sense of conservation laws. The operator $\mathrm{D}=D^{-1}\left(v \frac{\delta}{\delta v}-u \frac{\delta}{\delta u}\right)$ can be extended to a derivation on the space of polynomials obtained from $I_{n}, n \geq 0$.

In the last part of the paper we compare this example with the classical case and a non-linear system of heat equations, viz the Euclidean non-linear heat equation

$$
\begin{equation*}
\dot{u}+\frac{1}{2} u^{\prime \prime}=u^{2} v, \quad-\dot{v}+\frac{1}{2} v^{\prime \prime}=u v^{2} . \tag{2}
\end{equation*}
$$

We also study more generally the structure on the polynomials obtained from a derivation D. This is sketched below, details will appear elsewhere.

1. The heat Lie algebra in $\mathbf{1}+\mathbf{1}$ dimensions. For $u=u(t, q), t, q$ real, we define the (backward) free heat operator by

$$
\begin{equation*}
K u:=\dot{u}+\frac{1}{2} u^{\prime \prime} . \tag{3}
\end{equation*}
$$

Consider all linear partial differential operators $\Lambda$ of order at most one in $(t, q)$ :

$$
\begin{equation*}
\Lambda=T \frac{\partial}{\partial t}+Q \frac{\partial}{\partial q}+U \tag{4}
\end{equation*}
$$

where $T, Q$ and $U$ are functions of $(t, q)$, and where $U$ acts as multiplication operator.
Definition: $\Lambda$ belongs to the heat Lie algebra if, for some function $\Phi=\Phi_{\Lambda}(t, q)$ it holds that

$$
\begin{equation*}
[K, \Lambda]=K \Lambda-\Lambda K=\Phi \cdot K \tag{5}
\end{equation*}
$$

Simple calculations lead to the following well-known facts: The heat Lie algebra consists of two parts, of which the first is generated by the operators

$$
\begin{equation*}
\Lambda_{0}=1 \quad(\text { the centre }), \quad \Lambda_{1}=\frac{\partial}{\partial q}, \quad \Lambda^{*}=\Lambda_{1}^{*}=t \frac{\partial}{\partial q}-q \tag{6}
\end{equation*}
$$

forming the Heisenberg algebra (since $\left[\Lambda_{1}^{*}, \Lambda_{1}\right]=1$ ), whereas the second, generated by

$$
\begin{equation*}
\Xi_{1}=\Lambda_{2}=\frac{\partial}{\partial t}, \quad \Xi_{2}=t \frac{\partial}{\partial t}+\frac{1}{2} q \frac{\partial}{\partial q}\left(+\frac{1}{4}\right), \quad \Xi_{3}=\frac{t^{2}}{2} \frac{\partial}{\partial t}+\frac{t}{2} q \frac{\partial}{\partial q}-\frac{1}{4}\left(q^{2}-t\right) \tag{7}
\end{equation*}
$$

form the Lie algebra $s l_{2}$. (We remark that $\Lambda^{*}$ is not intended to suggest adjoint.)
2. The classical counterpart. Consider a two-dimensional phase space with coordinates $p$ and $q$, and the usual Poisson bracket

$$
\begin{equation*}
\{\phi, \psi\}=\frac{\partial \phi}{\partial p} \frac{\partial \psi}{\partial q}-\frac{\partial \phi}{\partial q} \frac{\partial \psi}{\partial p} \tag{8}
\end{equation*}
$$

Regarding $t$ as a parameter, the functions

$$
\begin{equation*}
1, \quad p \text { and } p t-q \tag{9}
\end{equation*}
$$

form the Heisenberg algebra, whereas

$$
\begin{equation*}
p^{2}, \quad p(p t-q) \quad \text { and } \quad(p t-q)^{2} \tag{10}
\end{equation*}
$$

form $s l_{2}$.
We now turn to the free Newton equation

$$
\begin{equation*}
\ddot{q}=0, \tag{11}
\end{equation*}
$$

in which case $p:=\dot{q}$ and $p t-q$ are obvious constants of motion (CMs). The functions $1, \ldots,(p t-q)^{2}$ is a basis for the CMs which are of order at most two in the variable $p$. We call it the classical algebra.

The first five functions correspond to the same operators as in the heat case. The sixth function corresponds to the operator

$$
\begin{equation*}
\frac{t^{2}}{2} \frac{\partial}{\partial t}+\frac{t}{2} q \frac{\partial}{\partial q}-\frac{q^{2}}{4} \quad(\text { no } t \text {-term }) \tag{12}
\end{equation*}
$$

The zero-order term $q^{2}-t$ in the heat case is the "quantum version", $q^{2}-t=: q^{2}$ : in physicist notation. Readers familiar with stochastic analysis will no doubt recognise the extra term, e.g. from Ito's formula.

The heat Lie algebra and the classical algebra satisfy the same commutator relations. The Heisenberg algebra is an ideal.

Clearly

$$
\begin{equation*}
I_{0}=1, \quad I_{1}=p, \quad I_{2}=p^{2}, \ldots \tag{13}
\end{equation*}
$$

all commute. With

$$
\begin{equation*}
I^{*}=I_{1}^{*}=p t-q \tag{14}
\end{equation*}
$$

we get

$$
\begin{equation*}
\left\{I^{*}, I_{n}\right\}=n I_{n-1}=\frac{d}{d p} I_{n} . \tag{15}
\end{equation*}
$$

We see that $I_{n} \rightarrow I_{n+1}$ is the "creation operator" multiplication with $p$, whereas $I_{n} \rightarrow I_{n-1}$ is the "annihilation operator" $d / d p$.
3. The free heat system. We consider the system of two equations

$$
\begin{equation*}
\dot{u}+\frac{1}{2} u^{\prime \prime}=0 \quad \text { and } \quad-\dot{v}+\frac{1}{2} v^{\prime \prime}=0, \tag{16}
\end{equation*}
$$

obtained from the Lagrangian

$$
\begin{equation*}
L=\frac{1}{2}(u \dot{v}-\dot{u} v)+\frac{1}{2} u^{\prime} v^{\prime} . \tag{17}
\end{equation*}
$$

The symmetry Lie algebra contains the vector fields

$$
\begin{equation*}
\Lambda_{0}=v \frac{\partial}{\partial v}-u \frac{\partial}{\partial u}, \Lambda_{1}=\frac{\partial}{\partial q}, \Lambda_{1}^{*}=t \frac{\partial}{\partial q}-q\left(v \frac{\partial}{\partial v}-u \frac{\partial}{\partial u}\right), \Lambda_{2}=\frac{\partial}{\partial t} \tag{18}
\end{equation*}
$$

By Noether's theorem we get the conservation laws

$$
\begin{equation*}
I_{0}=u v, \quad I_{1}=\frac{1}{2}\left(u^{\prime} v-u v^{\prime}\right), \quad I^{*}=t I_{1}-q I_{0}, \quad I_{2}=\frac{1}{2}\left(u^{\prime \prime} v+u v^{\prime \prime}\right) \tag{19}
\end{equation*}
$$

where $I_{0}, I_{1}$ and $I^{*}=I_{1}^{*}$ form a Heisenberg algebra with respect to the (field theory) bracket

$$
\begin{equation*}
\{F, G\}:=\int\left(\frac{\delta F}{\delta u} \frac{\delta G}{\delta v}-\frac{\delta F}{\delta v} \frac{\delta G}{\delta u}\right) d q \tag{20}
\end{equation*}
$$

$t$ being looked upon as a parameter. Here, the variational derivative refers to the space variable only:

$$
\begin{equation*}
\frac{\delta F}{\delta u}=\frac{\partial F}{\partial u}-\frac{d}{d q} \frac{\partial F}{\partial u^{\prime}}+\frac{d^{2}}{d q^{2}} \frac{\partial F}{\partial u^{\prime \prime}}-\ldots \ldots \tag{21}
\end{equation*}
$$

with a corresponding expression for $\delta F / \delta v$.
There are two more vector fields associated with the remaining elements of $s l_{2}$, viz. $\Xi_{2}=t \frac{\partial}{\partial t}+\frac{q}{2} \frac{\partial}{\partial q}$, and $\Xi_{3}=\frac{t^{2}}{2} \frac{\partial}{\partial t}+\frac{t q}{2} \frac{\partial}{\partial q}-\frac{q^{2}}{4} \Lambda_{0}-\frac{t}{4}\left(u \frac{\partial}{\partial u}+v \frac{\partial}{\partial v}\right)$ but our main interest is with $I_{0}, I_{1}, I^{*}$ and $I_{2}$. We remark however, that in this more symmetric setting the quantum correction disappears: the conservation law corresponding to $\Xi_{3}$ is $1 / 2$ times $t^{2} I_{2}+t q I_{1}-\frac{1}{2} q^{2} I_{0}$.

Now, defining

$$
\begin{equation*}
I_{n}:=\frac{1}{2}\left(u^{(n)} v+(-1)^{n} u v^{(n)}\right), \quad n \geq 0 \tag{22}
\end{equation*}
$$

i.e.

$$
\begin{equation*}
I_{n+1}=C I_{n}=\frac{1}{2} D \cdot I_{n} \quad \text { (Hirota bilinear derivative) } \tag{23}
\end{equation*}
$$

one finds

$$
\begin{equation*}
\left\{I_{m}, I_{n}\right\}=0 \quad \text { and } \quad\left\{I^{*}, I_{n}\right\}=n I_{n-1}, \quad m, n \geq 0 \tag{24}
\end{equation*}
$$

(with $I_{-1}=0$ ).

Exactly as in the classical case, $C$ is the creation and $\left\{I^{*}, \cdot\right\}$ the annihilation operator.
4. Constants of motion for the free heat system. Assume that $u$ and $v$ satisfy (16) (we could add interaction terms here). Then

$$
\begin{equation*}
\frac{d}{d t} \int u v d q=0 \tag{25}
\end{equation*}
$$

assuming, as always, sufficently rapid decrease at infinity, or the boundary, of $u$ and $v$. Let $f=f(t, q)$. It is easy to show that

$$
\begin{equation*}
\frac{d}{d t} \int f u v d q=\int D f u v d q=\int D^{*} f u v d q \tag{26}
\end{equation*}
$$

where

$$
\begin{align*}
D f & :=\frac{1}{u} K(f u)=\dot{f}+\frac{1}{2} f^{\prime \prime}+\frac{u^{\prime}}{u} f,  \tag{27}\\
D^{*} f: & =-\frac{1}{v} K^{\dagger}(f v)=\dot{f}-\frac{1}{2} f^{\prime \prime}-\frac{v^{\prime}}{v} f . \tag{28}
\end{align*}
$$

Then, if $\Lambda=T \partial_{t}+Q \partial_{q}+U$ belongs to the heat Lie algebra, we have

$$
\begin{equation*}
u D(\Lambda u / u)=K \Lambda u=([K, \Lambda]+\Lambda K) u=\left(\Phi_{\Lambda}+\Lambda\right) K u=0 \tag{29}
\end{equation*}
$$

This is an alternative way to express that $\Lambda u \cdot v$ is the density of a conservation law. In more detail, the preceding equation may be written

$$
\begin{equation*}
D(\Lambda u / u)=T \frac{\dot{u}}{u}+Q \frac{u^{\prime}}{u}+U=0 \tag{30}
\end{equation*}
$$

very much as in the classical case. The coefficients $\frac{\dot{u}}{u}$ and $\frac{u^{\prime}}{u}$ are, respectively, the energy density and the momentum density in a form that emphasises the backward motion. The density is $I_{0}=u v$, and e.g. $u^{\prime} v=\frac{u^{\prime}}{u} \cdot I_{0}$ is an equivalent form for $I_{1}$.
5. Euclidean non-linear Schrödinger system. ENS may be looked upon as an extension of the free heat system with a 'potential' $V$ that depends on $u$ and $v$. Let us start somewhat more generally with

$$
\begin{equation*}
\dot{u}+\frac{1}{2} u^{\prime \prime}=V u \quad \text { and } \quad-\dot{v}+\frac{1}{2} v^{\prime \prime}=V v \tag{31}
\end{equation*}
$$

obtained from the Lagrangian

$$
\begin{equation*}
L=\frac{1}{2}(u \dot{v}-\dot{u} v)+\frac{1}{2} u^{\prime} v^{\prime}+\Phi(u v) \tag{32}
\end{equation*}
$$

provided $V=\phi(u v)$, with $\phi=\Phi^{\prime}$.

The following are always conservation laws:

$$
\begin{align*}
& I_{0}=u v, \quad I_{1}=\frac{1}{2}\left(u^{\prime} v-u v^{\prime}\right), \quad I^{*}=t I_{1}-q I_{0}  \tag{33}\\
& I_{2}=\frac{1}{2}\left(u^{\prime \prime} v+u v^{\prime \prime}\right)-2 \Phi(u v) \tag{34}
\end{align*}
$$

for the same reasons as in the free heat case. They also commute.
One can prove that there is a third order conservation law,

$$
\begin{equation*}
\frac{1}{2}\left(u^{\prime \prime \prime} v-u v^{\prime \prime \prime}\right)+\text { terms of lower order } \tag{35}
\end{equation*}
$$

only when $\Phi^{\prime \prime \prime}=0$. Leaving the linear case $\left(\Phi^{\prime \prime}=0\right)$ aside, we choose $\Phi(s)=$ $\frac{1}{2} s^{2}$ so that our heat equations become

$$
\begin{equation*}
\dot{u}+\frac{1}{2} u^{\prime \prime}=u^{2} v \quad \text { and } \quad-\dot{v}+\frac{1}{2} v^{\prime \prime}=u v^{2} \tag{36}
\end{equation*}
$$

corresponding to $V=u v$. This can be seen as a two-dimensional field theory with quartic interaction.

One can prove [8], [16], that there is an operator $C$ such that

$$
\begin{equation*}
I_{n}:=C^{n} I_{0}, \quad n \geq 0, \tag{37}
\end{equation*}
$$

satisfy the same relations as in the free case:

$$
\begin{equation*}
\left\{I_{m}, I_{n}\right\}=0 \quad \text { and } \quad\left\{I^{*}, I_{n}\right\}=n I_{n-1}, \quad m, n \geq 0 \tag{38}
\end{equation*}
$$

After $I_{2}$, the next two are

$$
\begin{align*}
& I_{3}=\frac{1}{2}\left(u^{\prime \prime \prime} v-u v^{\prime \prime \prime}\right)-\frac{3}{2} u v\left(u^{\prime} v-u v^{\prime}\right)  \tag{39}\\
& I_{4}=\frac{1}{2}\left(u^{\mathrm{iv}} v+u v^{\mathrm{iv}}\right)+u^{2} v^{2}+u^{2} v^{\prime 2}+6 u u^{\prime} v v^{\prime}+2 u^{3} v^{3} \tag{40}
\end{align*}
$$

Since all $I_{n}$ commute with $I_{0}$, we have

$$
\begin{equation*}
v \frac{\delta I_{n}}{\delta v}-u \frac{\delta I_{n}}{\delta u}=\frac{d}{d q} a_{n} \tag{41}
\end{equation*}
$$

for some functional $a_{n}$. More generally, one sees that for each $I$ that commutes with $I_{0}$, the operator

$$
\begin{equation*}
\mathrm{D} I:=\left(\frac{d}{d q}\right)^{-1}\left(v \frac{\delta I}{\delta v}-u \frac{\delta I_{n}}{\delta u}\right) \tag{42}
\end{equation*}
$$

is well defined. One can show that for functions of $I_{0}, I_{1}, I_{2}, \ldots, \mathrm{D}$ is a derivation in that

$$
\begin{equation*}
\mathrm{D}\left\{f\left(I_{0}, I_{1}, \ldots, I_{n}\right)\right\}=\sum_{\mu=0}^{n} \partial_{\mu} f\left(I_{0}, I_{1}, \ldots, I_{n}\right) \mathrm{D} I_{\mu} \tag{43}
\end{equation*}
$$

for any $C^{1}$ function $f$. This holds also in the free heat case.
6. Invariant polynomials. We assume, without reference to the particular cases considered above, that we are given variables $I_{0}, I_{1}, I_{2}, \ldots$. , and an operator D such that

$$
\begin{equation*}
\mathrm{D} I_{\mu}=\mu I_{\mu-1} \quad \text { for all } \quad \mu=0,1, \ldots \ldots \ldots \tag{44}
\end{equation*}
$$

We also assume that

$$
\begin{equation*}
\mathrm{D}\left\{f\left(I_{0}, I_{1}, \ldots, I_{n}\right)\right\}=\sum_{\mu=0}^{n} \partial_{\mu} f\left(I_{0}, I_{1}, \ldots, I_{n}\right) \mu I_{\mu-1} \tag{45}
\end{equation*}
$$

for any $n \in \mathbb{N}$ and for any function $f \in C^{1}\left(\mathbb{R}^{n+1}\right)$.
Definition: A function $M=M_{\alpha}$ of the form

$$
\begin{equation*}
M=I_{0}^{\alpha_{0}} I_{1}^{\alpha_{1}} \cdots I_{n}^{\alpha_{n}}, \quad \alpha_{0}, \alpha_{1}, \ldots ., \alpha_{n} \in \mathbb{N} \tag{46}
\end{equation*}
$$

is a monomial of order

$$
\begin{equation*}
N=\sum \mu \alpha_{\mu}=\|\alpha\| . \tag{47}
\end{equation*}
$$

Definition: A function $P$ of the form

$$
\begin{equation*}
P=\sum_{\|\alpha\|=N} c_{\alpha} M_{\alpha} \tag{48}
\end{equation*}
$$

where $c_{\alpha}$ are constants, is a polynomial of order $N$.
Definition: A polynomial $P$ is invariant if

$$
\begin{equation*}
\mathrm{D} P=0 \tag{49}
\end{equation*}
$$

For $N=0$ every polynomial, in fact, every differentiable function, of $I_{0}$ is invariant. These functions should be looked upon as scalars.

For $N=1$ there are no invariant polynomials.
For $N=2$,

$$
\begin{equation*}
K_{2}=I_{1}^{2}-I_{0} I_{2} \tag{50}
\end{equation*}
$$

is invariant, and for $N=3$,

$$
\begin{equation*}
K_{3}=2 I_{1}^{3}-3 I_{0} I_{1} I_{2}+I_{0}^{2} I_{3} \tag{51}
\end{equation*}
$$

is invariant. Up to multiplication with functions of $I_{0}, K_{2}$ and $K_{3}$ are unique.
For $N=4$, of course $K_{2}^{2}$ is invariant. There is another one, unique up to multiplication with functions of $I_{0}$, viz.

$$
\begin{equation*}
K_{4}=4 I_{1} I_{3}-3 I_{2}^{2}-I_{0} I_{4} \tag{52}
\end{equation*}
$$

$K_{4}$ is irreducible.
For $N=5$ we get the obviously invariant polynomial $K_{2} K_{3}$ and a new, irreducible, invariant polynomial, $K_{5}$. For $N=6$ we get $K_{2}^{3}, K_{3}^{2}$ and $K_{2} K_{4}$ in addition to the new, irreducible, invariant polynomial $K_{6}$.

Theorem: For each $N \geq 2$ there is an irreducible invariant polynomial $K_{N}$, unique up to multiplication with functions of $I_{0}$.

Denote by $\mathcal{P}$ all polynomials, and by $\mathcal{M}$ the quotient space

$$
\begin{equation*}
\mathcal{M}=\mathcal{P} /\left(K_{2}, K_{3}, \ldots . .\right) \tag{53}
\end{equation*}
$$

That $K_{2} \equiv 0$ means that $I_{0} I_{2} \equiv I_{1}^{2}$ or

$$
\begin{equation*}
\frac{I_{2}}{I_{0}} \equiv\left(\frac{I_{1}}{I_{0}}\right)^{2} \tag{54}
\end{equation*}
$$

Using also $K_{3} \equiv 0$ we find $I_{3} / I_{0} \equiv\left(I_{1} / I_{0}\right)^{3}$, and so on:

$$
\begin{equation*}
\frac{I_{n}}{I_{0}} \equiv\left(\frac{I_{1}}{I_{0}}\right)^{n}, \quad n=2,3, \ldots \ldots \tag{55}
\end{equation*}
$$

Note that

$$
\begin{equation*}
\mathrm{D} \frac{I_{1}}{I_{0}}=1, \quad \text { and } \quad \mathrm{D} \frac{I_{n}}{I_{0}} \equiv \mathrm{D}\left(\frac{I_{1}}{I_{0}}\right)^{n}=n\left(\frac{I_{1}}{I_{0}}\right)^{n-1}, \quad n=0,1, \ldots . \tag{56}
\end{equation*}
$$

Hence $I_{1} / I_{0}$ correspond to $p$ in our first example, the free equation $\ddot{q}=0$. We remark that $I_{1} / I_{0}$ is the momentum density mentioned at the end of $\S 4$ above.

Acknowledgements: This article was written in memory of my friend Augusto Brandão Correia, 1961-2004, co-author of several papers, and discussion partner for many years. We thank the University of Cyprus and the organisers of Mogran X for their work as well as their friendly and constructive help.

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