Institutionen för matematik **KTH** Chaotic Dynamical Systems, Fall 2006 Michael Benedicks

## Homework assignment 5

This exercise set is due December 19, 2006

1. Consider the diffeomorphism  $Q_{\lambda}$  of the plane given by

$$x_1 = e^x - \lambda$$
  
 $y_1 = -\frac{\lambda}{2} \arctan y$ 

where  $\lambda$  is a parameter.

a. Find all fixed points and periodic points of period 2 for  $Q_{\lambda}$ .

b. Classify each of these periodic points as sinks, sources, or saddles.

c. If the point is a saddle, identify and sketch the stable and unstable manifolds.

2. Let

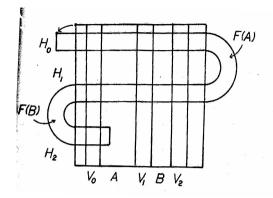
$$A = \begin{pmatrix} 2 & 1 \\ 1 & 1 \end{pmatrix}.$$

Construct a Markov partition for the corresponding map  $L_A$  of the torus.

3. Consider the map F on D defined geometrically as in the picture. Assume that F linearly contracts vertical lengths and linearly expands horizontal lengths in S exactly as in the case of Smale's horseshoe. Let

 $\Lambda = \{ p \in D | F^n(p) \in S \text{ for all } n \in \mathbb{Z} \}.$ 

Show that F on  $\Lambda$  is topologically conjugate to a two-sided subshift of finite type generated by a  $3 \times 3$  matrix A. Identify A. Discuss the dynamics of F off  $\Lambda$ 



4. Linear automorphims of the sphere. Let  $S^2$  denote the twodimensional sphere in  $\mathbb{R}^3$ , i.e.

$$S^{2} = \{ x \in \mathbb{R}^{3} | |x| = 1 \}.$$

Let

$$A = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{pmatrix}$$

and define the map

$$F(x) = F_A(x) = \frac{Ax}{|Ax|}.$$

 $F_A$  os called a linear automorphism of  $S^2$ .

a. Prove that F maps  $\mathbb{R}^3 - \{0\}$  onto  $S^2$ .

b. Prove that the restriction of F to  $S^2$  is a diffeomorphims of the sphere.

c. Let  $e_1 = (1, 0, 0) e_2 = (0, 2, 0) e_3 = (0, 0, 3)$ . Prove that the  $\pm e_i$  are the fixed points of F.

d. Compute the Jacobi matrices  $DF(\pm e_j)$ . Prove that  $DF(\pm e_j)$  has an eigenvalue equal to 0 with corresponding eigenvector  $e_j$ .

e. Prove that each of the other vectors  $e_i$ ,  $i \neq j$ , are also eigenvectors for  $DF(\pm e_j)$ . Evaluate the corresponding eigenvalues.

f. Conclude that  $\pm e_1$  is a source,  $\pm e_2$  is a saddle, and  $\pm e_3$  is a sink.

g. Define  $\phi : S^2 \to \mathbb{R}$  by  $\phi(x) = |A^{-1}x|^2$ . Prove that  $\phi(F(x)) = \phi(x)$  if and only if  $x = \pm e_j$  for some j. The function  $\phi$  is called a gradient function since it decreases along the orbits of F except the fixed points. F itself is called *gradient like*.

h. Use the information above (including the gradient function) to sketch the phase portrait of F