Modern Methods of Statistical Learning sf2935 Auxiliary material: Exponential Family of Distributions Timo Koski

ΤK

#### Second Quarter 2016



The family of distributions with densities (w.r.t. to a  $\sigma$ -finite measure  $\mu$ ) on  $\mathcal{X}$  defined by

$$f(x \mid \theta) = C(\theta)h(x)e^{R(\theta) \cdot T(x)}$$

is called an exponential family, where

- $C(\theta)$  and h(x) are functions from  $\Theta$  and  $\mathcal{X}$  to  $R_+$ ,
- $R(\theta)$  and T(x) are functions from  $\Theta$  and  $\mathcal{X}$  to  $R^k$ ,
- $R(\theta) \cdot T(x)$  is a scalar product in  $R^k$ , i.e.,

$$R(\theta) \cdot T(x) = \sum_{i=1}^{k} R_i(\theta) \cdot T_i(x)$$



The  $\sigma$ -finite measure  $\mu$  appears as follows:

$$\begin{split} 1 &= C(\theta) \int_{\mathcal{X}} h(x) e^{R(\theta) \cdot T(x)} d\mu(x). \\ C(\theta) &= \frac{1}{\int_{\mathcal{X}} h(x) e^{R(\theta) \cdot T(x)} d\mu(x)}. \\ \mathcal{N} &:= \left\{ \theta | \int_{\mathcal{X}} h(x) e^{R(\theta) \cdot T(x)} d\mu(x) < \infty \right\} \end{split}$$

 ${\cal N}$  is called the natural parameter space.



### EXAMPLES OF EXPONENTIAL FAMILIES: $Be(\theta)$

$$f(x|\theta) = \theta^{x} \cdot (1-\theta)^{1-x}$$
.  $x = 0, 1$ 

We write

$$f(x|\theta) = C(\theta)e^{R(\theta)\cdot x}$$
,

where

$$C(\theta) = e^{\log 1-\theta}, T(x) = x, R(\theta) = \log \frac{\theta}{1-\theta}, h(x) = 1.$$

ΤK



・ 同 ト ・ ヨ ト ・ ヨ ト

## EXAMPLES OF EXPONENTIAL FAMILIES: $N(\mu, \sigma^2)$

$$\begin{aligned} \mathbf{x}^{(n)} &= (x_1, x_2, \dots, x_n), \ x_i \ \text{I.I.D.} \sim \mathcal{N}(\mu, \sigma^2). \\ & f(\mathbf{x}^{(n)} | \mu, \sigma^2) = \frac{1}{\sigma^n (2\pi)^{n/2}} e^{-\frac{1}{2\sigma^2} \sum_{i=1}^n (x_i - \mu)^2} \\ &= \frac{1}{(2\pi)^{n/2}} \sigma^{-n} e^{-\frac{n\mu^2}{2\sigma^2}} e^{-\frac{1}{2\sigma^2} \sum_{i=1}^n x_i^2 + \frac{\mu}{\sigma^2} n \overline{x}}. \end{aligned}$$

ΤK



- 4 同 6 4 日 6 4 日 6

### EXAMPLES OF EXPONENTIAL FAMILIES: $N(\mu, \sigma^2)$

$$f(x^{(n)}|\mu,\sigma^{2}) = \frac{1}{(2\pi)^{n/2}} \sigma^{-n} e^{-\frac{n\mu^{2}}{2\sigma^{2}}} e^{-\frac{1}{2\sigma^{2}}\sum_{i=1}^{n}x_{i}^{2} + \frac{\mu}{\sigma^{2}}n\overline{x}}.$$

$$C(\theta) = \sigma^{-n} e^{-\frac{n\mu^{2}}{2\sigma^{2}}}, h(x) = \frac{1}{(2\pi)^{n/2}}.$$

$$R(\theta) \cdot T\left(x^{(n)}\right) = R_{1}(\theta) T_{1}\left(x^{(n)}\right) + R_{2}(\theta) T_{2}\left(x^{(n)}\right)$$

$$T_{1}\left(x^{(n)}\right) = \sum_{i=1}^{n}x_{i}^{2}, T_{2}\left(x^{(n)}\right) = n\overline{x}$$

$$R_{1}(\theta) = -\frac{1}{2\sigma^{2}}, R_{2}(\theta) = \frac{\mu}{\sigma^{2}}$$



- 4 同 6 4 日 6 4 日 6

In an exponential family there exists a *sufficient statistic* of constant dimension (i.e., not depending on n) for any I.I.D. sample

$$x_1, x_2, \ldots, x_n \sim f(x|\theta)$$
.

This means that

$$f(x_1|\theta) \cdot f(x_2|\theta) \cdot \ldots \cdot f(x_n|\theta)$$
$$= C(\theta)^n \prod_{i=1}^n h(x_i) e^{R(\theta) \cdot \sum_{i=1}^n T(x_i)}$$



### Exponential Families & Sufficient Statistics (2)

$$C(\theta)^n \cdot \prod_{i=1}^n h(x_i) \cdot e^{R(\theta) \cdot \sum_{i=1}^n T(x_i)}$$

where

$$\sum_{i=1}^{n} T(x_i) \in \mathcal{X}$$

ΤK

is a sufficient statistic (explained next  $\Rightarrow$ ).



For  $x \sim f(x|\theta)$ , a function T of x is called a sufficient statistic (for  $\theta$ ), if the distribution of x conditional on T(x) does not depend on  $\theta$ .

$$f(x|T,\theta) = f(x|T)$$

Bayesian definition:

$$\pi\left(\theta|x\right) = f\left(T,\theta\right)$$



$$\begin{aligned} \mathbf{x}^{(n)} &= (x_1, x_2, \dots, x_n), \ x_i \text{ I.I.D.} \sim \text{Be}(\theta). \\ f(\mathbf{x}^{(n)}|\theta) &= C(\theta)^n \prod_{i=1}^n e^{R(\theta) \cdot x_i} = C(\theta)^n e^{R(\theta) \sum_{i=1}^n t(x_i)} \\ &= \theta^t (1-\theta)^{n-t} \end{aligned}$$

We know that

$$\sum_{i=1}^{n} t(x_i) \sim \operatorname{Bin}(\theta, n)$$

ΤK



-∢ ≣ →

### Sufficient Statistic: Example (contn'd)

Since  $t = t(x_i)$  is determined by  $x^{(n)}$ ,

$$f(x^{(n)}|\theta, t) = \frac{f(x^{(n)}, t|\theta)}{f(t|\theta)}$$
$$= \frac{\theta^t (1-\theta)^{n-t}}{\binom{n}{t} \theta^t (1-\theta)^{n-t}} = \frac{1}{\binom{n}{t}}$$

which does not depend on  $\theta$ ,  $\sum_{i=1}^{n} t(x_i)$  is sufficient.



lf

$$f(x \mid \theta) = C(\theta)h(x)e^{\theta \cdot x}$$

where  $\Theta \subseteq R^k$  and  $\mathcal{X} \subseteq R^k$ , the family is said to be *natural*. Here  $\theta \cdot x$  is inner product on  $R^k$ .



### Natural Exponential Families (2)

$$f(x \mid \theta) = h(x)e^{\theta \cdot x - \psi(\theta)}$$

where

$$\psi\left(\theta\right) = -\log C(\theta).$$

ΤK



э

#### Natural Exponential Families: Poisson Distribution

$$f(x \mid \lambda) = e^{-\lambda} \frac{\lambda^{x}}{x!}, x = 0, 1, 2, \dots,$$
$$= \frac{1}{x!} e^{\theta x - e^{\theta}}$$
$$\psi(\theta) = e^{\theta}, \theta = \log \lambda, h(x) = \frac{1}{x!}$$

ТΚ



-∢ ≣ →

If  $E_{\theta}[x]$  denotes the mean (vector) of  $x \sim f(x|\theta)$  in a natural family, then

$$E_{\theta}\left[x
ight] = \int_{\mathcal{X}} xf\left(x \mid \theta
ight) dx = 
abla_{ heta}\psi\left( heta
ight).$$

where  $\Theta \in int(\mathcal{N})$  and  $\mathcal{X} \subseteq R^k$ . **Proof**:

$$\int_{\mathcal{X}} xf(x \mid \theta) \, dx = e^{-\psi(\theta)} \int_{\mathcal{X}} h(x) x e^{\theta \cdot x} \, dx$$



### Mean in a Natural Exponential Family

$$e^{-\psi(\theta)} \int_{\mathcal{X}} h(x) x e^{\theta \cdot x} dx = e^{-\psi(\theta)} \int_{\mathcal{X}} h(x) \nabla_{\theta} e^{\theta \cdot x} dx$$
$$= e^{-\psi(\theta)} \nabla_{\theta} \int_{\mathcal{X}} h(x) e^{\theta \cdot x} dx = e^{-\psi(\theta)} \nabla_{\theta} \frac{1}{C(\theta)} =$$
$$= e^{-\psi(\theta)} \frac{(-\nabla_{\theta} C(\theta))}{C(\theta)^{2}}$$
$$= C(\theta) \frac{(-\nabla_{\theta} C(\theta))}{C(\theta)^{2}} = \frac{(-\nabla_{\theta} C(\theta))}{C(\theta)}$$
$$= \nabla_{\theta} (-\log C(\theta)) = \nabla_{\theta} \psi(\theta).$$



- ( E

## Mean in a Natural Exponential Family : Poisson Distribution

$$f(x \mid \lambda) = \frac{1}{x!} e^{\theta x - e^{\theta}}$$
$$\psi(\theta) = e^{\theta}$$
$$E_{\theta}[x] = \frac{d}{d\theta} \psi(\theta) = e^{\theta} = \lambda.$$



## Conjugate Priors for Exponential Families: An Intuitive Example

$$x^{(n)} = (x_1, x_2, \dots, x_n). \ x_i \sim \text{Po}(\lambda), \text{ I.I.D.},$$

$$f\left(\mathbf{x}^{(n)} \mid \lambda\right) = e^{-n\lambda} \frac{\lambda \sum_{i=1}^{n} x_i}{\prod_{i=1}^{n} x_i!}$$

The likelihood is

$$I\left(\lambda|x^{(n)}\right) \propto e^{-n\lambda}\lambda^{\sum_{j=1}^{n}x_{j}}$$

This suggests the conjugate density as the density of the Gamma distribution, which is of the form

ΤK

$$\pi(\lambda) \propto e^{-\beta\lambda} \lambda^{\alpha-1}$$

and hence

$$\pi\left(\lambda|x^{(n)}\right) \propto e^{-\lambda(\beta+n)} \lambda^{\sum_{i=1}^{n} x_i + \alpha - 1}$$



∃ ► < ∃ ►</p>

Consider the natural exponential family

$$f(x \mid \theta) = h(x)e^{\theta \cdot x - \psi(\theta)}.$$

Then the conjugate family is given by

$$\pi\left(\theta\right) = \psi\left(\theta|\mu,\lambda\right) = K\left(\mu,\lambda\right) e^{\theta \cdot \mu - \lambda \psi(\theta)}$$

and the posterior is

$$\psi\left( heta | \mu + x, \lambda + 1 
ight)$$



Proof: By Bayes' rule

$$\pi(\theta|x) = \frac{f(x \mid \theta) \pi(\theta)}{m(x)}$$

We have

$$f(x \mid \theta) \pi(\theta) = h(x)e^{\theta \cdot x - \psi(\theta)}\psi(\theta \mid \mu, \lambda)$$
$$= h(x)K(\mu, \lambda)e^{\theta \cdot (x + \mu) - (1 + \lambda)\psi(\theta)}$$

ΤK



3.5

#### Conjugate Priors for Exponential Families: Proof

$$m(x) = \int_{\Theta} f(x \mid \theta) \pi(\theta) d\theta =$$
$$= h(x) K(\mu, \lambda) \int_{\Theta} e^{\theta \cdot (x+\mu) - (1+\lambda)\psi(\theta)} d\theta$$
$$= h(x) K(\mu, \lambda) K(x+\mu, \lambda+1)^{-1}$$

ΤK

as  $\psi$  is a density on  $\Theta$ .



#### Conjugate Priors for Exponential Families: Proof

$$\pi \left( \theta | x \right) = \frac{h(x) K\left(\mu, \lambda\right) e^{\theta \cdot (x+\mu) - (1+\lambda)\psi(\theta)}}{h(x) K\left(\mu, \lambda\right) K\left(x+\mu, \lambda+1\right)^{-1}}$$
$$= K\left(x+\mu, \lambda+1\right) e^{\theta \cdot (x+\mu) - (1+\lambda)\psi(\theta)},$$

which shows that the posterior belongs to the same family as the prior and that

ΤK

$$\pi\left(\boldsymbol{\theta}|\boldsymbol{x}\right) = \psi\left(\boldsymbol{\theta}|\boldsymbol{\mu} + \boldsymbol{x}, \boldsymbol{\lambda} + 1\right)$$

as claimed.



The proof requires that

$$\pi\left(\theta\right) = \psi\left(\theta|\mu,\lambda\right) = K\left(\mu,\lambda\right) e^{\theta \cdot \mu - \lambda \psi(\theta)}$$

is a probability density on  $\Theta.$  The conditions for this are given in exercise 3.35.



We have the following properties:

• if  $\pi\left(\theta\right) = K\left(x_{o},\lambda\right)e^{\theta\cdot x_{o}-\lambda\psi\left(\theta\right)}$  then

$$\xi(\theta) = \int_{\Theta} E_{\theta} \left[ x \right] \pi\left( \theta \right) d\theta = \frac{x_{o}}{\lambda}$$

This has been proved by Diaconis and Ylvisaker (1979). The proof is not summarized here.



# Posterior Means with Conjugate Priors for Exponential Families

• if 
$$\pi(\theta) = K(\mu, \lambda) e^{\theta \cdot \mu - \lambda \psi(\theta)}$$
 then  
$$\int_{\Theta} E_{\theta}[x] \pi(\theta | x^{(n)}) d\theta = \frac{\mu + n\overline{x}}{\lambda + n}$$

This follows from the preceding, as shown by Diaconis and Ylvisaker (1979).



$$\int_{\Theta} E_{\theta} [x] \pi \left( \theta | x^{(n)} \right) d\theta = \int_{\Theta} \int_{\mathcal{X}} x f(x|\theta) \, dx \pi \left( \theta | x^{(n)} \right) d\theta$$

(by Fubini's theorem)

$$= \int_{\mathcal{X}} x \int_{\Theta} f(x|\theta) \, \pi\left(\theta|x^{(n)}\right) \, d\theta \, dx$$

(by definition in lecture 9 of sf3935)

$$= \int_{\mathcal{X}} xg(x|x^{(n)}) dx$$

ΤK

the mean of the predictive distribution.

Hence if conjugate priors for exponential families are used, then

$$\int_{\mathcal{X}} xg(x|x^{(n)}) dx = \frac{\mu + n\overline{x}}{\lambda + n}$$

is the mean of the corresponding predictive distribution. This suggests  $\mu$  and  $\lambda$  as 'virtual observations'.



P.S. Laplace<sup>1</sup> formulated the principle of insufficient reason to choose a prior as a uniform prior. There are drawbacks in this. Consider Laplace's prior for  $\theta \in [0, 1]$ 

$$\pi\left(\theta\right) = \left\{ \begin{array}{ll} 1 & 0 \leq \theta \leq 1 \\ 0 & \text{elsewhere,} \end{array} \right.$$

Then consider

 $\phi = \theta^2$ .



1 http://www-groups -and.ac.uk/~history/Mathematicians/Laplace.html ΤK

We find the density of  $\phi = \theta^2$ . Take  $0 < \nu < 1$ .

$$F_{\phi}(v) = P(\phi \le v) = P(\theta \le \sqrt{v}) = \int_{0}^{\sqrt{v}} \pi(\theta) d\theta$$
$$= \sqrt{v}.$$
$$f_{\phi}(v) = \frac{d}{dv} F_{\phi}(v) = \frac{d}{dv} \sqrt{v} = \frac{1}{2} \frac{1}{\sqrt{v}}$$

which is no longer uniform. But how come we should have non-uniform prior density for  $\theta^2$  when there is full ignorance about  $\theta$ ?



We want to use a method (M) for choosing a prior density with the following property:

If  $\psi=g\left(\theta\right)\!,\,g$  a monotone map, then the density of  $\psi$  given by the method (M) is

$$\pi_{\Psi}(\psi) = \pi \left( g^{-1}(\psi) 
ight) \cdot \mid rac{d}{d\psi} g^{-1} \left( \psi 
ight) \mid$$

which is the standard probability calculus rule for change of variable in a probability density.



We shall now describe one method (M), i.e., Jeffreys' prior. In order to introduce Jeffreys' prior we need first to define Fisher information, which will be needed even for purposes other than choice of prior.



A parametric model  $x \sim f(x|\theta)$ , where  $f(x|\theta)$  is differentiable w.r.t to  $\theta \in R$ , we define  $I(\theta)$ , *Fisher information* of x, as

$$I(\theta) = \int_{\mathcal{X}} \left(\frac{\partial \log f(x|\theta)}{\partial \theta}\right)^2 f(x|\theta) \, d\mu(x)$$

Conditions for existence of  $I(\theta)$  are given in Schervish (1995), p. 111.



### Fisher Information of x: An Example

$$I\left(\theta\right) = E_{\theta} \left[ \left( \frac{\partial \log f\left(X|\theta\right)}{\partial \theta} \right)^{2} \right]$$

Example:

$$f(x|\theta) = \frac{1}{\sigma\sqrt{2\pi}} e^{-(x-\theta)^2/2\sigma^2}$$

 $\sigma$  is known.

$$\frac{\partial \log f(\mathbf{x}|\theta)}{\partial \theta} = \frac{(\mathbf{x} - \theta)}{\sigma^2}$$
$$I(\theta) = E\left[\frac{(\mathbf{x} - \theta)^2}{\sigma^4}\right] = \frac{\sigma^2}{\sigma^4} = \frac{1}{\sigma^2}$$



→

 $x \sim f(x|\theta)$ , where  $f(x|\theta)$  is differentiable w.r.t to  $\theta \in R^k$ , we define  $I(\theta)$ , Fisher information of x, as the matrix

$$I(\theta) = (I_{ij}(\theta))_{i,j=1}^{k,k}$$
$$I_{ij}(\theta) = \operatorname{Cov}_{\theta}\left(\frac{\partial \log f(x|\theta)}{\partial \theta_{i}}, \frac{\partial \log f(x|\theta)}{\partial \theta_{j}}\right)$$



## Fisher Information of $x^{(n)}$

Same parametric model  $x_i \sim f(x|\theta)$ , I.I.D.,  $x^{(n)} = (x_1, x_2, \dots, x_n)$ .

$$f\left(x^{(n)}|\theta\right) = f\left(x_1|\theta\right) \cdot f\left(x_2|\theta\right) \cdot \ldots \cdot f\left(x_n|\theta\right)$$

Fisher information of  $x^{(n)}$  is

$$I_{x^{(n)}}(\theta) = \int_{\mathcal{X}} \left( \frac{\partial \log f\left(x^{(n)}|\theta\right)}{\partial \theta} \right)^2 f\left(x^{(n)}|\theta\right) d\mu\left(x^{(n)}\right)$$
$$= n \cdot I(\theta).$$



#### Fisher Information of *x*: another form

A parametric model  $x \sim f(x|\theta)$ , where  $f(x|\theta)$  is twice differentiable w.r.t to  $\theta \in R$ . If we can write

$$\frac{d}{d\theta} \int_{\mathcal{X}} \left( \frac{\partial \log f(x|\theta)}{\partial \theta} \right) f(x|\theta) \, d\mu(x) =$$
$$= \int_{\mathcal{X}} \frac{\partial}{\partial \theta} \left( \frac{\partial \log f(x|\theta)}{\partial \theta} \right) f(x|\theta) \, d\mu(x),$$

then

$$I(\theta) = -\int_{\mathcal{X}} \left( \frac{\partial^2 \log f(x|\theta)}{\partial \theta^2} \right) f(x|\theta) \, d\mu(x)$$



 $x \sim f\left(x|\theta\right)$  , where  $f\left(x|\theta\right)$  is differentiable w.r.t to  $\theta \in R^k$  , then under some conditions

$$I(\theta) = \left[ \left( -E_{\theta} \left( \frac{\partial^2 \log f(x|\theta)}{\partial \theta_i \partial \theta_j} \right) \right)_{ij} \right]_{i,j=1}^{k,k}$$



For a natural exponential family

$$f(x \mid \theta) = h(x)e^{\theta \cdot x - \psi(\theta)}$$
$$\frac{\partial^2 \log f(x \mid \theta)}{\partial \theta_i \partial \theta_i} = -\frac{\partial^2 \psi(\theta)}{\partial \theta_i \partial \theta_i}$$

so no expectation needs to be computed to obtain  $I(\theta)$ .



$$\pi\left(\theta\right) := \frac{\sqrt{I\left(\theta\right)}}{\int_{\Theta} \sqrt{I\left(\theta\right)} d\theta}$$

assuming that the standardizing integral in the denominator exists. Otherwise the prior is improper.



Let  $\psi = g(\theta)$ , g a monotone map. The prior  $\pi(\theta)$  is Jeffreys' prior. Let us compute the prior density  $\pi_{\Psi}(\psi)$  for  $\psi$ :

$$\begin{aligned} \pi_{\Psi}(\psi) &= \pi \left( g^{-1}(\psi) \right) \cdot \left| \frac{d}{d\psi} g^{-1}(\psi) \right| \\ &\propto \sqrt{E_{\theta} \left[ \left( \frac{\partial \log f\left( X | \theta \right)}{\partial \theta} \right)^2 \right]} \left| \frac{d}{d\psi} g^{-1}(\psi) \right| \\ &= \sqrt{E_{g^{-1}(\psi)} \left[ \left( \frac{\partial \log f\left( X | g^{-1}(\psi) \right)}{\partial \theta} \frac{d}{d\psi} g^{-1}(\psi) \right)^2 \right]} \\ &= \sqrt{E_{g^{-1}(\psi)} \left[ \left( \frac{\partial \log f\left( X | g^{-1}(\psi) \right)}{\partial \psi} \right)^2 \right]} = I(\psi) \end{aligned}$$

ΤK

Hence the prior for  $\psi$  is the Jeffreys' prior.



(日) (同) (三) (三)

We are going to discuss maximum entropy prior densities. We need a new definition: Kullback's Information Measure.



Let f(x) and g(x) be two densities. Kullback's information measure I(f;g) is defined as

$$I(f;g) := \int_{\mathcal{X}} f(x) \log \frac{f(x)}{g(x)} d\mu(x).$$

We intertpret  $\log \frac{f(x)}{0} = \infty$ ,  $0 \log 0 = 0$ . It can be shown that  $I(f;g) \ge 0$ . Kullback's Information Measure does not require the same kind of

conditions for existence as the Fisher information.



# Kullback's Information Measure: Two Normal Distributions

Let f(x) and g(x) be densities for  $N(\theta_1; \sigma^2)$ ,  $N(\theta_2; \sigma^2)$ , respectively.

Then

$$\log \frac{f(x)}{g(x)} = \frac{1}{2\sigma^2} \left[ (x - \theta_2)^2 - (x - \theta_1)^2 \right]$$
$$I(f;g) = \frac{1}{2\sigma^2} E_{\theta_1} \left[ (x - \theta_2)^2 - (x - \theta_1)^2 \right]$$
$$= \frac{1}{2\sigma^2} \left[ E_{\theta_1} (x - \theta_2)^2 - \sigma^2 \right].$$



### Kullback's Information Measure: Two Normal Distributions

We have

$$\begin{split} E_{\theta_1}\left(x-\theta_2\right)^2 &= E_{\theta_1}\left(x^2\right)-2\theta_2 E_{\theta_1}\left(x\right)+\theta_2^2\\ &= \sigma^2+\theta_1^2-2\theta_2\theta_1+\theta_2^2=\sigma^2+(\theta_1-\theta_2)^2\,. \end{split}$$

Then

$$\begin{split} I\left(f;g\right) &= \frac{1}{2\sigma^2}\left[\sigma^2 + (\theta_1 - \theta_2)^2 - \sigma^2\right] = \\ &= \frac{1}{2\sigma^2}\left(\theta_1 - \theta_2\right)^2. \end{split}$$

$$I(f;g) = \frac{1}{2\sigma^2} \left(\theta_1 - \theta_2\right)^2$$



< ∃⇒

## Kullback's Information Measure: Natural exponential densities

Let 
$$f_i(x) = h(x)e^{\theta_i \cdot x - \psi(\theta_i)}$$
,  $i = 1, 2$ . Then  
 $I(f_1; f_2) = (\theta_1 - \theta_2) \cdot \nabla_{\theta} \psi(\theta_1) - (\psi(\theta_1) - \psi(\theta_2))$ 



Let  $\pi\left(\theta\right)$  and  $\pi_{o}\left(\theta\right)$  be two densities on  $\Theta$ 

$$I(\pi; \pi_o) = \int_{\Theta} \pi(\theta) \log \frac{\pi(\theta)}{\pi_o(\theta)} dv(\theta).$$

ΤK

Here v is another  $\sigma$ -finite measure.



Find  $\pi(\theta)$  so that

$$I\left(\pi;\pi_{o}\right):=\int_{\Theta}\pi\left(\theta\right)\log\frac{\pi\left(\theta\right)}{\pi_{o}\left(\theta\right)}d\nu(\theta).$$

is maximized under the constraints (on moments, quantiles e.t.c.)

$$E_{\pi}\left[g_{k}(\theta)\right]=\omega_{k}.$$

The method is due to E. Jaynes, see, e.g., his *Probability Theory: The Logic of Science* 



Find  $\pi(\theta)$  so that

$$I\left(\pi;\pi_{o}\right):=\int_{\Theta}\pi\left(\theta\right)\log\frac{\pi\left(\theta\right)}{\pi_{o}\left(\theta\right)}d\nu(\theta).$$

is maximized under the constraints (on moments, quantiles e.t.c.)

$$E_{\pi}\left[g_{k}(\theta)\right]=\omega_{k}$$

Maybe Winkler's experiments could be redone like this: the assessor gives several  $\omega_k$ , and maximum entropy  $\pi$ .



This gives, by use of calculus of variation,

$$\pi^{*}\left(\theta\right) = \frac{e^{\sum_{k}\lambda_{k}g_{k}\left(\theta\right)}\pi_{o}\left(\theta\right)}{\int e^{\sum_{k}\lambda_{k}g_{k}\left(\eta\right)}\pi_{o}\left(d\eta\right)},$$

ΤK

where  $\lambda_k$  are derived from Lagrange multipliers.

