

```
r=[1+0.9^(2) -0.9 0 0]
```

← ~~Aut~~ = $[y(0), y(1), y(2), y(3)]$ for
ACVF

$$z_t = z_t - 0.5 z_{t-1}$$

```
r =
```

```
1.8100 -0.9000 0 0
```

```
GA=toeplitz(r)
```

```
GA =
```

COVARIANCE MATRIX

```
1.8100 -0.9000 0 0
-0.9000 1.8100 -0.9000 0
0 -0.9000 1.8100 -0.9000
0 0 -0.9000 1.8100
```

 Γ_4

```
[C v]=ldl(GA)
```

← lower diagonal decomposition of Γ_n using MATLAB
SIGNAL PROCESSING TOOLBOX

```
C =
```

```
1.0000 0 0 0
-0.4972 1.0000 0 0
0 -0.6606 1.0000 0
0 0 -0.7404 1.0000
```

$$\Gamma_4 = C_4 D_4 C_4^T$$

↓

```
v =
```

```
1.8100 0 0 0
0 1.3625 0 0
0 0 1.2155 0
0 0 0 1.1436
```

= D_4

```
innov(GA,3)
```

← SF 2543 HOME PROC

```
ans =
```

```
-0.4972 0 0
-0.6606 0 0
-0.7404 0 0
```

```
v.*eye(4)
```

```
ans =
```

```
1.8100 0 0 0
0 1.3625 0 0
0 0 1.2155 0
0 0 0 1.1436
```

```
D=v.*eye(4)
```

```
D =
```

```
1.8100 0 0 0
0 1.3625 0 0
0 0 1.2155 0
0 0 0 1.1436
```

```
C*D*C'
```

```
ans =
```

```
1.8100 -0.9000 0 0
-0.9000 1.8100 -0.9000 0
0 -0.9000 1.8100 -0.9000
0 0 -0.9000 1.8100
```

A CHECK
↓

```
GA
```

```
GA =
```

```
1.8100 -0.9000 0 0
```

$$GA = D * C * D * C'$$

```

-0.9000    1.8100   -0.9000         0
      0   -0.9000    1.8100   -0.9000
      0         0   -0.9000    1.8100

```

help `ldl`

`<strong>ldl</strong>` Block `<strong>ldl</strong>` factorization for Hermitian indefinite matrices. Assuming that A is a Hermitian matrix (that is, $A = A'$), `[L,D] = <strong>ldl</strong>(A)` stores a block diagonal matrix D and a "psychologically lower triangular matrix" (i.e. a product of unit lower triangular and permutation matrices) in L so that $A = L*D*L'$. The block diagonal matrix D has 1×1 and 2×2 blocks on its diagonal. This syntax is not valid for sparse A .

`[L,D,P] = <strong>ldl</strong>(A)` returns unit lower triangular matrix L , block diagonal D , and permutation matrix P so that $P'*A*P = L*D*L'$. This is equivalent to `[L,D,P] = <strong>ldl</strong>(A,'matrix')`.

`[L,D,p] = <strong>ldl</strong>(A,'vector')` returns the permutation information as a vector instead of a matrix. That is, p is a row vector such that $A(p,p) = L*D*L'$.

`L = <strong>ldl</strong>(A)` returns only the "psychologically lower triangular matrix" L as in the two output form. The permutation information is lost, as is the block diagonal factor D . This syntax is not valid for sparse A .

By default, `<strong>ldl</strong>` references only the diagonal and lower triangle of A , and assumes that the upper triangle is the complex conjugate transpose of the lower triangle. Therefore `[L,D,P] = <strong>ldl</strong>(TRIL(A))` and `[L,D,P] = <strong>ldl</strong>(A)` both return the exact same factors.

`[U,D,P] = <strong>ldl</strong>(A,'upper')` references only the diagonal and upper triangle of A and assumes that the lower triangle is the complex conjugate transpose of the upper triangle. This call returns a unit upper triangular matrix U such that $P'*A*P = U'*D*U$ (assuming that A is Hermitian, and not just upper triangular). Similarly, `[L,D,P] = <strong>ldl</strong>(A,'lower')` gives the default behavior.

`[U,D,p] = <strong>ldl</strong>(A,'upper','vector')` returns the permutation information as a vector, as does `[L,D,p] = <strong>ldl</strong>(A,'lower','vector')`.

`[L,D,P,S] = <strong>ldl</strong>(A)` returns unit lower triangular L , block diagonal D , permutation matrix P , and scaling matrix S such that $P'*S*A*S*P = L*D*L'$. This syntax is only available for real sparse matrices, and only the lower triangle of A is referenced. `<strong>ldl</strong>` uses MA57 for real sparse A .

`[L,D,P,S] = <strong>ldl</strong>(A,THRESH)` uses THRESH as the pivot tolerance in MA57. THRESH must be a double scalar lying in the interval $[0, 0.5]$. The default value for THRESH is 0.01. Using smaller values of THRESH may give faster factorization times and fewer entries, but it may also result in a less stable factorization. This syntax is only available for real sparse matrices.

`[U,D,p,S] = <strong>ldl</strong>(A,THRESH,'upper','vector')` sets the pivot tolerance and returns upper triangular U and permutation vector p as described above.

See also [chol](matlab:help chol), [lu](matlab:help lu), [qr](matlab:help qr).

Reference page in Help browser

[doc ldl](matlab:doc ldl)

`inv(C)`

ans =

```

1.0000         0         0         0
0.4972    1.0000         0         0
0.3285    0.6606    1.0000         0
0.2432    0.4891    0.7404    1.0000

```

```

r=[1+0.9^(2) -0.9 zeros(1,98)];
GA=toeplitz(r);
[C v]=ldl(GA);
y=simarma([], -0.9, 100,0.5);
e=inv(C)*y';
yp=(C-eye(100))*e;
i=[1:1:100];
plot(i,y,'r',i,yp,'b')
plot(e)
std(e)

```

```

ans =
    0.6822

```

```
std(e)^2
```

```

ans =
    0.4654

```

```
v(1)
```

```

ans =
    1.8100

```

```
1+0.9^2
```

```

ans =
    1.8100

```

diary off

ACVF (100 values) FOR

$$x_t = z_t - 0.9z_{t-1}$$

$$P_n = (P(i-j))$$

$$\text{Factorize } P_n = C_n D_n C_n^T \quad n=5000$$

SIMULATES 5000 SAMPLES OF $x_t = z_t - 0.9z_{t-1}$

COMPUTES THE INNOVATIONS

$$\varepsilon_n = Ax_n = C^{-1} x_n$$

$$\text{computes } \hat{x}_n = (C - I)\varepsilon_n = C\varepsilon_n - \varepsilon_n \quad (= x_n - \varepsilon_n)$$

estimate

$$A \sigma^2 (=0.5)$$

$$v(1) = y(1)$$

```

y=simarma([], -0.9, 100,0.5);
z=acvf(y);
GA=toeplitz(z);
[C v]=ldl(GA);
e=inv(C)*y';
yp=(C-eye(100))*e;
i=[1:1:100];
plot(i,y,'r',i,yp,'b')
f=acvf(e);
f1=acf(f,1);

```

1
compute $\hat{\gamma}(h)$ by sample covariance
Forms $\hat{C}_n$
FINDS $\hat{C}_n$

```

plot(e)
std(e)^2

```

1
PREDICTORS USING $\hat{C}_n$

$$\hat{x}_n = (\hat{C}_n - I) \epsilon_n$$

```
ans =
```

```
0.3152
```

```

f2=armaacvf([], -0.9, 100, 0.5);
GA=toeplitz(f2);
[C v]=ldl(GA);
e=inv(C)*y';
yp=(C-eye(100))*e;
plot(i,y,'r',i,yp,'b')
plot(f2)
f2=armaacvf([], -0.9, 100, 0.5);
GA=toeplitz(f2);
[C v]=ldl(GA);
e=inv(C)*y';
yp=(C-eye(100))*e;
plot(i,y,'r',i,yp,'b')
plot(f2)
r=[1+0.9^(2) -0.9 0 0 0 0 0]

```

1
compute $\hat{\gamma}(h)$ ACVF FROM
THE PARAMETER VALUE -0.9
 $\hat{x}_t = \hat{\gamma}_t - 0.9 \hat{\gamma}_{t-1}$

BD,
pp. 73-77

```
r =
```

```
1.8100 -0.9000 0 0 0 0 0
```

```
r=[1+0.9^(2) -0.9 0 0 0 0 0]
```

```
r =
```

```
1.8100 -0.9000 0 0 0 0 0
```

```
GA=toeplitz(r)
```

```
GA =
```

```

1.8100 -0.9000 0 0 0 0 0
-0.9000 1.8100 -0.9000 0 0 0 0
0 -0.9000 1.8100 -0.9000 0 0 0
0 0 -0.9000 1.8100 -0.9000 0 0
0 0 0 -0.9000 1.8100 -0.9000 0
0 0 0 0 -0.9000 1.8100 -0.9000
0 0 0 0 0 -0.9000 1.8100

```

```
[C v]=ldl(GA);
```

```
[C v]=ldl(GA)
```

```
C =
```

```

1.0000 0 0 0 0 0 0
-0.4972 1.0000 0 0 0 0 0
0 -0.6606 1.0000 0 0 0 0
0 0 -0.7404 1.0000 0 0 0
0 0 0 -0.7870 1.0000 0 0
0 0 0 0 -0.8169 1.0000 0
0 0 0 0 0 -0.8374 1.0000

```

```
v =
```

1.8100	0	0	0	0	0	0
0	1.3625	0	0	0	0	0
0	0	1.2155	0	0	0	0
0	0	0	1.1436	0	0	0
0	0	0	0	1.1017	0	0
0	0	0	0	0	1.0748	0
0	0	0	0	0	0	1.0564

```
z=iddata(y',[],1);
M=armax(z,[ 0 1])
```

| SYSTEM IDENTIFICATION TOOLBOX

```
M =
Discrete-time MA model: y(t) = C(z)e(t)
C(z) = 1 - 0.9351 z^-1
```

Sample time: 1 seconds

```
Parameterization:
Polynomial orders: nc=1
Number of free coefficients: 1
Use "polydata", "getpvec", "getcov" for parameters and their uncertainties.
```

```
Status:
Estimated using ARMAX on time domain data "z".
Fit to estimation data: 23.39% (prediction focus)
FPE: 0.4902, MSE: 0.4755
diary off
```

$$r = 0.5 * (0.3.^1) / (1 - 0.3^2)$$

r =

0.1648	0.0495	0.0148	0.0045	0.0013
--------	--------	--------	--------	--------

GA=toeplitz(r)

GA =

0.1648	0.0495	0.0148	0.0045	0.0013
0.0495	0.1648	0.0495	0.0148	0.0045
0.0148	0.0495	0.1648	0.0495	0.0148
0.0045	0.0148	0.0495	0.1648	0.0495
0.0013	0.0045	0.0148	0.0495	0.1648

[C v]=ldl(GA)

C =

1.0000	0	0	0	0
0.3000	1.0000	0	0	0
0.0900	0.3000	1.0000	0	0
0.0270	0.0900	0.3000	1.0000	0
0.0081	0.0270	0.0900	0.3000	1.0000

v =

0.1648	0	0	0	0
0	0.1500	0	0	0
0	0	0.1500	0	0
0	0	0	0.1500	0
0	0	0	0	0.1500

 $\text{inv}(C) = C^{-1} = A$

ans =

1.0000	0	0	0	0
-0.3000	1.0000	0	0	0
0.0000	-0.3000	1.0000	0	0
-0.0000	0	-0.3000	1.0000	0
0	0	0.0000	-0.3000	1.0000

diary off

$$y(l) = \frac{0.5}{1-0.3^2} (0.3)^l \quad l=1,2,3,4,5$$

$$\text{ACUE of } \hat{X}_t - 0.3\hat{X}_{t-1} = \hat{e}_t$$

$$P_5 = C_5 D_5 C_5^T$$

 C_5 D_5

Hence:

$$\hat{X}_t = +\phi \hat{X}_{t-1} = 0.3 \hat{X}_{t-1}$$

AS IS KNOWN.

(SEE HANDOUT ON
LINEAR ESTIMATION)

~~$$\hat{X}_n = A_n \hat{X}_n$$~~

$$\hat{e}_n = A_n \hat{X}_n$$

$$\hat{X}_n = (C_n - I) \hat{e}_n = (C_n - I) A_n \hat{X}_n$$

$$A_n C_n = I \Rightarrow \hat{X}_n - A_n \hat{X}_n$$

$$= (I - A_n) \hat{X}_n$$