

# BOOTSTRAP FOR TIME-SERIES

EX. AR(1)

$$z_t = \beta z_{t-1} + \varepsilon_t \quad t=1, 2, \dots$$

$z_0$  GIVEN

$$|\beta| < 1$$

$\{\varepsilon_t\}$  WHITE NOISE  $E[\varepsilon_t \varepsilon_s] = \sigma^2 \delta_{ts} = \begin{cases} \sigma^2 & t=s \\ 0 & t \neq s \end{cases}$

$\varepsilon_t \in \mathcal{F}$  (= UNKNOWN DISTRIBUTION)

OBSERVED TIME-SERIES  $z_0, z_1, \dots, z_n$

LEAST SQUARES: MINIMIZE  $Q(\beta)$

$$Q(\beta) = \sum_{t=1}^n (z_t - \beta z_{t-1})^2$$

$$\hat{\beta} = \frac{\sum_{t=1}^{n-1} (z_t - \bar{z})(z_{t+1} - \bar{z})}{\sum_{t=1}^n (z_t - \bar{z})^2} \quad (\text{yuracel})$$

$$\bar{z} = \frac{1}{n} \sum_{t=1}^n z_t$$

Q: 1) IS  $\hat{\beta}$  BIAISED?

2) WHAT IS  $D(\hat{\beta})$  (= STANDARD ERROR)

A BOOTSTRAP TECHNIQUE:

$$\hat{\varepsilon}_t = z_t - \hat{\beta} z_{t-1} \quad t=2, 3, \dots, n$$

$\hat{F}$ : THE EMPIRICAL DIST'N OF  
THE  $n-1$  RESIDUALS  $\hat{\varepsilon}_t$   
(OR OF  $(\bar{\varepsilon} = \frac{1}{n-1} \sum_{t=2}^n \varepsilon_t) | \hat{\varepsilon}_t - \bar{\varepsilon}$ )

GENERATE BOOTSTRAP TIME SERIES

$$z_t^* = \hat{\beta} z_{t-1}^* + \varepsilon_t^* \quad t=2, 3, \dots, n$$

REPEAT  $B$  TIMES FOR  $t=2, \dots, n$

AND ESTIMATE  $\hat{\beta}^*$  FOR EACH BOOTSTRAP  
TIME SERIES

-  $\hat{SE}_{\text{BOOT}, B}$ : estimate of  $D(\hat{\beta})$