NADA, KTH, Lennart Edsberg

## Tentamen i Kursen DN2221 Tillämpade Numeriska Metoder I Thursday 2012-12-13 kl 14–19

No means of help allowed. To pass 13 credits of max 29 is needed. Present your answers in English or Swedish.

- **1.** Given an  $n \times n$  matrix A with eigenvalues  $\lambda_i$  and eigenvectors  $\mathbf{c}_i$  (column vectors).
  - (1) a) A diagonalization transformation of A is the so called similarity transformation  $S^{-1}AS = D$ , where D is a diagonal matrix. How are S and D related to the eigenvalues and the eigenvectors of A?
  - (2) b) Assume

$$A = \begin{pmatrix} -1 & \alpha \\ \alpha & -1 \end{pmatrix},$$

where  $\alpha$  is a real parameter. Which are the eigenvalues of A? Can A be transformed to diagonal form for all values of  $\alpha$ ? Motivate your answer.

- **2.** Given the ODE  $\ddot{u} + au = 0$  (\*), where the parameter *a* is a real number different from zero.
  - (1) a) For which values of a are the solutions of (\*) stable, and for which unstable?
  - (2) b) When Euler's explicit method is applied to (\*) for which values of the constant stepsize h are the numerical solutions stable?
  - (2) c) Same question as b) when Euler's implicit method is applied.
- **3.** Compute the coefficients a, b and c in the approximation formula  $y''(0) = ay(0) + by(h) + cy(2h) + O(h^p)$  so that the order p is as high as possible.
  - (2) a) Which are the values of a, b and c?
  - (1) b) What is the value of p?
- 4. The following boundary value problem (BVP) occurs in chemical engineering:

$$\frac{1}{P}\frac{d^2u}{dx^2} - \frac{du}{dx} - Du = 0, \quad u(0) = 1 + \frac{1}{P}\frac{du}{dx}(0), \quad \frac{du}{dx}(1) = 0$$

where P is called the Peclet number and D the Dahmköhler number. This problem can be solved with e.g. the shooting method.

- (2) a) Formulate the shooting method for this problem, i.e. formulate the initial value problem (IVP) when introducing  $\frac{du}{dr}(0) = k$
- (2) b) When the IVP is solved numerically for P = 100 and D = 0.21, the *u*-value at x = 1 turns out to be of order  $10^{43}$  almost independently of k. This result came up both for a nonstiff method and a stiff method. Explain why! (this part b) can be solved without having solved a))

5. Consider the first-order PDE-system

$$\frac{\partial \mathbf{u}}{\partial t} + A \frac{\partial \mathbf{u}}{\partial x} = 0$$

where A is the matrix in 1b) above ( $\alpha$  is real).

- (1) a) Verify that the system is hyperbolic for all values of  $\alpha$ .
- (2) b) Use the diagonalization transformation in 1a) to decouple the system into two scalar hyperbolic PDE's.
- (1) c) Let  $\alpha = 3$ . Which are the characteristics of the two decoupled PDEs in 5b).
- 6. Consider the space between two long concentric cylinders, the inner with radius a the outer with radius R. In that space there is a gas with variable concentration c(r, z). The gas is transported with diffusion in the r-direction and convection in the z-direction. The walls of the cylinders are isolated, which means that (∂c/∂r)<sub>r=a</sub> = 0 and (∂c/∂r)<sub>r=R</sub> = 0. The concentration c(r, z) is modeled by the following PDE:

$$v\frac{\partial c}{\partial z} = D(\frac{\partial^2 c}{\partial r^2} + \frac{1}{r}\frac{\partial c}{\partial r})$$

At the entrance of the space the concentration is  $c(r, 0) = c_0$ . The parameters v and D are constants.

- (1) a) Is this PDE elliptic, parabolic or hyperbolic?
- (5) b) Use the Method of Lines to discretize the *r*-interval [a, R] into discrete points  $r_1 = a, r_2 = a + h_r, r_3 = a + 2h_r, \ldots, r_N = R$ . Add yourself ghost points if necessary. Formulate the system of ODEs

$$\frac{d\mathbf{c}}{dz} = B\mathbf{c} + \mathbf{q}, \mathbf{c}(0) = \mathbf{c}_0,$$

i.e. what is B,  $\mathbf{q}$  and  $\mathbf{c}_0$ ? What is the relation between a, R, N and  $h_r$ ?

(4) c) Assume that the implicit Euler method with constant stepsize  $h_t$  is used to solve the ODE-system in 6b). A linear system of equations  $T\mathbf{c}_{k+1} = M\mathbf{c}_k + \mathbf{g}$ ,  $\mathbf{c}_0 = \mathbf{c}(0)$  is obtained. Express how T, M and  $\mathbf{g}$  are related to  $B, \mathbf{q}$  and  $h_t$ .