

Introduction to QR-method

SF2524 - Matrix Computations for Large-scale Systems

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Methods suitable for large sparse matrices

- Power method
 - ▶ Computes largest eigenvalue

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- Arnoldi method for eigenvalue problems
 - ▶ Computes extreme eigenvalue

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Now: QR-method

- Compute all eigenvalues
- Suitable for dense problems
- Small matrices in relation to other algorithms

Agenda QR-method

- 1 Decompositions
 - ▶ Jordan form
 - ▶ Schur decomposition
 - ▶ QR-factorization
- 2 Basic QR-method
- 3 Improvement 1: Two-phase approach
 - ▶ Hessenberg reduction
 - ▶ Hessenberg QR-method
- 4 Improvement 2: Acceleration with shifts
- 5 Convergence theory

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Reading instructions

Point 1: TB Lecture 24

Points 2-4: Lecture notes "QR-method" on course web page

Point 5: TB Chapter 28

(Extra reading: TB Chapter 25-26, 28-29)

1 Decompositions

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Similarity transformation

Suppose $A \in \mathbb{C}^{m \times m}$ and $V \in \mathbb{C}^{m \times m}$ is an invertible matrix. Then

$$A$$

and

$$B = VAV^{-1}$$

have the same eigenvalues.

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Numerical methods based on similarity transformations

- If B is triangular we can read-off the eigenvalues from the diagonal.
- Idea of numerical method: Compute V such that B is triangular.

First idea: compute the Jordan canonical form

Jordan canonical form

Suppose $A \in \mathbb{C}^{m \times m}$. There exists an invertible matrix $V \in \mathbb{C}^{m \times m}$ and a block diagonal matrix such that

$$A = V \Lambda V^{-1}$$

First idea: compute the Jordan canonical form

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where

$$\Lambda = \begin{pmatrix} J_1 & & \\ & \ddots & \\ & & J_k \end{pmatrix},$$

where

$$J_i = \begin{pmatrix} \lambda_i & 1 & & \\ & \ddots & \ddots & \\ & & \ddots & 1 \\ & & & \lambda_i \end{pmatrix}, \quad i = 1, \dots, k$$

Common case: distinct eigenvalues

Suppose $\lambda_i \neq \lambda_j$, $i = 1, \dots, m$. Then,

$$\Lambda = \begin{pmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_m \end{pmatrix}.$$

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Common case: symmetric matrix

Suppose $A = A^T \in \mathbb{R}^{m \times m}$. Then,

$$\Lambda = \begin{pmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_m \end{pmatrix}.$$

Example - numerical stability of Jordan form

Consider

$$A = \begin{pmatrix} 2 & 1 & \\ & 2 & 1 \\ \varepsilon & & 2 \end{pmatrix}$$

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If $\varepsilon > 0$. Then, the eigenvalues are distinct and

$$\Lambda = \begin{pmatrix} 2 + O(\varepsilon^{1/3}) & & \\ & 2 + O(\varepsilon^{1/3}) & \\ & & 2 + O(\varepsilon^{1/3}) \end{pmatrix}.$$

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⇒ Not continuous with respect to ε

⇒ The Jordan form is often not numerically stable

Schur decomposition (essentially TB Theorem 24.9)

Suppose $A \in \mathbb{C}^{m \times m}$. There exists an unitary matrix P

$$P^{-1} = P^*$$

and a triangular matrix T such that

$$A = PTP^*.$$

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The Schur decomposition is numerically stable.

Goal with QR-method: Numerically compute a Schur factorization

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- 2 **Basic QR-method**
- 3 Improvement 1: Two-phase approach
 - ▶ Hessenberg reduction
 - ▶ Hessenberg QR-method
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QR-factorization

Suppose $A \in \mathbb{C}^{m \times m}$. There exists a unitary matrix Q and an upper triangular matrix R such that

$$A = QR$$

QR-factorization

Suppose $A \in \mathbb{C}^{m \times m}$. There exists a unitary matrix Q and an upper triangular matrix R such that

$$A = QR$$

Note: Very different from Schur factorization

$$A = QTQ^*$$

- QR-factorization can be computed with a finite number of iterations
- Schur decomposition directly gives us the eigenvalues

Basic QR-method

Didactic simplifying assumption: All eigenvalues are real

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Basic QR-method = basic QR-algorithm

Simple basic idea: Let $A_0 = A$ and iterate:

- Compute QR -factorization of $A_k = QR$
- Set $A_{k+1} = RQ$.

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- $A_1 = RQ = Q^*A_0Q \Rightarrow A_0, A_1, \dots$ have the same eigenvalues

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- $A_1 = RQ = Q^*A_0Q \Rightarrow A_0, A_1, \dots$ have the same eigenvalues
- More remarkable: $A_k \rightarrow$ triangular matrix (except special cases)

$A_k \rightarrow$ triangular matrix:



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* Time for matlab demo *

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Disadvantages

- Computing a QR-factorization is quite expensive. One iteration of the basic QR-method

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- The method often requires many iterations. (HW3, problem 1)

Improvement demo:

<http://www.youtube.com/watch?v=qmgxzszWwsNc>

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Two-phase approach

We will separate the computation into two phases:

$$\begin{bmatrix} \times & \times & \times & \times & \times \\ \times & \times & \times & \times & \times \\ \times & \times & \times & \times & \times \\ \times & \times & \times & \times & \times \\ \times & \times & \times & \times & \times \end{bmatrix} \xrightarrow{\text{Phase 1}} \begin{bmatrix} \times & \times & \times & \times & \times \\ \times & \times & \times & \times & \times \\ \times & \times & \times & \times & \times \\ \times & \times & \times & \times & \times \\ \times & \times & \times & \times & \times \end{bmatrix} \xrightarrow{\text{Phase 2}} \begin{bmatrix} \times & \times & \times & \times & \times \\ & \times & \times & \times & \times \\ & & \times & \times & \times \\ & & & \times & \times \\ & & & & \times \end{bmatrix}$$

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Phases:

- Phase 1: Reduce the matrix to a Hessenberg with similarity transformations (Section 2.2.1 in lecture notes)

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Phases:

- Phase 1: Reduce the matrix to a Hessenberg with similarity transformations (Section 2.2.1 in lecture notes)
- Phase 2: Specialize the QR-method to Hessenberg matrices (Section 2.2.2 in lecture notes)

Phase 1: Hessenberg reduction

Idea: Compute unitary P and Hessenberg matrix H such that

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Unlike the Schur factorization, this can be computed with a finite number of operations.