

Homework 2.

$$1. a). C_1 B = (1 \ 0 \ 0 \ 0) \begin{pmatrix} 0 & 0 \\ 0 & 1 \\ 1 & 0 \\ 1 & 1 \end{pmatrix} = (0 \ 0).$$

$$C_1 A B = (1 \ 0 \ 0 \ 0) \begin{pmatrix} 0 & 1 & 1 & 0 \\ -1 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 0 \\ 0 & 1 \\ 1 & 0 \\ 1 & 1 \end{pmatrix} \\ = (0 \ 1 \ 1 \ 0) \begin{pmatrix} 0 & 0 \\ 0 & 1 \\ 1 & 0 \\ 1 & 1 \end{pmatrix} = (1 \ 1) \neq (0 \ 0).$$

$$\Rightarrow r_1 = 2.$$

$$C_2 B = (0 \ a \ 1 \ 1) \begin{pmatrix} 0 & 0 \\ 0 & 1 \\ 1 & 0 \\ 1 & 1 \end{pmatrix} = (2 \ a+1) \neq (0 \ 0).$$

$$\Rightarrow r_2 = 1.$$

$L = \begin{pmatrix} 1 & 1 \\ 2 & a+1 \end{pmatrix}$ nonsingular when the system has a relative degree. $\Rightarrow a \neq 1$.

$$b). \quad \dot{\xi}_1 = x_1 = 0.$$

$$\dot{\xi}_1 = \dot{\xi}_2 = x_2 + x_3 = 0.$$

$$\dot{\xi}_2 = \dot{x}_2 + \dot{x}_3 = x_4 + u_1 + u_2 = 0.$$

$$\dot{\xi}_1 = a x_2 + x_3 + x_4 = 0$$

$$\dot{\xi}_1 = (1-a)x_1 + x_2 + x_3 + x_4 + 2u_1 + (a+1)u_2 = 0.$$

$$z = x_2 + x_3 - x_4.$$

$$\dot{z} = -x_2 - x_3 + x_4 = -z.$$

$$c). \quad P_{\Sigma}(s) = \det \begin{pmatrix} sI - A & B \\ -C & 0 \end{pmatrix}$$

$$= \begin{vmatrix} s & -1 & -1 & 0 & 0 & 0 \\ 1 & s & 0 & -1 & 0 & 1 \\ -1 & 0 & s & 0 & 1 & 0 \\ 0 & -1 & -1 & s & 1 & 1 \\ -1 & 0 & 0 & 0 & 0 & 0 \\ 0 & -a & -1 & -1 & 0 & 0 \end{vmatrix} = \begin{vmatrix} -1 & -1 & 0 & 0 & 0 \\ s & 0 & -1 & 0 & 1 \\ 0 & s & 0 & 1 & 0 \\ -1 & -1 & s & 1 & 1 \\ -a & -1 & -1 & 0 & 0 \end{vmatrix}$$

$$= - \begin{vmatrix} 0 & -1 & 0 & 1 \\ s & 0 & 1 & 0 \\ -1 & s & 1 & 1 \\ -1 & -1 & 0 & 0 \end{vmatrix} + \begin{vmatrix} s & -1 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ -1 & s & 1 & 1 \\ -a & -1 & 0 & 0 \end{vmatrix}$$

$$= - \begin{vmatrix} s & 1 & 0 \\ -1 & 1 & 1 \\ -1 & 0 & 0 \end{vmatrix} + \begin{vmatrix} s & 0 & 1 \\ -1 & s & 1 \\ -1 & -1 & 0 \end{vmatrix} - \begin{vmatrix} s & -1 & 1 \\ -1 & s & 1 \\ -a & -1 & 0 \end{vmatrix}$$

$$= +1 + (1+s+s) - (a+1+as+s)$$

$$= +1+1+2s-a-1-as-s = (1-a)s+1-a$$

$$= \cancel{(-3-a)s} - \cancel{3-a} = 0$$

$$\Rightarrow s = -1 \quad \text{when } a \neq 1$$

2. a). Sylvester equation.

$$A\Pi - \Pi P = -b\bar{q} \quad \Pi \in \mathbb{R}^{3 \times 2}$$

$$\begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -1 & -3 & -3 \end{pmatrix} \begin{pmatrix} \pi_{11} & \pi_{12} \\ \pi_{21} & \pi_{22} \\ \pi_{31} & \pi_{32} \end{pmatrix} - \begin{pmatrix} \pi_{11} & \pi_{12} \\ \pi_{21} & \pi_{22} \\ \pi_{31} & \pi_{32} \end{pmatrix} \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} = - \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} \begin{pmatrix} 1 & 0 \end{pmatrix}$$

$$\begin{pmatrix} \pi_{21} & \pi_{22} \\ \pi_{31} & \pi_{32} \end{pmatrix} \begin{pmatrix} \pi_{21} & \pi_{22} \\ \pi_{31} & \pi_{32} \end{pmatrix} - \begin{pmatrix} -\pi_{11} - 3\pi_{21} - 3\pi_{31} & -\pi_{12} - 3\pi_{22} - 3\pi_{32} \end{pmatrix} = \begin{pmatrix} -\pi_{12} & \pi_{11} \\ -\pi_{22} & \pi_{21} \\ -\pi_{32} & \pi_{31} \end{pmatrix} = - \begin{pmatrix} 0 & 0 \\ 0 & 0 \\ 1 & 0 \end{pmatrix}$$

$$\begin{cases} \pi_{21} + \pi_{12} = 0 \Rightarrow \pi_{21} = -\pi_{12} \\ \pi_{22} - \pi_{11} = 0 \Rightarrow \pi_{22} = \pi_{11} \\ \pi_{31} + \pi_{22} = 0 \Rightarrow \pi_{31} = -\pi_{22} = -\pi_{11} \\ \pi_{32} - \pi_{21} = 0 \Rightarrow \pi_{32} = \pi_{21} = -\pi_{12} \\ -\pi_{11} - 3\pi_{21} - 3\pi_{31} + \pi_{32} = -1 \\ -\pi_{12} - 3\pi_{22} - 3\pi_{32} - \pi_{31} = 0 \end{cases}$$

$$-\pi_{11} - 3(-\pi_{12}) - 3(-\pi_{11}) + (-\pi_{12}) = 2\pi_{11} + 2\pi_{12} = -1$$

$$-\pi_{12} - 3\pi_{11} - 3(-\pi_{12}) - (-\pi_{11}) = -2\pi_{11} + 2\pi_{12} = 0 \Rightarrow \pi_{11} = \pi_{12}$$

$$\Rightarrow \pi_{11} = -\frac{1}{4}$$

$$\Rightarrow \Pi = \frac{1}{4} \begin{pmatrix} -1 & -1 \\ 1 & -1 \\ 1 & 1 \end{pmatrix}$$

b) we want (C, A) to be observable and no eigenvalue of T is transmission zero of the system.

$$\Omega = \begin{pmatrix} C \\ CA \\ CA^2 \end{pmatrix} = \begin{pmatrix} c_1 & c_2 & 1 \\ -1 & c_1-3 & c_2-3 \\ 3-c_2 & 8-3c_2 & 6-3(c_2+c_1) \end{pmatrix}.$$

$$\begin{aligned} \det \Omega &= c_1(c_1-3)(6-3c_2+c_1) + c_2(c_2-3)(3-c_2) - (8-3c_2) \\ &\quad - (c_1-3)(3-c_2) + c_2(6-3(c_2+c_1)) - c_1(c_2-3)(8-3c_2) \\ &= c_1^3 - 3c_1^2c_2 + 3c_1c_2^2 - c_2^3 + 3c_1^2 - 6c_1c_2 + 3c_2^2 \\ &\quad + 3c_1 - 3c_2 + 1 \\ &= (c_1 - c_2 + 1)^3 \neq 0 \quad \text{since } c_1 - c_2 + 1 \neq 0. \end{aligned}$$

Eigenvalues of T is $\pm i$.

Transmission zero:

$$\begin{aligned} P_{\Sigma}(s) &= \det \begin{pmatrix} sI - A & B \\ -C & 0 \end{pmatrix} \\ &= \begin{vmatrix} s & -1 & 0 & 0 \\ 0 & s & -1 & 0 \\ 1 & 3 & s+3 & 1 \\ -c_1 & -c_2 & -1 & 0 \end{vmatrix} = s^2 + c_2s + c_1. \end{aligned}$$

For $s = \pm i$, $P_{\Sigma}(s)$ should not be zero

$$\Rightarrow -1 \pm ic_2 + c_1 \neq 0.$$

Consider real c_1, c_2 , the only possibility for this equal to zero is $c_1 = 1, c_2 = 0$.

$$c) \quad c\bar{\pi} = 9 \Rightarrow \begin{cases} -c_1 + c_2 + 1 = 4 \\ -c_1 - c_2 + 1 = 0 \end{cases} \Rightarrow c_1 = -1, c_2 = 2.$$

3. a). $S = \begin{pmatrix} 0 & 1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$ has eigenvalues $0, \pm i$.

Rosenbrock matrix: $\begin{pmatrix} sI-A & B \\ -C & 0 \end{pmatrix}$.

$$P_{\Sigma}(s) = \det \begin{pmatrix} sI-A & B \\ -C & 0 \end{pmatrix}$$

$$= \begin{vmatrix} s & -1 & 0 & -1 & 0 & 0 \\ 0 & s-1 & 0 & 0 & 1 & 0 \\ 0 & 0 & s+2 & 0 & 0 & 1 \\ -1 & 0 & \alpha & s+1 & 0 & 1 \\ -1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & -1 & 0 & 0 \end{vmatrix}$$

$= -s + (\alpha - 2)$ cannot have zero ^{as} root.

$\Rightarrow \alpha \neq 2$ (consider only real α).

We also need (A, B) to be controllable, but it is always true since

$$(B \ AB \ A^2B) = \begin{pmatrix} 0 & 0 & 1 & 1 & 1 & -\alpha+1 \\ 1 & 0 & 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & -2 & 0 & 4 \\ 0 & 1 & 0 & -\alpha-1 & 1 & 3\alpha+2 \end{pmatrix}$$

already has rank 4.

b). Besides the conditions in a), we also need

$(C-Q), \begin{pmatrix} A & P \\ 0 & S \end{pmatrix}$ detectable.

In fact, when $\alpha=0$, the pair (C, A) is not observable. So $(C-Q), \begin{pmatrix} A & P \\ 0 & S \end{pmatrix}$ is not observable.

(also not detectable by further argument).

For the other cases, the pair $(C-Q), \begin{pmatrix} A & P \\ 0 & S \end{pmatrix}$ is always observable.

So the EFORP is solvable when $\alpha \neq 0$ and $\alpha \neq 2$.

c). $\alpha = 1$.

$$A = \begin{pmatrix} 0 & 1 & 0 & 1 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & -2 & 0 \\ 1 & 0 & -1 & 0 \end{pmatrix}$$

We want to solve Sylvester equation

$$\Pi S = A \Pi + P + B T \quad \textcircled{1}$$

$$0 = C \Pi - Q \quad \textcircled{2}$$

$$\textcircled{2} \Rightarrow \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} \pi_{11} & \pi_{12} & \pi_{13} \\ \pi_{21} & \pi_{22} & \pi_{23} \\ \pi_{31} & \pi_{32} & \pi_{33} \\ \pi_{41} & \pi_{42} & \pi_{43} \end{pmatrix} - \begin{pmatrix} 2 & 0 & 0 \\ 0 & 3 & 0 \end{pmatrix} = 0$$

$$\Rightarrow \begin{aligned} \pi_{11} &= 2, \quad \pi_{12} = 0, \quad \pi_{13} = 0, \\ \pi_{41} &= 0, \quad \pi_{42} = 3, \quad \pi_{43} = 0. \end{aligned}$$

$$\begin{aligned} \textcircled{1} \Rightarrow \begin{pmatrix} 2 & 0 & 0 \\ \pi_{21} & \pi_{22} & \pi_{23} \\ \pi_{31} & \pi_{32} & \pi_{33} \\ 0 & 3 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} &= \begin{pmatrix} 0 & 1 & 0 & 1 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & -2 & 0 \\ 1 & 0 & -1 & 1 \end{pmatrix} \begin{pmatrix} 2 & 0 & 0 \\ \pi_{21} & \pi_{22} & \pi_{23} \\ \pi_{31} & \pi_{32} & \pi_{33} \\ 0 & 3 & 0 \end{pmatrix} + \\ &+ \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix} + \begin{pmatrix} 0 & 0 \\ 1 & 0 \\ 0 & 1 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} \pi_{11} & \pi_{12} & \pi_{13} \\ \pi_{21} & \pi_{22} & \pi_{23} \end{pmatrix} \end{aligned}$$

$$\text{row 1: } (0 \ 2 \ 0) = (\pi_{21} \ \pi_{22} + 3 \ \pi_{23}) + (0 \ 0 \ 0) + (0 \ 0 \ 0)$$

$$\Rightarrow (\pi_{21} \ \pi_{22} \ \pi_{23}) = (0 \ -1 \ 0)$$

$$\text{row 2: } (1 \ 0 \ 0) = (0 \ -1 \ 0) + (0 \ 0 \ 0) + (\pi_{11} \ \pi_{12} \ \pi_{13})$$

$$\Rightarrow (\pi_{11} \ \pi_{12} \ \pi_{13}) = (1 \ 1 \ 0)$$

$$\text{row 3: } (-3 \ 0 \ 0) = (2 - \pi_{31} \ -\pi_{32} - 3 \ -\pi_{33}) + (\pi_{21} \ \pi_{22} \ \pi_{23})$$

$$\text{row 4: } (-\pi_{32} \ \pi_{31} \ 0) = (-2\pi_{31} \ -2\pi_{32} \ -2\pi_{33}) + (0 \ 0 \ 1) + (\pi_{21} \ \pi_{22} \ \pi_{23})$$

$$\text{row 3} - \text{row 4} \Rightarrow (\pi_{32} - 3 \ -\pi_{31} \ 0) = (2 + \pi_{31} \ \pi_{32} - 3 \ \pi_{33}) + (0 \ 0 \ -1)$$

$$\Rightarrow \pi_{33} = -1 \quad \pi_{32} = 4, \quad \pi_{31} = 1$$

$$(\pi_{21} \ \pi_{22} \ \pi_{23}) = (-3 \ 0 \ 0) + (\pi_{31} - 2 \ \pi_{32} + 3 \ \pi_{33}) = (-6 \ 7 \ 1)$$

$$\Rightarrow \pi = \begin{pmatrix} 2 & 0 & 0 \\ 0 & -1 & 0 \\ -1 & 4 & 1 \\ 0 & 3 & 0 \end{pmatrix}, \quad T = \begin{pmatrix} 1 & 1 & 0 \\ -6 & 7 & 1 \end{pmatrix}.$$

By using Matlab, we can find K matrix to stabilize

$$A + BK. \quad \text{For example } K = \begin{pmatrix} 1 & 3 & 0 & 1 \\ 1 & 1/2 & -1 & 1/2 \end{pmatrix}.$$

$u = K(x - \pi w) + Tw$ is the answer.