

SF2812 Applied linear optimization, final exam Monday March 13 2017 8.00–13.00

Examiner: Anders Forsgren, tel. 08-790 71 27.

Allowed tools: Pen/pencil, ruler and eraser.

Note! Calculator is not allowed.

Solution methods: Unless otherwise stated in the text, the problems should be solved by systematic methods, which do not become unrealistic for large problems. Motivate your conclusions carefully. If you use methods other than what have been taught in the course, you must explain carefully.

Note! Personal number must be written on the title page. Write only one exercise per sheet. Number the pages and write your name on each page.

22 points are sufficient for a passing grade. For 20-21 points, a completion to a passing grade may be made within three weeks from the date when the results of the exam are announced.

1. Let (LP) be defined as

(LP) minimize
$$c^T x$$

subject to $Ax = b$,
 $x \ge 0$.

where

$$A = \begin{pmatrix} 2 & 1 & -1 & 0 & 0 \\ 1 & 3 & 0 & -1 & 0 \\ -1 & 4 & 0 & 0 & -1 \end{pmatrix}, \quad b = \begin{pmatrix} 5 \\ 5 \\ 1 \end{pmatrix} \quad \text{and} \quad c = \begin{pmatrix} 6 & 1 & 2 & 3 & 1 \end{pmatrix}^T.$$

(a) A person named AF has used GAMS to model and solve this problem. The GAMS input file can be found at the end of the exam. Unfortunately, AF has lost the GAMS output file. He does have a partial GAMS output file, which reads:

---- EQU obj -1.000 obj objective function ---- EQU cons constraints LOWER LEVEL UPPER MARGINAL 5.000 2.000 i1 5.000 5.000 i2 5.000 5.000 5.000 1.000 i3 1.000 1.000 1.000 -1.000 LOWER LEVEL UPPER. MARGINAL. ---- VAR objval -INF 14.000 +INF objval objective function value --- VAR x decision variables LOWER LEVEL UPPER MARGINAL

•	2.000	+INF	•
•	1.000	+INF	
	•	+INF	4.000
	•	+INF	4.000
	1.000	+INF	
		. 1.000 	. 1.000 +INF +INF +INF

- (c) AF is also worried about the precise value of b_1 and wants to know how sensitive the optimal value is to changes in b_1 . Help AF to provide this information. (2p)
- 2. Consider the linear programming problem (*PLP*) and its dual (*DLP*) defined as

 $\begin{array}{lll} \text{minimize} & c^T x & \text{maximize} & b^T y \\ (PLP) & \text{subject to} & Ax = b, & (DLP) & \text{subject to} & A^T y + s = c, \\ & x \ge 0, & s \ge 0, \end{array}$

where

$$A = \begin{pmatrix} 3 & 2 & 1 & 1 \\ 0 & 1 & -1 & 2 \end{pmatrix}, \quad b = \begin{pmatrix} 5 \\ 1 \end{pmatrix}, \quad c = \begin{pmatrix} 6 & 3 & 3 & 3 \end{pmatrix}^{T}.$$

- (b) AF has then implemented a primal-dual interior method in Matlab. To test his solver, he has solved the primal-dual nonlinear equations accurately for $\mu = 10^{-4}$. He has then obtained the following approximate numbers for $x(\mu)$, $y(\mu)$, and $s(\mu)$:

```
xmu' =
    0.4227 1.5773 0.5774 0.0000
ymu' =
    1.9999 -0.9999
smu' =
    0.0002 0.0001 0.0002 2.9999
```

3. Consider a linear program in standard form

 $\begin{array}{ll} \text{minimize} & c^T x \\ \text{subject to} & A_H x = b_H, & A_H \text{ is "complicating", dimension } m \times n, \\ & A_E x = b_E, & A_E \text{ is "easy",} \\ & x \ge 0. \end{array}$

Assume that $\{x : A_E x = b_E, x \ge 0\}$ is bounded with extreme points $v_i, i = 1, ..., k$. Assume further that the problem is solved by Dantzig-Wolfe decomposition.

The master problem becomes

 $\begin{array}{lll} \text{minimize} & c^T V \alpha & \text{minimize} & \sum_{i=1}^k c^T v_i \alpha_i \\ \text{subject to} & A_H V \alpha = b_H, \\ & e^T \alpha = 1, \\ & \alpha \ge 0. \end{array} \Leftrightarrow \begin{array}{lll} \text{minimize} & \sum_{i=1}^k A_H v_i \alpha_i = b_H, \\ & \text{subject to} & \sum_{i=1}^k \alpha_i = 1, \\ & \alpha \ge 0. \end{array}$

Here e denotes a k-dimensional vector with all components one, and $V = \begin{pmatrix} v_1 & v_2 & \cdots & v_k \end{pmatrix}$.

4. Consider the integer program (IP) defined as

(*IP*) minimize $-x_1 - 4x_3 - x_4$ subject to $-4x_1 - 7x_2 - 6x_3 - 5x_4 \ge -10$, $-x_1 - x_2 \ge -1$, $-x_3 - x_4 \ge -1$, $x_j \in \{0, 1\}, \quad j = 1, \dots, 4$.

Assume that the constraints $-x_1 - x_2 \ge -1$ and $-x_3 - x_4 \ge -1$ are relaxed with corresponding nonnegative multipliers v_1 and v_2 . Let $\varphi(v)$ denote the resulting dual objective function. Finally, let $\hat{v} = (1 \ 2)^T$.

5. Consider the linear program (LP) given by

$$(LP) \quad \begin{array}{l} \text{maximize} \quad b^T y \\ \text{subject to} \quad A^T y \le c. \end{array}$$

Let the dimensions of the problem be such that A is an $m \times n$ matrix and let A_i denote the *i*th column of A.

For i = 1, ..., n, let \mathcal{P}_i be a polytope given by $\mathcal{P}_i = \{v_i \in \mathbb{R}^m : C_i^T v_i \leq d_i\}$, for given matrices C_i of dimensions $m \times n_i$ and given vectors d_i of length n_i . Each polytope \mathcal{P}_i is such that $A_i \in \mathcal{P}_i$.

The reason for introducing the sets P_i is that we are interested in solving an optimization problem which is robust against uncertainties in A, given by

(RP)
$$\begin{array}{l} \max inite \quad b^T y \\ \text{subject to} \quad \max_{v_i \in \mathcal{P}_i} \{v_i^T y\} \le c_i, \quad i = 1, \dots, n. \end{array}$$

Hint 1: For a given y, the problem

$$\begin{array}{ll} \underset{v_i \in \mathbb{R}^m}{\operatorname{maximize}} & y^T v_i \\ \text{subject to} & C_i^T v_i \leq d_i, \end{array}$$

is a linear program.

Hint 2: Use strong duality for linear programming.

$$C_i^T = \begin{pmatrix} I \\ -I \end{pmatrix}$$
 and $d_i = \begin{pmatrix} A_i \\ -A_i \end{pmatrix}$,

Good luck!

GAMS file for exercise 1:

```
sets
i rows
               / i1*i3 /
               / j1*j5 /;
j columns
table A(i,j)
       j1
               j2
                       jЗ
                              j4
                                      j5
i1
        2
                       -1
               1
        1
                3
i2
                               -1
       -1
i3
                4
                                      -1;
parameter b(i)
               5
         / i1
           i2 5
           i3 1/;
parameter c(j)
         / j1
               6
           j2 1
           j3 2
           j4 3
           j5 1/;
variables
       objval objective function value
       x(j)
               decision variables;
positive variable x;
equations
                     objective function
       obj
       cons(i)
                     constraints;
obj .. sum(j,c(j)*x(j)) =e= objval;
cons(i) .. sum(j,A(i,j)*x(j)) =e= b(i);
model lpex / all /;
solve lpex using lp minimizing objval;
```