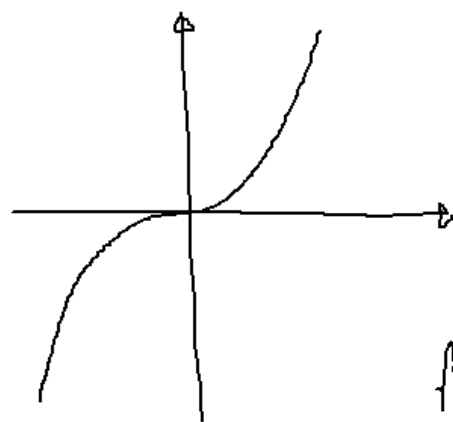


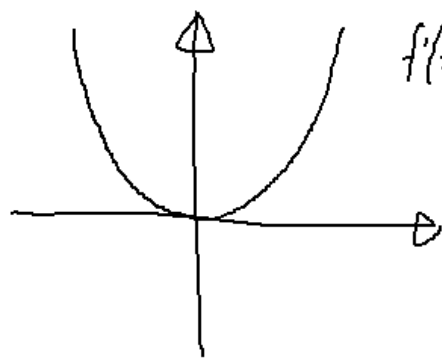
Om lokalt maximum eller
minimum så är $f'(x) = 0$.



$$f(x) = x^3$$

$$f'(0) = 0$$

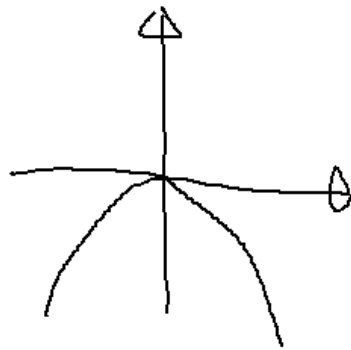
men $x=0$ är varken
lokalt max eller
minimum



$$f(x) = x^2$$

$$f''(0) = 2 > 0$$

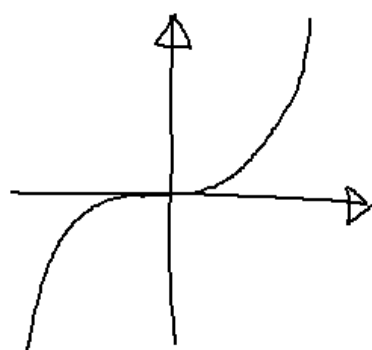
lok min



$$f(x) = -x^2$$

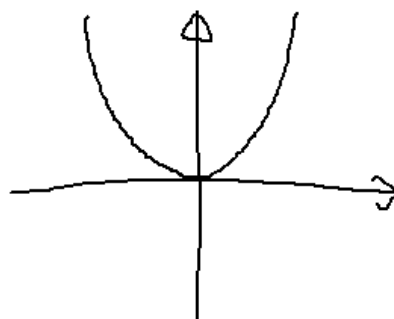
$$f''(0) = -2$$

lok max



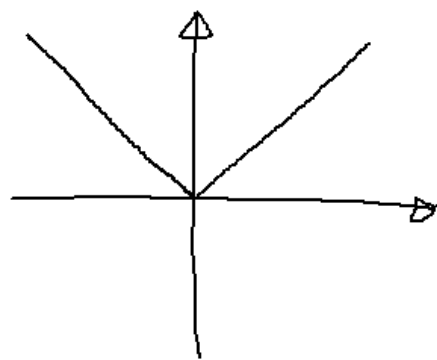
$$f(x) = x^3$$

$$f'(0) = 0$$



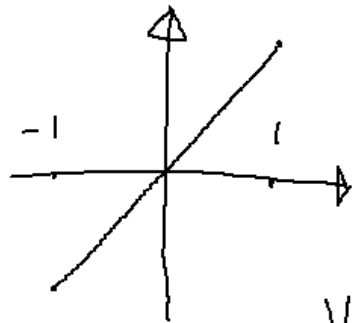
$$f(x) = x^4$$

$$f'(0) = 0$$



$$f(x) = |x|$$

f ej deriverbar
i punkten $x=0$



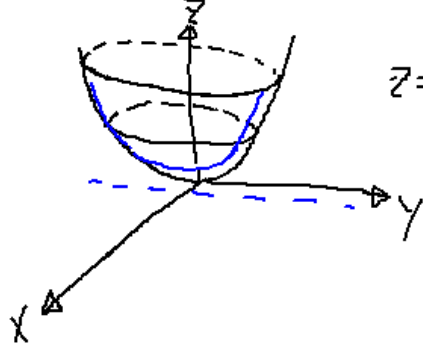
$$f(x) = x$$

$$f'(x) = 1 \neq 0$$

för alla x

V: får min och max
i ändpunkterna.

$$f: \mathbb{R}^2 \rightarrow \mathbb{R}$$



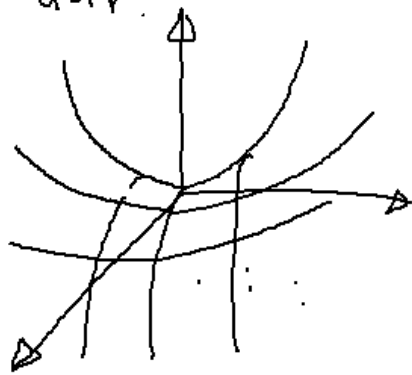
$$z = f(x, y) = x^2 + y^2$$

Lokalt max eller min
medför att $\text{grad} f = (0, 0)$.

Om vi fixerar
 x är vi tillbaka
i en variabel fallet,
så lokalt max eller
min ger $\frac{\partial f}{\partial y} = 0$.

På samma sätt får
vi att $\frac{\partial f}{\partial x} = 0$ i punkten.

$\text{grad } f(a,b) = (0,0)$ ger inte
nödvändigtvis att funktionen
har lokalt max eller min
där.



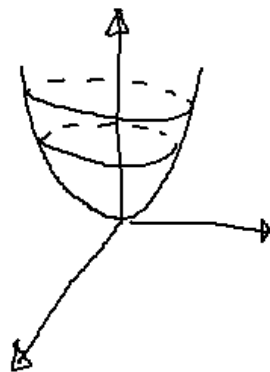
$$z = f(x,y) = y^2 - x^2$$

$$\text{grad } f(0,0) = (0,0)$$

men $(0,0)$ varken
min eller max

En sadelpunkt.

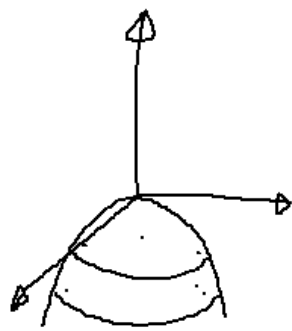
En punkt där $\text{grad } f = (0,0)$
kallas kritisk eller stationär
punkt



$$z = f(x,y) = x^2 + y^2$$

$$\frac{\partial^2 f}{\partial x^2}(0,0) = 2 \quad ; \quad \frac{\partial f}{\partial y}(0,0) = 2$$

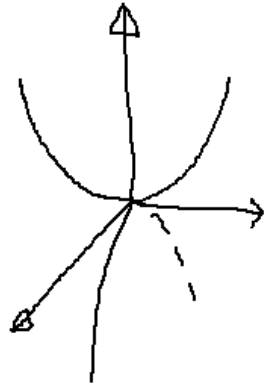
$$\frac{\partial^2 f}{\partial x \partial y}(0,0) = 0$$



$$z = f(x, y) = -x^2 - y^2$$

$$\frac{\partial^2 f}{\partial x^2}(0,0) = -2$$

$$\frac{\partial^2 f}{\partial y^2}(0,0) = -2 \quad \frac{\partial^2 f}{\partial x \partial y}(0,0) = 0$$



$$z = f(x, y) = y^2 - x^2$$

$$\frac{\partial^2 f}{\partial x^2}(0,0) = -2 \quad \frac{\partial^2 f}{\partial y^2}(0,0) = 2$$

$$\frac{\partial^2 f}{\partial x \partial y}(0,0) = 0$$

$$\begin{aligned}
 f(x+h, y+k) &= f(x, y) + \frac{\partial f}{\partial x}(x, y) h + \\
 &+ \frac{\partial f}{\partial y}(x, y) k + \frac{1}{2} \left(\frac{\partial^2 f}{\partial x^2}(x, y) h^2 + 2 \frac{\partial^2 f}{\partial x \partial y}(x, y) h k \right. \\
 &\left. + \frac{\partial^2 f}{\partial y^2}(x, y) k^2 \right) + O(3)
 \end{aligned}$$

Om stationär punkt har vi
att $\frac{\partial f}{\partial x}(x, y) = \frac{\partial f}{\partial y}(x, y) = 0$.

$$\frac{\partial^2 f}{\partial x^2}(x, y) h^2 + 2 \frac{\partial^2 f}{\partial x \partial y}(x, y) h k + \frac{\partial^2 f}{\partial y^2}(x, y) k^2 =$$

$$(h, k) \begin{pmatrix} \frac{\partial^2 f}{\partial x^2}(x, y) & \frac{\partial^2 f}{\partial x \partial y}(x, y) \\ \frac{\partial^2 f}{\partial x \partial y}(x, y) & \frac{\partial^2 f}{\partial y^2}(x, y) \end{pmatrix} \begin{pmatrix} h \\ k \end{pmatrix}$$

\mathbb{K} (symmetrisk matris)

$$\det \mathbb{K} = \frac{\partial^2 f}{\partial x^2}(x, y) \frac{\partial^2 f}{\partial y^2}(x, y) - \left(\frac{\partial^2 f}{\partial x \partial y}(x, y) \right)^2$$

$$\parallel \\ \lambda_1 \cdot \lambda_2 = \det \begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{pmatrix}$$

$$\det K > 0.$$

$$\lambda_1, \lambda_2 > 0$$

$$\lambda_1 \xi^2 + \lambda_2 \eta^2$$

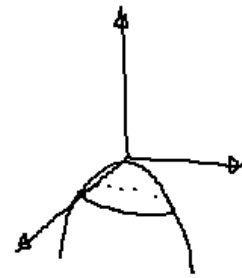
lokalt min



$$\lambda_1, \lambda_2 < 0$$

$$-|\lambda_1| \xi^2 - |\lambda_2| \eta^2$$

lokale max

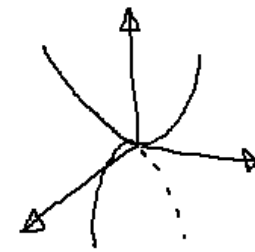


$$\det K < 0$$

$$\lambda_1 < 0, \lambda_2 > 0$$

$$-|\lambda_1| \xi^2 + \lambda_2 \eta^2$$

sattelpunkte



Exempel: $f(x, y) = xy$

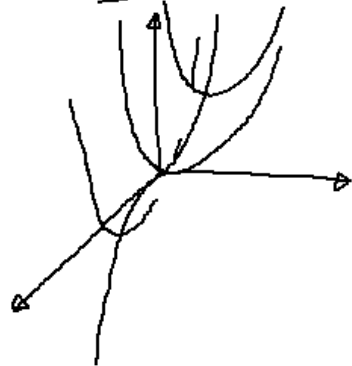
$$\text{grad } f(x, y) = (y, x)$$

$$(x, y) = (0, 0) \text{ stationär punkte}$$

$$\frac{\partial^2 f}{\partial x^2}(0,0) = 0, \quad \frac{\partial^2 f}{\partial y^2}(0,0) = 0, \quad \frac{\partial^2 f}{\partial x \partial y}(0,0) = 1$$

$$\begin{vmatrix} 0 & 1 \\ 1 & 0 \end{vmatrix} = -1 \quad \text{sadel punkte}$$

det H = 0.

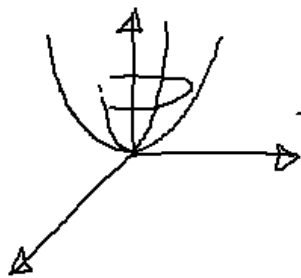


$$z = f(x, y) = y^2 - x^3$$

$$\frac{\partial^2 f}{\partial x^2}(0,0) = 0 \quad \frac{\partial^2 f}{\partial y^2}(0,0) = 2$$

$$\frac{\partial^2 f}{\partial x \partial y} = 0$$

$$\frac{\partial^2 f}{\partial x^2}(0,0) \frac{\partial^2 f}{\partial y^2}(0,0) - \left(\frac{\partial^2 f}{\partial x \partial y}(0,0) \right)^2 = 0 \cdot 2 - 0 = 0$$



$$z = f(x, y) = y^2 + x^4$$

$$\frac{\partial^2 f}{\partial x^2}(0,0) = 0 \quad \frac{\partial^2 f}{\partial y^2}(0,0) = 2, \quad \frac{\partial^2 f}{\partial x \partial y}(0,0) = 0$$

$$\det H = 0.$$

Exempel: $f(x, y) = x^2 + axy + y^2$

$$\frac{\partial f}{\partial x}(x, y) = 2x + ay, \quad \frac{\partial f}{\partial y}(x, y) = ax + 2y$$

Punkten $(x, y) = (0, 0)$ är en stationär punkt.

$$\frac{\partial^2 f}{\partial x^2}(0, 0) = 2 \quad \frac{\partial^2 f}{\partial y^2}(0, 0) = 2$$

$$\frac{\partial^2 f}{\partial x \partial y}(0, 0) = a$$

$$\frac{\partial^2 f}{\partial x^2}(0, 0) \frac{\partial^2 f}{\partial y^2}(0, 0) - \left(\frac{\partial^2 f}{\partial x \partial y}(0, 0) \right)^2 = 4 - a^2$$

$$4-a^2 \quad \begin{array}{c} -2 \qquad 2 \\ \hline - \quad 0 \quad + \quad 0 \quad - \end{array}$$

$$|a| > 2 \Rightarrow 4-a^2 < 0 \Rightarrow \text{saddelpunkte}$$

$$-2 < a < 2 \Rightarrow 4-a^2 > 0 \Rightarrow \text{lokale max} \\ \text{eller min}$$

$$\begin{vmatrix} 2-\lambda & a \\ a & 2-\lambda \end{vmatrix} = (2-\lambda)^2 - a^2 \quad \begin{array}{l} \lambda_1 = 2+a \\ \lambda_2 = 2-a \end{array}$$

$$\lambda_1, \lambda_2 > 0 \Rightarrow \text{lokale minimum.}$$

$$a = -2: \quad x^2 - 2xy + y^2 = (x - y)^2$$

konstant = 0
längs $x = y$



$$a = 2: \quad x^2 + 2xy + y^2 = (x + y)^2$$



konstant = 0
längs linjen $x = -y$.

$$\lambda_1, \lambda_2 > 0 \quad \lambda_1 \xi^2 + \lambda_2 \eta^2 \geq 0$$

och = 0 enbart då

$$(\xi, \eta) = (0, 0)$$

positivt definit

$$\lambda_1, \lambda_2 < 0 \quad -|\lambda_1| \xi^2 - |\lambda_2| \eta^2 \leq 0$$

och = 0 precis då

$$(\xi, \eta) = (0, 0).$$

negativt definit

$\lambda_1 > 0, \lambda_2 < 0$: $\lambda_1 \xi^2 - |\lambda_2| \eta^2 > 0$
för vissa (ξ, η) men
 < 0 för andra.
indefinit

$\lambda_1 > 0, \lambda_2 = 0$: $\lambda_1 \xi^2 \geq 0 = 0$ precis då
positivt semidefinit $\xi = 0$

$\lambda_1 < 0, \lambda_2 = 0$: $-|\lambda_1| \xi^2 \leq 0 = 0$ om
negativt semidefinit $\xi = 0$

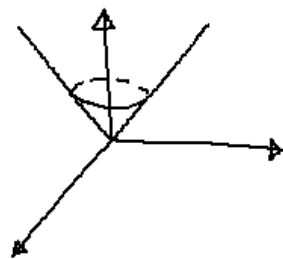
Exempel: $x^2 + 2xy + y^2 = (x+y)^2 \geq 0$
 $(x+y)^2 = 0$ om $x = -y$
positivt semi definit

Sats: $f(\vec{x} + \vec{h}) = f(\vec{x}) + p_k(\vec{h}) + O(k+1)$
där $f: \mathbb{R}^n \rightarrow \mathbb{R}$, p_k är en form
av grad k , så gäller
 $p_k(\vec{h})$ positiv def \Rightarrow lok min
 $p_k(\vec{h})$ neg def \Rightarrow lok max

Eksempel: $f(x) = x^3$
indefinit
ingen ekstremværdi

$f(x) = x^4$
pos def
 $x=0$ lokalt min

Exempel: $z = f(x, y) = \sqrt{x^2 + y^2}$



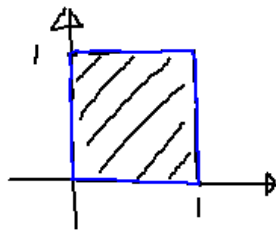
$$\frac{\partial f}{\partial x}(x, y) = \frac{x}{\sqrt{x^2 + y^2}}$$

$$\frac{\partial f}{\partial y}(x, y) = \frac{y}{\sqrt{x^2 + y^2}}$$

Derivatorna är ej definierade
när $(x, y) = (0, 0)$.

V: kan ha extrempunkter även i
sådana punkter.

Exempel: $f(x,y) = x^2 + y^2$



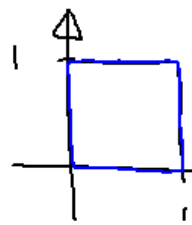
Bestäm max och min för f i området

– Stationära punkter

$$\text{grad } f(x,y) = (2x, 2y) \neq (0,0)$$

i det inre av området \Rightarrow

inga stationära punkter



Randen består av
sträckorna

$$I1. x=0, 0 \leq y \leq 1$$

$$I2. x=1, 0 \leq y \leq 1$$

$$I3. y=0, 0 \leq x \leq 1$$

$$I4. y=1, 0 \leq x \leq 1$$

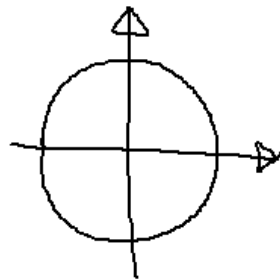
Vi vill maximera
 f när vi är på
 $I1, I2, I3, I4.$

$I1: g(y) = f(0, y)$ ska maximeras då $0 \leq y \leq 1.$

Kolla om $g'(y) = 0$ för något $0 < y < 1$

och sedan $y=0$ och $y=1.$

Exempel:



Området

$$\{x^2 + y^2 \leq 1\}$$

$$f(x, y) = x$$

Kolla stationära punkter: det inre av området

$$\text{grad } f(x, y) = (1, 0) \neq (0, 0)$$

Kolla randen: $\begin{cases} x = \cos t \\ y = \sin t \end{cases} \quad 0 \leq t \leq 2\pi$

$$g(t) = f(\cos t, \sin t) = \cos t$$

$$g'(t) = -\sin t = 0 \text{ om } t = \cancel{0}, \pi, \cancel{2\pi}$$

$$t = \pi \Rightarrow f(\cos t, \sin t) = \cos t = -1$$

Slutligen tollar vi ändpunkterna

$$\begin{array}{l} t = 0 \\ t = 2\pi \end{array} \Rightarrow f(\cos t, \sin t) = \cos t = 1.$$

Så f antar max i punkten $(1, 0)$
och min i punkten $(-1, 0)$.

Det kan vara svårt att hitta en parametrisering av randen. Men om randen ges av en funktion

$$g(x, y) = 0$$

och $\text{grad } g(x_0, y_0) \neq 0$

så vet vi att den kan beskrivas nära punkten som en parameterkurva.

Nära randpunkten (x_0, y_0)

ges randen av $\vec{r}(t)$.

Det betyder att vi vill

minimera/maximera $f(\vec{r}(t))$ som funktion
av t . Från envariabel analys följer
att

$$0 = \frac{d}{dt} f(\vec{r}(t)) = \text{grad } f(\vec{r}(t)) \cdot \vec{r}'(t)$$

Vi kan också beskriva randen

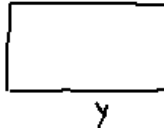
som en nivåkurva $g(x, y) = 0$

så $\text{grad } g$ är normal till kurvan.

Det betyder att

$$\text{grad } f(x_0, y_0) = \lambda \text{ grad } g(x_0, y_0)$$

Exempel:

x  $g(x, y) = x + y - 1 = 0$

$$f(x, y) = x \cdot y$$

$$\text{grad } f(x, y) = (y, x)$$

$$\text{grad } g(x, y) = (1, 1)$$

$$g(x, y) = 0$$

Bestäm x, y så att rektangeln får maximal area.

$$\text{grad } f \parallel \text{grad } g$$

$$\Rightarrow x = y = \frac{1}{2}$$

Des max när kvadrat.

$$f(x, y) = x \quad g(x, y) = x^2 + y^2 - 1 = 0$$

$$\text{grad } f = (1, 0) \quad \text{grad } g(x, y) = (2x, 2y)$$

\Rightarrow extrempunkt när $y = 0$

$$\Rightarrow x^2 - 1 = 0 \Rightarrow x = \pm 1.$$