

# Theory - Primal and dual Simplex method

$$(P) \quad \min c^T x$$

$$\text{s.t. } Ax = b$$

$$x \geq 0$$

$$(D) \quad \max \bar{b}^T y$$

$$\text{s.t. } \bar{A}^T y + s = c$$

$$s \geq 0$$

Partition:  $A = (B \ N)$  ( $B$  with linearly independent columns,  $x_N = 0, s_B = 0$ )

$$\begin{pmatrix} B & N \\ 0 & I \end{pmatrix} \begin{pmatrix} x_B \\ x_N \end{pmatrix} = \begin{pmatrix} b \\ 0 \end{pmatrix} \quad (1)$$

b.f.s. if  $x_B \geq 0$

$$\begin{pmatrix} B^T & 0 \\ N^T & I \end{pmatrix} \begin{pmatrix} y \\ s_N \end{pmatrix} = \begin{pmatrix} c_B \\ c_N \end{pmatrix} \quad (2)$$

b.f.s. if  $s_N \geq 0$

## Primal Simplex

- Given  $x_B \geq 0$  (b.f.s. to (P)) solve (2) to obtain  $y$  and  $s_N$ .

Some  $(s_N)_t$  might be  $< 0$

primal feasibility

$(x_N)_t$  enters the base

- For  $(s_N)_t < 0$  find search direction  $p^t$  from

$$\begin{pmatrix} B & N \\ 0 & I \end{pmatrix} \begin{pmatrix} p_B \\ p_N \end{pmatrix} = \begin{pmatrix} 0 \\ e_t \end{pmatrix}$$

$$c^T p^t = (s_N)_t$$

- Compute maximal step length  $\alpha_{\max}$  and limiting constraint  $r$ :

$$\alpha_{\max} = \min_i \left\{ \frac{(x_B)_i}{-(p_B)_i} \mid (p_B)_i < 0 \right\}$$

$$r = \operatorname{argmin}_i \left\{ \frac{(x_B)_i}{-(p_B)_i} \right\}$$

want  $x_B + \alpha p_B \geq 0$

$(x_B)_r$  leaves the base

- Take the step:

$$x + \alpha_{\max} p$$

## Dual Simplex

- Given  $s_N \geq 0$  (b.f.s. to (D)) solve (1) to obtain  $x_B$ .

Some  $(x_B)_t$  might be  $< 0$

dual feasibility

$(x_B)_t$  leaves the base

- For  $(x_B)_t < 0$  find search directions  $q^t$  and  $\eta_N^t$  from

$$\begin{pmatrix} B^T & 0 \\ N^T & I \end{pmatrix} \begin{pmatrix} q \\ \eta_N \end{pmatrix} = \begin{pmatrix} -e_t \\ 0 \end{pmatrix}$$

$$b^T q^t = -(x_B)_t$$

- Compute maximal step length  $\alpha_{\max}$  and limiting constraint  $r$ :

$$\alpha_{\max} = \min_i \left\{ \frac{(s_N)_i}{-(\eta_N)_i} \mid (\eta_N)_i < 0 \right\}$$

$$r = \operatorname{argmin}_i \left\{ \frac{(s_N)_i}{-(\eta_N)_i} \right\}$$

want  $s_N + \alpha \eta_N \geq 0$

$(x_N)_r$  enters the base

- Take the step:

$$y + \alpha_{\max} q$$

$$s_B + \alpha_{\max} e_t$$

$$s_N + \alpha_{\max} \eta_N$$

Optimal when we have both primal and dual feasibility, since complementarity  $x_j s_j = 0 \forall j$  is always fulfilled.