Mathematical Foundation for Compressed Sensing

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A short summary from last lectures: A lower estimate for RIP.

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- A lower estimate for RIP.
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Non-uniform versus uniform recovery of sparse vectors.

Things that remains to be done:

• The proof of RIP estimate for Structured Random matrices.

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More about non-uniform recovery.

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- More about non-uniform recovery.
- The recoverey of almost *s*-sparse vector with noise.

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$$m > Cs \log(Ne/s).$$

More precisely we get

$$m \geq \frac{s \log(2Ne/s) - \log 4}{2(\log(\sqrt{1-\delta_s} + 4\sqrt{1+\delta_s}) - \log(1-\delta_s))}.$$

For Gaussian random matrices we have Theorem 4.5: There is a constant C > 0 such that for any $\epsilon > 0$, and $0 < \delta \le 1$, the following holds: If

$$m > C rac{s}{\delta^2} \log(N/(s\epsilon) + \text{ lower order terms},$$

then the Gaussian $m \times N$ matrix **A** (as above) satisfy RIP constant $\delta_s = \delta$ with a probability not less than $1 - \epsilon$.

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Construction of RIP matrices:

We constructed an $m \times N$ matrix **A** statistfying the RIP property with constant δ_s with

$$m \sim C rac{s^2}{\delta_s^2} \log N.$$

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More precisely:

$$\mathbf{A}_{\mathcal{S}}=\mathbf{U}+\mathbf{V},$$

where **U** is orthonormal and the column in **V** has length less than δ_s/\sqrt{s} .

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Note that A_i is the columns of A then

 $E(\langle \mathbf{A}_i, \mathbf{A}_j \rangle) = 1$ for $i \neq j$ and $E(\langle \mathbf{A}_i, \mathbf{A}_i \rangle) = 1$ all j.

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• Let Z be the any row of **B** multiplied by \sqrt{N} , each row chosen by equal probability $\frac{1}{N}$.

Example: The discrete Fourier matrix

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Random Matrix from an Orthonormal basis

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• Let $\{\varphi_j(t)\}_j$ be an orthononomal basis on an interval *I*.

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• Let
$$Z = (Z_1, Z_2, ..., Z_N)$$
, where $Z_j = \varphi(T)$.

Example: A wavelet basis and ..

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Since

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an upper bound for these innerproducts has to be at least $1/\sqrt{N}$.

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Definition:

The pair of orthonormal bases is incoherent with constant K if all the inner products above are bounded by K/\sqrt{N} .

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• Let \mathbf{E}^{-1} be the $N \times N$ -matrix with rows \mathbf{e}_j .

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- the $N \times N$ matrix **B** we get stuctured random matrix by selecting each row by probaility $\frac{1}{N}$.

If U is the input signal we use the basis $\{\mathbf{e}_j\}$ and random measurement

$$\mathbf{y}_j = \langle U, \mathbf{e}_j \rangle,$$

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If U is the input signal we use the basis $\{\mathbf{e}_j\}$ and random measurement

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and U is sparsely represented int the basis $\{\mathbf{f}_k\}$ i.e

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for $\mathbf{x} = (\mathbf{x}_k)$ sparse. This gives the equation

$$\mathbf{y} = \mathbf{A}\mathbf{x}$$

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Theorem 6.1

There is a constant C > 0 and D < 0 such that

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The constant D is very large, it satisfies D < 163931.48.

Theorem 6.2 There is a constant C > 0 and D < 0 such that for any $\epsilon > 0$, and $0 < \delta \le 1$, the following holds:

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There is a constant C > 0 and D < 0 such that for any $\epsilon > 0$, and $0 < \delta \le 1$, the following holds: If

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The constants C and D are very large: The constants satisfy C < 17190 and D < 456.

Uniform versus non-uniform recovery with random matrices

Let **A** be $m \times N$ random matrix. Let sparsness level *s* and let $\epsilon > 0$ be given

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then the $m \times N$ structured random matrix **A** (as above) will have the uniform recovery property with a probability not less than $1 - \epsilon$.

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Recovery with appoximative sparsness and noise

Refer to Cande's et al.

Assume that the vector \mathbf{x} to be recoverd is not s sparse but can be well approximated by s-sparse functions for some s.

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$$\mathbf{y} = \mathbf{A}\mathbf{x} + \sigma \mathbf{z},$$

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where z is Gaussian z N(0, 1). (However assuming $\|\mathbf{A}\mathbf{z}\|_{\infty} \leq \lambda_N$ for some $\lambda_N \geq 0$.) We consider the l_1 regularized least-square problem

$$\min_{\overline{\mathbf{x}}\in R^N} \|\mathbf{A}\overline{\mathbf{x}} - \mathbf{y}\|_2 + \lambda \|\overline{\mathbf{x}}\|_1, \qquad (*)$$

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or with error in l_1 norm:

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