Quantitative stability in geometric & functional inequalities

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Alessio Figalli (ETH Zürich) Stability in geom. & funct. ineq.

Geometric and functional inequalities play a crucial role in several problems arising in the calculus of variations, partial differential equations, geometry, physics, etc.

Classical examples:

- Isoperimetric inequalities;
- Sobolev inequalities;
- Gagliardo-Nirenberg inequalities;
- Brunn-Minkowski.

Basic question:

(1) Find the sharp constant for these inequalities.

(2) Characterize the minimizers.

These are by now well understood.

What next?

(3) Are minimizers stable? That is, if a function/set almost attains the equality in one of the previous inequalities, is it close to one of the minimizers?

- Stability for isoperimetric inequalities
- Stability for the Brunn-Minkowski inequality
- Stability for the Sobolev inequality: minimizers vs critical points

Part 1: Isoperimetric inequalities

Classical isoperimetric inequality: For any bounded open smooth set $E \subset \mathbb{R}^n$, the perimeter P(E) controls the volume |E|:

 $P(E) \ge n|B_1|^{1/n}|E|^{(n-1)/n}.$

Moreover equality holds if and only if *E* is a ball.

Stability question: If E is "almost a minimizer", does this imply that E is close to a ball, if possible in some quantitative way?

Isoperimetric deficit of *E*:

$$\delta(E) := \frac{P(E)}{n|B_1|^{1/n}|E|^{(n-1)/n}} - 1.$$

- $\delta(E) \geq 0$.
- $\delta(E) = 0 \quad \Leftrightarrow \quad E \text{ is a ball.}$

Asymmetry index of *E*:

$$A(E) := \inf_{x} \left\{ \frac{|E\Delta(B_r(x))|}{|E|} : |B_r| = |E| \right\}$$

Here $E \Delta F$ denotes the symmetric difference between the sets *E* and *F*, i.e., $E \Delta F := (E \setminus F) \cup (F \setminus E)$.

Question: can we find positive constants C = C(n) and $\alpha = \alpha(n)$ such that

 $A(E) \leq C \, \delta(E)^{\alpha}$?

Remark: by testing the above inequality on a sequence of ellipsoids converging to B_1 , we get $\alpha \leq 1/2$.

This is actually the sharp result:

Theorem (Fusco-Maggi-Pratelli, 2008)

The stability result holds with $\alpha = 1/2$.

The proof of Fusco-Maggi-Pratelli uses symmetrization techniques which are very specific to the Euclidean case.

We want to describe a different approach which has the advantage to work for much more general perimeter-type functionals. More precisely, we replace the classical perimeter by

$$P_f(E) := \int_{\partial E} f(\nu_E)$$

with *f* positively 1-homogeneous and convex, and we look for the stability of the corresponding isoperimetric inequality (the so-called **Wulff inequality**).

Theorem (Figalli-Maggi-Pratelli, 2010)

The stability result holds for P_f with $\alpha = 1/2$.

Also, C is an explicit constant depending only on the dimension (and not on f).

Consider a liquid drop/crystal $E \subset \mathbb{R}^n$ under the action of an exterior potential $g : \mathbb{R}^n \to \mathbb{R}$.

Then *E* minimizes the free energy under a volume constraint:

free energy = surface energy + bulk energy

More precisely, *E* minimizes

$$F\mapsto P_f(F)+\int_F g(x)\,dx$$

among all sets F with |F| = |E|.

Let $K = K_f$ be the minimizer when $g \equiv 0$ with |K| = 1.

Theorem (Figalli-Maggi, 2011)

Let m := |E|, $\hat{E} := m^{-1/n}E$ (so that $|\hat{E}| = 1$).

Then, up to a translation, if $m \ll 1$:

If f smooth and "uniformly convex", then $\|\partial \hat{E} - \partial K\|_{C^2} \lesssim m^{2/[n(n+2)]};$

If n = 2 and f is crystalline (equivalently, K is a convex polygon), then Ê is a convex polygon with sides parallel to that of K.

Theorem (Figalli-Zhang, 2021)

Last statement true also for $n \ge 3$.

Given E smooth and bounded, consider the probability densities

$$f(x) := rac{\chi_{\mathcal{E}}(x)}{|\mathcal{E}|}, \qquad g(y) := rac{\chi_{\mathcal{B}_1}(y)}{|\mathcal{B}_1|}.$$

By Optimal Transportation Theory, there exists $\varphi : \mathbb{R}^n \to \mathbb{R}$ convex such that $T := \nabla \varphi$ sends *f* onto *g*, that is

$$T_{\#}f = g \qquad \Leftrightarrow \qquad \int_{A}g = \int_{T^{-1}(A)}f \quad \forall A.$$

Properties of **T**:

- $|T| \leq 1$ in E (since $T(E) \subset B_1$)
- 2 det $(DT) = |B_1|/|E|$ (since $T_{\#}f = g$)

• div $T \ge n (\det(DT))^{1/n}$ (wait for the next slide).

Then:

$$P(E) = \int_{\partial E} 1 \stackrel{(1)}{\geq} \int_{\partial E} |T| \ge \int_{\partial E} T \cdot \nu_E$$

$$= \int_{E} \operatorname{div} T \stackrel{(3)}{\geq} n \int_{E} (\operatorname{det}(DT))^{1/n} \stackrel{(2)}{=} n |B_{1}|^{1/n} |E|^{(n-1)/n}.$$

Proof of (3)

Since $T = \nabla \varphi$ with φ convex, the eigenvalues $\lambda_1, \ldots, \lambda_n$ of $D^2 \varphi$ are non-negative.

Hence:

$$\operatorname{div} T = \Delta \varphi = n \left(\frac{1}{n} \sum_{i=1}^{n} \lambda_i \right) \ge n \left(\prod_{i=1}^{n} \lambda_i \right)^{1/n} = n (\operatorname{det}(DT))^{1/n},$$

where we used the arithmetic-geometric inequality.

Strengths of this proof:

- It works also for the functional P_f.
- It is very robust.

In particular, by carefully making "quantitative" each inequality one can prove the desired stability result.

Part 2: The Brunn-Minkowski inequality

Semisum of sets

Let $A \subset \mathbb{R}^n$ be a Borel set with |A| > 0. We define

$$\frac{A+A}{2}:=\left\{\frac{a+a'}{2}:\,a,a'\in A\right\}.$$

Obviously $\frac{A+A}{2} \supset A$, hence

$$\left|\frac{A+A}{2}\right| \ge |A|.$$

In addition equality holds iff

 $|\mathrm{co}(A)\setminus A|=0,$

where co(A) denote the convex hull of A.

This is a particular case of a more general inequality: the *Brunn-Minkowski inequality*.

Given $A, B \subset \mathbb{R}^n$ Borel, with |A|, B| > 0, define

$$\frac{A+B}{2} := \left\{ \frac{a+b}{2} : a \in A, b \in B \right\}.$$

Then

$$\left|\frac{A+B}{2}\right|^{1/n} \geq \frac{|A|^{1/n} + |B|^{1/n}}{2}.$$

In addition, equality holds iff *A* and *B* are homothetic convex sets: there exist $\alpha, \beta > 0, v, w \in \mathbb{R}^n$, *K* convex, such that

$$A \subset \alpha K + v, \qquad |(\alpha K + v) \setminus A| = 0,$$
$$B \subset \beta K + w, \qquad |(\beta K + w) \setminus B| = 0.$$

Question: are these results stable?

That is, if for instance

$$\left.\frac{\mathbf{A}+\mathbf{A}}{\mathbf{2}}\right|=|\mathbf{A}|+\varepsilon$$

with $\varepsilon \ll |A|$, is it true that A is close to its convex hull?

Let *A*, *B* be bounded convex set with $0 < \lambda \le |A|, |B| \le \Lambda$. Define $|A + B|^{1/n} = |A|^{1/n} + |B|^{1/n}$

$$\delta := \left| \frac{A+B}{2} \right|^{1/n} - \frac{|A|^{1/n} + |B|^{1/n}}{2}.$$

Then $\delta \ge 0$, and we would like to show that δ controls the distance between *A* and *B*.

First of all, renormalize *A* so that it has the same measure of *B*: if $\gamma := \frac{|B|^{1/n}}{|A|^{1/n}}$ then $|\gamma A| = |B|.$ Define a "distance" between *A* and *B*:

$$d(A,B) := \min_{x \in \mathbb{R}^n} |B\Delta(x + \gamma A)|,$$

where

 $E\Delta F := (E \setminus F) \cup (F \setminus E).$

Theorem (Figalli-Maggi-Pratelli, 2009)

There exists $C = C(n, \lambda, \Lambda)$ such that

 $d(A,B) \leq C\sqrt{\delta}.$

Remark: the exponent 1/2 is optimal and *C* is explicit.

Without loss of generality |A| = 1. Define

 $\delta(\boldsymbol{A}) := |\boldsymbol{A} + \boldsymbol{A}| - 2|\boldsymbol{A}|.$

REMARK: $\delta(A)$ cannot control in general $|co(A) \setminus A|$:

One may have $\delta(A) = 1(= |A|)$ and $|co(A) \setminus A|$ arbitrarily large.

By Freiman, this is the only thing that can go wrong:

Theorem (Freiman, 1959)

Let $A \subset \mathbb{R}$ be a Borel set with |A| = 1, and denote by co(A) its convex hull. If $\delta(A) < 1$ then

 $|\mathrm{co}(A) \setminus A| \leq \delta(A).$

To be precise, Freiman's Theorem is about the structure of additive subsets of \mathbb{Z} .

Let $A \subset \mathbb{R}^n$ with |A| = 1, and define

$$\delta(\boldsymbol{A}) := \left|\frac{\boldsymbol{A} + \boldsymbol{A}}{2}\right| - |\boldsymbol{A}|.$$



Theorem (Figalli-Jerison, 2015)

Let $n \ge 1$. There exist computable dimensional constants δ_n , $C_n > 0$ such that if $\delta(A) \le \delta_n$, then

 $|\mathrm{co}(A) \setminus A| \leq C_n \delta(A)^{\alpha_n}, \qquad \alpha_n := \frac{1}{8^{n-1}}$

$$=\frac{1}{8^{n-1}n!\left[(n-1)!\right]^2}.$$

Many improvement and generalizations in the last 6 years...

Part 3: The Sobolev inequality

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The Sobolev inequality

Let $n \ge 3$. The Sobolev inequality states

 $(Sob_2) \|\nabla u\|_{L^2} \ge S \|u\|_{L^{2^*}}$

where

$$2^*=\frac{2n}{n-2}.$$

Also, equality holds iff

$$u = c U_{\lambda,z}, \qquad U_{\lambda,z}(x) = [n(n-2)]^{\frac{n-2}{4}} \frac{\lambda^{\frac{n-2}{2}}}{(1+\lambda|x-z|^2)^{\frac{n-2}{2}}}.$$

Assume

$$\|\nabla u\|_{L^2} = S^{n/2} = \|\nabla U_{\lambda,z}\|_{L^2}$$

and

$$\delta(u) := \|\nabla u\|_{L^2} - S\|u\|_{L^{2^*}} \ll 1.$$

Is *u* close to some $U_{\lambda,z}$?

Theorem (Bianchi-Egnell, 1991)

Let $\|\nabla u\|_{L^2} = S^{n/2}$. Then

$$\min_{\lambda,z} \|\nabla u - \nabla U_{\lambda,z}\|_{L^2} \leq C(n) \,\delta(u)^{1/2}.$$

Remark: The power 1/2 is optimal.

Let *u* be a minimizer of (*Sob*₂). Then

$$0 = \frac{d}{d\varepsilon} \bigg|_{\varepsilon=0} \Big(\|\nabla u + \varepsilon \nabla \varphi\|_{L^2} - S \|u + \varepsilon \varphi\|_{L^{2*}} \Big)$$

for all $\varphi \in W^{1,2}$.

From this, we find the Euler-Lagrange equation

$$-\Delta u = \gamma u^{p}, \qquad p = 2^{*} - 1,$$

for some $\gamma > 0$.

Characterization of critical points

Up to rescaling u, one can assume $\gamma = 1$.



Stability question: Assume

 $-\Delta u = u^{p} + R, \qquad R \approx 0.$

Is *u* close to some $U_{\lambda,z}$?

Issue: What is the natural space for *R*?

 $u \in W^{1,2} \cap L^{2^*} \quad \Rightarrow \quad \Delta u + u^p \in (W^{1,2})' = W^{-1,2}.$

This suggests the definition

 $\delta(\boldsymbol{u}) := \|\Delta \boldsymbol{u} + \boldsymbol{u}^{\boldsymbol{p}}\|_{\boldsymbol{W}^{-1,2}}.$

In this setting, *bubbling* can occur.

Consider $u = \sum_{i=1}^{m} U_{\lambda_i, z_i}$, where the functions $\{U_{\lambda_i, z_i}\}$ are supported far away from each other. Then

$$-\Delta u = -\sum_{i=1}^{m} \Delta U_{\lambda_i, z_i} = \sum_{i=1}^{m} U_{\lambda_i, z_i}^p \approx \left(\sum_{i=1}^{m} U_{\lambda_i, z_i}\right)^p = u^p.$$

Theorem (Struwe, 1984)

Assume

$$\int |\nabla u|^2 \leq \left(L + \frac{1}{2}\right) S^n.$$

For all $\varepsilon > 0$ there exists $\delta_{\varepsilon} > 0$ such that

$$\delta(\boldsymbol{u}) \leq \delta_{\varepsilon} \quad \Rightarrow \quad \left\| \nabla \boldsymbol{u} - \sum_{i=1}^{m} \nabla \boldsymbol{U}_{\lambda_{i}, \boldsymbol{z}_{i}} \right\|_{L^{2}} \leq \varepsilon$$

for some $m \leq L$.

Also

$$\frac{\lambda_i}{\lambda_j} + \frac{\lambda_j}{\lambda_i} \geq \frac{1}{\varepsilon}, \qquad \lambda_i \lambda_j |z_i - z_j|^2 \geq \frac{1}{\varepsilon}.$$

Theorem (Ciraolo-Figalli-Maggi, 2017;

Figalli-Glaudo, 2020)

Assume

$$\int |\nabla u|^2 \leq L + \frac{1}{2}S^n.$$

Then:

$$L = 1 \quad \Rightarrow \quad \|\nabla u - \nabla U_{\lambda,z}\|_{L^2} \leq C(n) \,\delta(u);$$

$$L > 1, 3 \le n \le 5 \quad \Rightarrow \quad \left\| \nabla u - \sum_{i=1}^m \nabla U_{\lambda_i, Z_i} \right\|_{L^2} \le C(n) \, \delta(u).$$

Remark: power is 1 instead of 1/2. Also, $n \le 5$ is optimal.

This result allows us to prove rates of convergence to equilibrium for the Yamabe flow on the sphere.

Thanks for your attention!

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