



KTH Teknikvetenskap

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Chapter 10

projective toric varieties and polytopes: definitions

10.1 Introduction

Toric varieties are algebraic varieties related to the study of **sparse polynomials**. A polynomial is said to be sparse if it only contains prescribed monomials.

Let $A = \{m_0, \dots, m_d\} \subset \mathbb{Z}^n$ be a finite subset of integer points. We will use the multi-exponential notation:

$$x^a = x_1^{a_1} \cdot x_2^{a_2} \cdots x_n^{a_n} \text{ where } x = (x_1, \dots, x_n) \text{ and } a = (a_1, \dots, a_n) \in \mathbb{Z}^n$$

Sparse polynomials of type A are polynomials in n variables of type:

$$p(x) = \sum_{a \in A} c_a x^a$$

For example if $A = \{(i, j) \in \mathbb{Z}_+^2 \text{ such that } i + j \leq k\}$ then the polynomials of type A are all possible polynomials of degree up to k .

Toric varieties admit equivalent definitions arising naturally in many mathematical areas such as: Algebraic Geometry, Symplectic Geometry, Combinatorics, Statistics, Theoretical Physics etc.

We will present here an approach coming from Convex geometry and will see that toric varieties represent a natural generalization of projective spaces.

There are two main features we will try to emphasise:

- (1) toric varieties, X , are prescribed by **sparse polynomials**, in the sense that they are mapped in projective space via these pre-assigned monomials, whose exponents span an integral polytope **polytope** P_X . You

can think at a parabola parametrized locally by $t \mapsto (t, t^2)$. The monomials are prescribed by the points $1, 2 \in \mathbb{Z}$. The polytope spanned by these points is a segment of length 1, $[1, 2]$. Discrete data A (i.e. points in $\mathbb{Z}^n$) gives rise to a polytope P_A and in turn to a toric variety X_A allowing a geometric analysis of the original data. This turns out to be very useful in Statistics or Bio-analysis for example.

- (2) Toric varieties are defined by **binomial ideals**, i.e. ideals generated by polynomials consisting of two monomials: $x^u - x^v$. In the example of the parabola all the points in the image are zeroes of the binomial: $y - x^2$. This feature is particularly useful in integer programming when one wants to find a vertex (of the associated polytope) that minimises a certain (cost) function.

10.2 Recap example

Consider the ideal $(x^3 - y^2) \in \mathbb{C}[x, y]$.

- (a) The generating polynomial is irreducible and thus the corresponding affine variety $X = Z(x^3 - y^2) \subset \mathbb{C}^2$ is an **irreducible affine variety**.
- (b) Consider now the **algebraic torus** $\mathbb{C}^* = \mathbb{C} \setminus \{0\} \subset \mathbb{C}$. Notice that $\mathbb{C}^* = \mathbb{C} \setminus Z(x)$, a Zariski-open subset of $\mathbb{C}$. Consider now the map $\phi : \mathbb{C}^* \rightarrow \mathbb{C}^2$ defined as $\phi(t) = (t^2, t^3)$. Observe that $\text{Im}(\phi) \subseteq X$ and that $\psi : \text{Im}(\phi) \rightarrow \mathbb{C}^*$ defined as $\psi(x, y) = (y/x)$ is an inverse. It follows that $\mathbb{C}^* \cong \text{Im}(\phi)$, i.e. $\mathbb{C}^* \subset X$.
- (c) The open set $\mathbb{C}^*$ is also a multiplicative group. We can define a **group action** on X as follows:

$$\mathbb{C}^* \times X \rightarrow X, (t, (x, y)) \mapsto (t^2x, t^3y).$$

Notice that, by definition, the action restricted to $\mathbb{C}^* \subset X$ is the multiplication in the group.

We will call such a variety, i.e. a variety satisfying (a), (b) and (c), an **affine toric variety**

10.3 Algebraic tori

Definition 10.3.1. A linear algebraic group is a Zariski-open set G having the structure of a group and such that the multiplication map and the

inverse map:

$$m : G \times G \rightarrow G, i : G \rightarrow G$$

are morphisms of affine varieties.

Let G, G' be two linear algebraic groups, a **morphism** $G \rightarrow G'$ of linear algebraic groups is a map which is a morphism of affine varieties and a homomorphism of groups.

We will indicate the SET of such morphisms with $\text{Hom}_{AG}(G, G')$.

Excercise 10.3.2. Show that when G, G' are abelian $\text{Hom}_{AG}(G, G')$ is an abelian group.

Example 10.3.3. The classical examples of algebraic groups are: $(\mathbb{C}^*)^n, GL_n, SL_n$.

Definition 10.3.4. An n -dimensional algebraic torus is a Zariski-open set T , isomorphic to $(\mathbb{C}^*)^n$.

An algebraic torus is a group, with the group operation that makes the isomorphism (of affine varieties) a group-homomorphism. Hence an algebraic torus is a linear algebraic group.

From now on we will drop the adjective algebraic in algebraic torus.

Definition 10.3.5. Let T be a torus.

- An element of the abelian group $\text{Hom}_{AG}(\mathbb{C}^*, T)$ is called a one parameter subgroup of T .
- An element of the abelian group $\text{Hom}_{AG}(T, \mathbb{C}^*)$ is called a character of T .

Lemma 10.3.6. Let $T \cong (\mathbb{C}^*)^n$ be a torus.

$$\text{Hom}_{AG}(T, \mathbb{C}^*) \cong \mathbb{Z}^n.$$

Proof. Because $\text{Hom}_{AG}(T, \mathbb{C}^*) \cong (\text{Hom}_{AG}(\mathbb{C}^*, \mathbb{C}^*))^n$ it suffices to prove that $\text{Hom}_{AG}(\mathbb{C}^*, \mathbb{C}^*) \cong \mathbb{Z}$. Let $F : \mathbb{C}^* \rightarrow \mathbb{C}^*$ be an element of $\text{Hom}_{AG}(\mathbb{C}^*, \mathbb{C}^*)$. Then $F(t)$ is a polynomial such that $F(0) = 0$ Moreover it is a multiplicative group homomorphism, e.g. $F(t^2) = F(t)^2$. It follows that $F(t) = t^k$ for some $k \in \mathbb{Z}$. $\square$

A **Laurent monomial** in n variables is defined by

$$t^a = t^{a_1} \cdot t^{a_2} \cdot \dots \cdot t^{a_n}, \text{ where } a = (a_1, \dots, a_n) \in \mathbb{Z}^n$$

Observe that t^a defines a function $(\mathbb{C}^*)^n \rightarrow \mathbb{C}^*$, i.e. t^a is a character of the torus $(\mathbb{C}^*)^n$. Such character is usually denoted by $\chi^a : T \rightarrow \mathbb{C}^*$ where $\chi^a(t) = t^a$.

Another important fact, whose proof can be found in [H] is that:

Lemma 10.3.7. *Any irreducible closed subgroup of a torus (i.e. an irreducible affine sub-variety which is a subgroup) is a sub-torus.*

10.4 Toric varieties

Definition 10.4.1. *A (affine or projective) **toric variety** of dimension n is an irreducible (affine or projective) variety X such that*

- (1) X contains an n -dimensional torus $T \cong (\mathbb{C}^*)^n$ as Zariski-open subset.
- (2) the multiplicative action of $(\mathbb{C}^*)^n$ on itself extends to an action of $(\mathbb{C}^*)^n$ on X .

Example 10.4.2. $\mathbb{C}^n$ is an affine toric variety of dimension n .

Example 10.4.3. $\mathbb{P}^n$ is a projective toric variety of dimension n . The map $(\mathbb{C}^*)^n \rightarrow \mathbb{P}^n$ defined as $(t_1, \dots, t_n) \mapsto (1, t_1, \dots, t_n)$ identifies the torus $(\mathbb{C}^*)^n$ as a subset of the affine patch $\mathbb{C}^n \subset \mathbb{P}^n$. The action:

$$(t_1, \dots, t_n) \cdot (x_0, x_1, \dots, x_n) = (x_0, t_1 x_1, \dots, t_n x_n)$$

is an extension of the multiplicative action on the torus.

Example 10.4.4. Consider the Segre embedding $seg : \mathbb{P}^1 \times \mathbb{P}^1 \hookrightarrow \mathbb{P}^3$ given by $((x_0, x_1), (y_0, y_1)) \mapsto (x_0 y_0, x_0 y_1, x_1 y_0, x_1 y_1)$. Consider now the map $\phi : (\mathbb{C}^*)^2 \rightarrow (\mathbb{C}^*)^4$ given by $\phi(t_1, t_2) = (1, t_1, t_2, t_1 t_2)$. Observe that if one identifies $(\mathbb{C}^*)^2$ with the Zariski open $\mathbb{P}^1 \times \mathbb{P}^1 \setminus (V(x_0 - 1) \cup V(y_0 - 1))$ then it is $\phi = seg|_{(\mathbb{C}^*)^2}$. By Lemma 10.3.7 this image is a torus which shows that the torus $(\mathbb{C}^*)^2$ can be identified with a Zariski open of the Segre variety $Im(seg) \subset \mathbb{P}^3$. The torus action of $(\mathbb{C}^*)^2$ on $Im(seg)$ defined by $(t_1, t_2) \cdot (x_0, x_1, x_3, x_4) = (x_0, t_1 x_1, t_2 x_3, t_1 t_2 x_4)$ is by definition an extension of the multiplicative self-action.

10.5 Discrete data: polytopes

Definition 10.5.1. *A subset $M \subset \mathbb{R}^n$ is called a **lattice** if it satisfies one of the following equivalent statements.*

- (1) M is an additive subgroup which is discrete as subset, i.e. there exists a positive real number ϵ such that for each $y \in M$ the only element x such that $d(x, y) < \epsilon$ is given by $y = x$.

(2) There are $\mathbb{R}$ -linearly independent vectors $b_1, \dots, b_n$ such that:

$$M = \sum_1^n \mathbb{Z}b_i = \left\{ \sum_1^n c_i b_i, c_i \in \mathbb{Z} \right\}$$

A lattice of rank n is then isomorphic to $\mathbb{Z}^n$.

Definition 10.5.2. Let $A = \{m_1, \dots, m_d\} \in \mathbb{Z}^n$ be a finite set of lattice points. A combination of the form

$$\sum a_i m_i, \text{ such that } \sum_a^d a_i = 1, a_i \in \mathbb{Q}_{\geq 0}$$

is called a **convex combination**. The set of all convex combinations of points in A is called the **convex hull** of A and is denoted by $\text{Conv}(A)$.

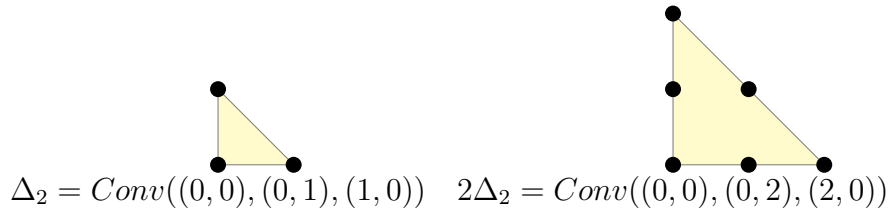
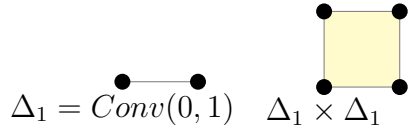
Definition 10.5.3. A **convex lattice polytope** $P \subset \mathbb{R}^n$ is the convex hull of a finite subset $A \subset \mathbb{Z}^n$. The dimension of P is the dimension of the smallest affine space containing P .

In what follows the term polytope will always mean a lattice convex polytope.

Example 10.5.4. Let $e_1, \dots, e_n$ be the standard basis of $\mathbb{R}^n$. The polytope $\text{Conv}(0, e_1, \dots, e_n)$ is called the n -dimensional regular simplex and it is denoted by Δ_n .

Given a polytope $P = \text{Conv}(m_0, m_1, \dots, m_n)$.

Let $kP = \{m_1 + \dots + m_k \in \mathbb{R}^n \text{ s.t. } m_i \in P\}$.



10.6 faces of a polytope

Let $P \subset \mathbb{R}^n$ be an n -dimensional lattice polytope. It can be described as the intersection of a finite number of upper-half planes.

Definition 10.6.1. Let $\xi \in \mathbb{Z}^n$ be a vector with integer coordinates and let $b \in \mathbb{Z}$. Define:

$$H_{\xi,b}^+ = \{m \in \mathbb{R}^n \mid \langle m, \xi \rangle \geq b\}, H_{\xi,b} = \{m \in \mathbb{R}^n \mid \langle m, \xi \rangle = b\}$$

$H_{\xi,b}^+$ is called an **upper half plane** and $H_{\xi,b}$ is called an **hyperplane**.

Definition 10.6.2. Let $P \subset \mathbb{R}^n$ be a convex lattice polytope. We say that $H_{\xi,b}$ is a **supporting hyperplane** for P if $H_{\xi,b} \cap P \neq \emptyset$ and $P \subset H_{\xi,b}^+$.

It is immediate to see that a polytope has a finite number of supporting hyperplanes and that:

$$P = \bigcap_{i=1}^s H_{\xi_i, b_i}^+$$

Definition 10.6.3. A **face** of a polytope P is the intersection of P with a supporting hyperplane. P is considered an (improper) face of itself.

Faces are convex lattice polytopes as $\text{Conv}(S) \cap H_{\xi,b} = \text{Conv}(S \cap H_{\xi,b})$.

The dimension of the face is equal to the dimension of the corresponding polytope.

Let F be a face, then

- F is a **facet** if $\dim(F) = \dim(P) - 1$.
- F is a **edge** if $\dim(F) = 1$.
- F is a **vertex** if $\dim(F) = 0$.

Remark 10.6.4. Observe (and try to justify) that:

- All polytopes of dimension one are segments.
- All the edges of a polytope contain two vertices.
- $\text{Conv}(S)$ contains all the segments between two points in S .
- Every convex lattice polytope P is the convex hull of its vertices.

Definition 10.6.5. Let $P, P' \subset \mathbb{R}^n$ be two n -dimensional polytopes. They are *affinely equivalent* if there is a lattice-preserving affine isomorphism $\phi : \mathbb{R}^n \rightarrow \mathbb{R}^n$ that maps P to P' and thus bijectively $P \cap \mathbb{Z}^n$ to $P' \cap \mathbb{Z}^n$.

Definition 10.6.6. Let P be a lattice polytope of dimension n .

- P is said to be **simple** if through every vertex there are exactly n vertices.

- P is said to be smooth if it is simple and for every vertex m the set of vectors $(v_1 - m, \dots, v_n - m)$, where v_i is the first lattice point on the i -th edge, forms a basis for the lattice $\mathbb{Z}^n$.

Remark 10.6.7. All the polygons are simple.

Lemma 10.6.8. *a set of vectors $\{v_1, \dots, v_n\} \in \mathbb{R}^n$ is a basis for the lattice $\mathbb{Z}^n$ if and only if the associated matrix B (having the v_i as columns) has determinant ± 1 .*

Proof. Let $\{v_1, \dots, v_n\} \in \mathbb{R}^n$ is a basis for the lattice $\mathbb{Z}^n$. Then there is an integral matrix U such that $I_n = UB$. Moreover one can observe that the matrix U defines a lattice isomorphism and thus, because the determinant of the inverse has to be an integer, $\det(U) = \pm 1$. $\square$

10.7 Assignment: exercises

- (1) Consider a minimal hyperplane description of a lattice polytopes P . In other words let $P = \bigcap_{i=1}^s H_{\xi_i, b_i}^+$ where s is the minimum number of half-spaces necessary to cut out P . Show that P has s facets and that the vectors ξ_i are normal vectors to the associated facet. Moreover show that the pairs (ξ_i, b_i) are uniquely determined up to enumeration (the vectors ξ_i are unique up to positive scalar factors).
- (2) Classify, up to affine equivalence, all the smooth polygons containing at most 8 lattice points.

Bibliography

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