Generating random numbers

Computer Intensive Methods in Mathematical Statistics

Johan Westerborn

Department of mathematics KTH Royal Institute of Technology johawes@kth.se

Lecture 2 Random number generation 23 March 2017

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Last time: Principal aim

We formulated the main problem of the course, namely to compute some expectation

$$au = \mathbb{E}(\phi(X)) = \int_X \phi(x) f(x) \, dx,$$

where

- X is a random variable taking values in $X \subseteq \mathbb{R}^d$ (where $d \in \mathbb{N}^*$ may be very large),
- *f* : X → ℝ₊ is the probability density (target density) of X, and

Summary

Last time: The MC method in a nutshell

■ Let *X*¹, *X*²,..., *X*^{*N*} be independent random variables with density *f*. Then, by the law of large numbers, as *N* tends to infinity,

$$au_N \stackrel{\text{\tiny def}}{=} rac{1}{N} \sum_{i=1}^N \phi(X^i) o \mathbb{E}(\phi(X)).$$
 (a.s.)

Inspired by this result, we formulated the basic MC sampler:

for $i = 1 \rightarrow N$ do $| \text{ draw } X^i \sim f;$ end

set
$$\tau_N \leftarrow \sum_{i=1}^N \phi(X^i)/N;$$

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Summary

Some properties of MC estimators

• We note that τ_N is unbiased in the sense that for all N,

$$\mathbb{E}(\tau_N) = \mathbb{E}\left(\frac{1}{N}\sum_{i=1}^N \phi(X^i)\right) = \frac{1}{N}\sum_{i=1}^N \mathbb{E}(\phi(X^i)) = \tau.$$

In addition, as we saw last time, the variance of τ_N is

$$\mathbb{V}(\tau_N) = \frac{1}{N}\sigma^2(\phi) \Rightarrow \mathbb{D}(\tau_N) = \frac{1}{\sqrt{N}}\sigma(\phi).$$

Finally, the CLT implies that the normalized MC error is asymptotically normally distributed:

$$\sqrt{N} (au_N - au) \stackrel{\text{d.}}{\longrightarrow} \mathsf{N}(\mathbf{0}, \sigma^2(\phi)), \quad \text{as } N o \infty,$$

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Summary o

What do we need to know?

- OK, so what do we need to master for having practical use of the MC method?
- We agreed on that, for instance, the following questions should be answered:
 - How do we generate the needed input random variables?
 - How many computer experiments should we do? What can be said about the error?
 - Can we exploit problem structure to speed up the computation?
- Today we will discuss the first two issues.

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Summary

Plan of today's lecture

- 1 Plug-in MC estimators
- 2 MC output analysis
- 3 Generating random numbers
 - Uniform pseudo-random numbers
 - Transformation-based methods

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- For a given estimand τ one is often interested in estimating $\varphi(\tau)$ for some function $\varphi : \mathbb{R} \to \mathbb{R}$. For instance, one may be interested in the squared expectation $\varphi(\tau) = \tau^2$.
- Question: what are the properties of the plug-in estimator $\varphi(\tau_N)$ of $\varphi(\tau)$?
- The estimator $\varphi(\tau_N)$ is generally biased for finite *N*; indeed, under suitable assumptions on φ it holds that

$$\mathbb{E}\left(\varphi(\tau_N) - \varphi(\tau)\right) = \frac{\varphi''(\tau)}{2} \mathbb{V}(\tau_N) + O(N^{-3/2})$$
$$= \frac{\varphi''(\tau)\sigma^2(\phi)}{2N} + O(N^{-3/2}),$$

implying that $\varphi(\tau_N)$ is still consistent.

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Image: A matrix

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implying that $\varphi(\tau_N)$ is still consistent.

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The delta method

In addition, one may establish the CLT

$$\sqrt{N}(\varphi(\tau_N)-\varphi(\tau)) \stackrel{d.}{\longrightarrow} \mathsf{N}(0, \varphi'(\tau)^2 \sigma^2(\phi)), \quad \text{as } N \to \infty,$$

which implies that the standard deviation of the plug-in estimator is obtained by simply scaling the standard deviation of the original estimator by $\varphi'(\tau)$.

This will be discussed further during the first exercise class.

MC output analysis

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Confidence bounds

Using the CLT one obtains straightforwardly the two-sided confidence bound

$$\mathsf{I}_{\alpha} = \left(\tau_{\mathsf{N}} - \lambda_{\alpha/2} \frac{\sigma(\phi)}{\sqrt{\mathsf{N}}}, \tau_{\mathsf{N}} + \lambda_{\alpha/2} \frac{\sigma(\phi)}{\sqrt{\mathsf{N}}}\right),$$

for τ , where λ_p denotes the *p*-quantile of the standard normal distribution.

I I_{α} covers τ with (approximate) probability $1 - \alpha$.

A problem here is that $\sigma^2(\phi)$ is generally not known.

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Confidence bounds (cont.)

Quick fix: the variance $\sigma^2(\phi)$ is again an expectation that can be estimated using the already generated MC sample $(X^i)_{i=1}^N$. More specifically, using the plug-in estimator,

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ight)^2 &= \mathbb{E}(\phi^2(X)) - au^2 \ &pprox rac{1}{N}\sum_{i=1}^N \phi^2(X^i) - au_N^2 &= rac{1}{N}\sum_{i=1}^N \left(\phi(X^i) - au_N
ight)^2. \end{aligned}$$

This estimator has however bias. A bias-corrected estimator (in MATLAB: var alt. std) is

$$\sigma_N^2(\phi) \stackrel{\text{\tiny def}}{=} \frac{1}{N-1} \sum_{i=1}^N \left(\phi(X^i) - \tau_N \right)^2$$

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Summary

Confidence bounds (cont.)

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Computer Intensive Methods (12)

Example: Buffon's needle

- Consider a grid of parallel lines of spacing *d* on which we drop randomly a needle of length *l*, with *l* ≤ *d*. Let
 - $\begin{cases} X = \text{distance from lower needlepoint to upper grid line,} \\ \theta = \text{angle between needle and grid normal} \in (-\pi/2, \pi/2). \end{cases}$
- Then

 $\tau = \mathbb{P}(\text{needle intersects grid}) = \mathbb{P}(X \le \ell \cos \theta) = \ldots = \frac{2\ell}{\pi d}$

or, equivalently,

$$\pi = \varphi(\tau) = \frac{2\ell}{\tau d}.$$

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Computer Intensive Methods (13)

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Computer Intensive Methods (13)

Example: Buffon's needle (cont.)

Since

 $\tau = \mathbb{P} \left(\text{needle intersects grid} \right) = \mathbb{E} \left(\mathbb{1}_{\{X \leq \ell \cos \theta\}} \right),$

we may obtain an approximation of π through

X = d*rand(1,N); theta = - pi/2 + pi*rand(1,N); tau = mean(X <= L*cos(theta));</pre>

and then letting pi_est = 2*L./(tau*d).

In addition, a 95% confidence interval is obtained through

sigma = std(X <= L*cos(theta)); LB = pi_est - norminv(0.975)*2*L/(d*tau^2*sqrt(N))*sigma; UB = pi_est + norminv(0.975)*2*L/(d*tau^2*sqrt(N))*sigma;

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Example: Buffon's needle (cont.)

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```

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Example: Buffon's needle (cont.)

- Here we are actually cheating, since we require the value of π in our simulation code...
- As we will see later this lecture and during the first exercise class, it is however possible to simulate cos(θ) directly by using only U(0, 1) random numbers.

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Example: Buffon's needle (cont.)

Executing this code for N = 1:10:1000 yields the following graph (where the red-dashed lines are confidence bounds):



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"Random"?!...

Laplace's demon:

"We may regard the present state of the universe as the effect of its past and the cause of its future. An intellect which at a certain moment would know all forces that set nature in motion, and all positions of all items of which nature is composed, if this intellect were also vast enough to submit these data to analysis, it would embrace in a single formula the movements of the greatest bodies of the universe and those of the tiniest atom; for such an intellect nothing would be uncertain and the future just like the past would be present before its eyes."

-P.-S. Laplace, Essai philosophique sur les probabilités, 1814

- Expresses determinism.
- The possibility of Laplace's demon is a fundamental question in philosophy.

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Generating pseudo-random numbers

- Pseudo-random numbers = numbers exhibiting statistical randomness while being generated by a deterministic process.
- We will discuss
 - how to generate pseudo-random uniform numbers,
 - transformation and inversion methods,
 - rejection sampling, and
 - conditional methods.

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Generating random numbers

Good pseudo-random numbers

"Good" pseudo-random numbers

- appear to come from the correct distribution (also in the tails),
- have long periodicity,
- look "independent", and
- are fast to generate.
- Most standard computing languages have packages or functions that generate either U(0, 1) random numbers or integers on U(0, 2³² – 1):
 - rand and unifrnd in MATLAB,
 - rand in C/C++,
 - Random in Java.

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Generating random numbers

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Uniform pseudo-random numbers

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Uniform pseudo-random numbers

Linear congruential generator

The linear congruential generator is a simple, fast, and popular way of generating pseudo-random numbers:

$$X_n = (a \cdot X_{n-1} + c) \mod m,$$

where a, c, and m are integers.

- This recursion generates integer numbers (X_n) in
 [0, m 1]. These are mapped to (0, 1) through division by
 m. It turns out that the period of the generator is m if
 - (i) *c* and *m* are relatively prime,

(22)

- (ii) a 1 is divisible by all prime factors of *m*, and
- (iii) a 1 is divisible by 4 if *m* is divisible by 4.

As an example, MATLAB (pre v. 5) uses $m = 2^{32} - 1$, $a = 7^5 = 16807$, and c = 0.

Generating random numbers

Summary

Uniform pseudo-random numbers

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Transformation-based methods

Bijective transformations of random variables

- Let *X* be a stochastic variable with density f_X on $X \subseteq \mathbb{R}$ and let $g : X \to Y \subseteq \mathbb{R}$ be some differentiable, strictly increasing function with inverse g^{-1} .
- Define Y = g(X) and let f_Y denote the density of Y. We show that

$$f_Y(y)=f_X(g^{-1}(y))\frac{d}{dy}g^{-1}(y) \quad (y\in \mathsf{Y}).$$

In the case where g is strictly decreasing we may argue similarly, and it holds generally that

$$f_Y(y) = f_X(g^{-1}(y)) \left| \frac{d}{dy} g^{-1}(y) \right| \quad (y \in \mathsf{Y})$$

for a strictly monotone function g.

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Summary

Transformation-based methods

The transformation theorem

Now, let X be *n*-dimensional, i.e., $X \subseteq \mathbb{R}^n$, $g : X \to Y \subseteq \mathbb{R}^n$ a bijection, and set

$$Y = \begin{pmatrix} Y_1 \\ Y_2 \\ \vdots \\ Y_n \end{pmatrix} = g(X) = \begin{pmatrix} g_1(X_1, \dots, X_n) \\ g_2(X_1, \dots, X_n) \\ \vdots \\ g_n(X_1, \dots, X_n) \end{pmatrix} \Leftrightarrow$$
$$X = \begin{pmatrix} X_1 \\ X_2 \\ \vdots \\ X_n \end{pmatrix} = g^{-1}(Y) = \begin{pmatrix} h_1(Y_1, \dots, Y_n) \\ h_2(Y_1, \dots, Y_n) \\ \vdots \\ h_n(Y_1, \dots, Y_n) \end{pmatrix}$$

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Summary

Transformation-based methods

The transformation theorem (cont.)

Generally, the following holds true.

Theorem (the transformation theorem)

The density of Y is

$$f_{\mathsf{Y}}(y) = \begin{cases} f_{\mathsf{X}}(h_1(y), h_2(y), \dots, h_n(y)) \, | \mathbf{J}(y) | & \text{if } y \in \mathsf{Y}, \\ 0 & \text{otherwise} \end{cases}$$

where J(y) is the Jacobian matrix, i.e.,

$$\mathbf{J}(\mathbf{y}) = \begin{pmatrix} \frac{\partial}{\partial y_1} h_1(\mathbf{y}) & \frac{\partial}{\partial y_2} h_1(\mathbf{y}) & \cdots & \frac{\partial}{\partial y_n} h_1(\mathbf{y}) \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial}{\partial y_1} h_n(\mathbf{y}) & \frac{\partial}{\partial y_2} h_n(\mathbf{y}) & \cdots & \frac{\partial}{\partial y_n} h_n(\mathbf{y}) \end{pmatrix}$$

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MC output analysis

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Transformation-based methods

Example: Buffon's needle (again)

In order to simulate cos(θ), where θ ∼ U(−π/2, π/2), we may generate repeatedly independent U₁ ∼ U(−1, 1) and U₂ ∼ U(0, 1) until

$$U_1^2 + U_2^2 \le 1$$

and then return

$$Y = \frac{U_1}{\sqrt{U_1^2 + U_2^2}}$$

Using the transformation theorem, one may the show that

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$$Y \mid \{U_1^2 + U_2^2 \leq 1\} \stackrel{\text{d.}}{=} \cos(\theta).$$

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Transformation-based methods

The inversion method

- The transformation theorem can be used for generating random variables being functions of easily-simulated variables.
- In particular, we now assume that we have access to a U(0, 1) pseudo-random number generator and want to generate a random number X from some univariate distribution with a distribution function F whose inverse F⁻¹ is at hand.
- For this purpose, we proceed as follows:

draw $U \sim U(0, 1)$; set $X \leftarrow F^{-1}(U)$;

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The inversion method, remarks

Then the following is a consequence of the transformation theorem:

Theorem (the inverse method)

The output X of the algorithm above has distribution function F.

The previous result holds can be extended to the generalized inverse

$$F^{\leftarrow}(u) \stackrel{\text{\tiny def}}{=} \inf\{x \in \mathbb{R} : F(x) \ge u\}.$$

- If *F* is continuous and strictly increasing, then $F^{\leftarrow} = F^{-1}$.
 - The method is limited to cases where
 - we want to generate univariate random numbers and
 - the generalized inverse F[←] is easy to evaluate (which is far from always the case).

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Transformation-based methods

Example: exponential distribution

We use the inverse method for generating exponentially distributed random numbers (with unit expectation). Recall that this distribution has density

$$f(x) = e^{-x} \Rightarrow F(x) = \int_0^x f(z) \, dz = 1 - e^{-x} \quad (x \ge 0).$$

Taking the inverse yields

$$F(x) = 1 - e^{-x} = u \Leftrightarrow x = F^{-1}(u) = -\log(1-u) \quad (u \in (0,1)).$$

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Example: exponential distribution



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Summary

Today we have

- shown that plug-in estimator φ(τ_N) of φ(τ) is asymptotically consistent,
- discussed how to construct confidence intervals of the MC estimates using the CLT,
- shown how to generate pseudo-random numbers using
 - the linear congruential generator (for uniform random numbers) and
 - the inversion method (when the general inverse F[←] of F is obtainable).