



KTH Mathematics

Errata to

“On Cooperative Surveillance, Online Trajectory Planning and Observer Based Control”

by David A. Anisi

Page	Line	Says	Should say
139	12	$\dot{x}_1^r = -a_2 w^2 \sin(wt)$	$\ddot{x}_2^r = -a_2 w^2 \sin(wt)$
140	25	$A(t) = a(t)^T a(t)$	$A(t) = a(t)a(t)^T$
141	6	$x(0) = [1, -1, \frac{\pi}{2}]^T$	$x(0) = [1, -1, \frac{2\pi}{5}]^T$
141	7	$z(0) = [\frac{23\pi}{4}, \frac{242\pi}{1101}, \frac{\pi}{2}]^T$	$z(0) = [\frac{23\pi}{4}, \frac{242\pi}{1101}, \frac{2\pi}{5}]^T$